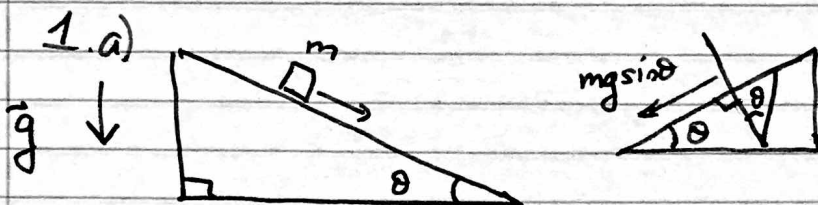


Physics 105A

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Midterm Solutions.



$$m \frac{dv}{dt} = -kmv^2 + mg \sin \theta$$

$$\frac{dv}{dt} = -kv^2 + g \sin \theta; \quad \int_0^v \frac{dv'}{g \sin \theta - kv'^2} = t$$

$$\Rightarrow \tanh^{-1} \left[\sqrt{\frac{k}{g \sin \theta}} v \right] \frac{1}{\sqrt{k g \sin \theta}} = t$$

$$\text{So } v(t) = \sqrt{\frac{g \sin \theta}{k}} \tanh \left[\sqrt{k g \sin \theta} t \right]$$

Now, $\frac{d}{dx} \log(\cosh x) = \frac{\sinh x}{\cosh x} = \tanh x$ so

$$x(t) = \int_0^t v(t') dt' = \sqrt{\frac{g \sin \theta}{k}} \frac{1}{\sqrt{k g \sin \theta}} \ln \left[\cosh \left(\sqrt{k g \sin \theta} t \right) \right]$$

\Rightarrow distance traveled D is given by

$$kD = \ln \left[\cosh \left(\sqrt{k g \sin \theta} t \right) \right] \text{ or}$$

$$e^{kD} = \cosh \left(\sqrt{k g \sin \theta} t \right) \Rightarrow \boxed{T = \frac{1}{\sqrt{k g \sin \theta}} \cosh^{-1} \left(e^{kD} \right)}$$

b) As $D \rightarrow \infty$ the block approaches terminal velocity. (2)

$v \rightarrow v^*$ when $D \rightarrow \infty$

$$-kmv^{*2} + mg\sin\theta = 0 \Rightarrow v^* = \sqrt{\frac{g\sin\theta}{k}}$$

So the drag force is: $F_D = km\left(\frac{g\sin\theta}{k}\right) = mg\sin\theta$
in magnitude.

Power dissipated $P = Fv = F_D v^*$

$$P = mg\sin\theta \sqrt{\frac{g\sin\theta}{k}} = \left(\frac{m^2 g^3 \sin^3\theta}{k}\right)^{1/2}$$

c) The kinetic energy of the block after sliding a distance D .

$$T = \frac{1}{2} m v^2(D); \quad v(D) = \sqrt{\frac{g\sin\theta}{k}} \tanh\left[\cosh^{-1}(e^{kD})\right]$$

Using the list of formulae:

$$v(D) = \sqrt{\frac{g\sin\theta}{k}} \sqrt{\frac{e^{2kD} - 1}{e^{2kD}}} = v^* (1 - e^{-2kD})^{1/2}$$

$\Rightarrow T(D) = \frac{1}{2} m v^{*2} (1 - e^{-2kD}) \leftarrow$ We see the approach to terminal velocity.

Now, the kinetic energy without drag would have been.

$$\frac{1}{2} m v^2 = \overline{T_0} = mgD\sin\theta$$

↑
drag-free

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$$\Delta E = T_0 - T = mgD \sin \theta - \frac{1}{2} m v^{*2} (1 - e^{-2kD})$$

w/o drag ↑
 ↑
 with drag

$$\Delta E(D) = mg \sin \theta \left\{ D - \frac{1}{2k} (1 - e^{-2kD}) \right\}$$

Note that at first the difference ΔE grows with D as D^2

$$kD \ll 1 \Rightarrow \Delta E \sim mg \sin \theta \times \frac{1}{3} D^2 k^2$$

Later on $kD \gg 1$ it grows linearly:

$$kD \gg 1; \Delta E \sim D mg \sin \theta - \text{constant.}$$

(4)

2.

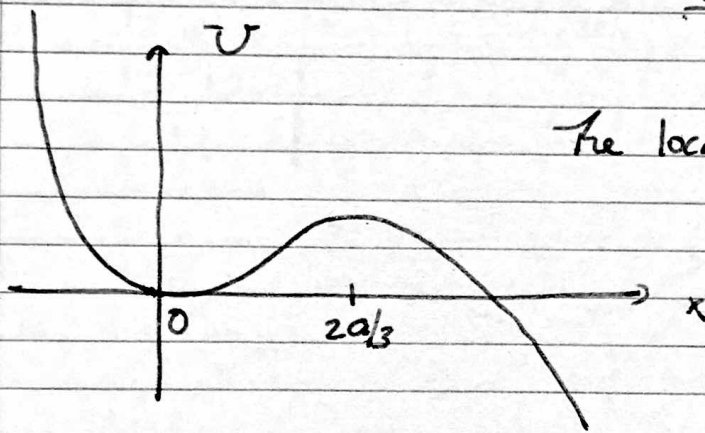
$$a) U(x) = -U_0 [x^3 - ax^2]$$

$$\frac{dU}{dx} = -U_0 [3x^2 - 2ax] \quad \text{zeros at } x=0 \text{ and}$$

$$3x - 2a = 0 \Rightarrow x = 2a/3.$$

$$\frac{d^2U}{dx^2} = -U_0 [6x - 2a]; \quad \left. \frac{d^2U}{dx^2} \right|_{x=0} = 2aU_0 > 0$$

$$\left. \frac{d^2U}{dx^2} \right|_{x=2a/3} = -4U_0a < 0$$



$$\text{The local max is: } U_0 a^3 \frac{4}{12} = \frac{U_0 a^3}{3}$$

b) Stable fixed pt at $x=0$

unstable fixed pt at $x=2a/3$

c) expand EOM around $x=0$

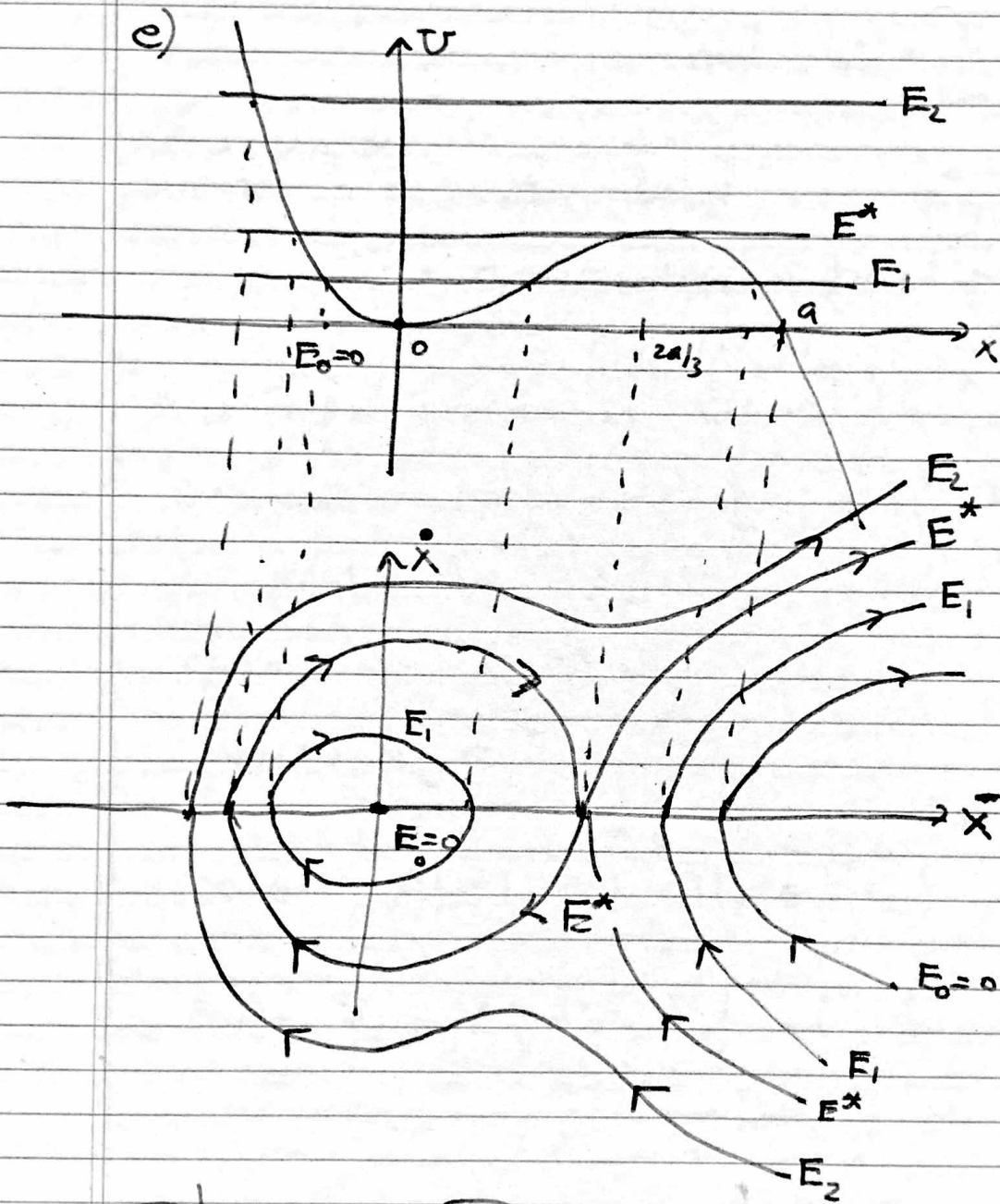
$$m \ddot{x} = \cancel{F(x)} F(0) + x \left. \frac{dF}{dx} \right|_{x=0} = 0 - x \left. \frac{d^2U}{dx^2} \right|_{x=0}$$

$$m \ddot{x} = -x 2aU_0$$

$$\Rightarrow \omega_0^2 = \sqrt{\frac{2aU_0}{m}}$$

d) For bounded oscillations we need

$$0 < E < \frac{1}{3}U_0 a^3$$



Phase Space Picture.

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a) We have oscillations obeying

$$\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = 0 \quad \text{where } 2\beta = \frac{b}{2m} = \frac{b}{2m}$$

$$\text{and } \omega_0^2 = \frac{k}{2m}$$

Now consider the collision:

momentum $P = MV$ before

← x take this direction as positive based on the picture.

$P = 2mV$ after

\Rightarrow initial velocity $v_0 = V/2$.
and initial position is $x(0) = 0$.

We have an overdamped system.

$$x(t) = Ae^{-\Gamma_- t} + Be^{-\Gamma_+ t} \quad \text{where: } \Gamma_{\pm} = \beta \pm \sqrt{\beta^2 - \omega_0^2}$$

$$x(0) = 0 \Rightarrow A + B = 0 \Rightarrow$$

$$x(t) = A \left[e^{-\Gamma_- t} - e^{-\Gamma_+ t} \right]$$

$$\dot{x}(t) = A \left\{ -\Gamma_- e^{-\Gamma_- t} + \Gamma_+ e^{-\Gamma_+ t} \right\}$$

$$\dot{x}(0) = \frac{V}{2} = A \{ \Gamma_+ - \Gamma_- \} \text{ so}$$

$$x(t) = \frac{V}{2[\Gamma_+ - \Gamma_-]} \left(e^{-\Gamma_- t} - e^{-\Gamma_+ t} \right)$$

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b) Stopping distance.

Find when $\dot{x}(t) = 0$ for $t > 0$.

$$0 = -\Gamma_- e^{-\Gamma_- t} + \Gamma_+ e^{-\Gamma_+ t} \text{ so}$$

$$\Gamma_- e^{-\Gamma_- t} = \Gamma_+ e^{-\Gamma_+ t}$$

$$\frac{\Gamma_-}{\Gamma_+} = \exp[-t(\Gamma_+ - \Gamma_-)] \text{ or}$$

$$t^* = -\frac{1}{\Gamma_+ - \Gamma_-} \ln(\Gamma_- / \Gamma_+) \leftarrow \text{Note that this is } > 0 \text{ as required since } \Gamma_- < \Gamma_+.$$

Now plug back into the EOM

$$x(t^*) = \frac{V}{2[\Gamma_+ - \Gamma_-]} \left(e^{-\Gamma_- t^*} - e^{-\Gamma_+ t^*} \right) \text{ or}$$

$$x(t^*) = \frac{V e^{-\Gamma_- t^*}}{2[\Gamma_+ - \Gamma_-]} \left(1 - \frac{\Gamma_-}{\Gamma_+} \right) = \frac{V}{2\Gamma_+} e^{-\Gamma_- t^*}$$

Finally, plug in t^* from above:

$$-\Gamma_- t^* = \frac{\Gamma_-}{\Gamma_+ - \Gamma_-} \ln(\Gamma_- / \Gamma_+)$$

$$e^{-\Gamma_- t^*} = \left(\frac{\Gamma_-}{\Gamma_+} \right)^{\frac{\Gamma_-}{\Gamma_+ - \Gamma_-}} \text{ and}$$

$$\boxed{D = x(t^*) = \frac{V}{2\Gamma_+} \left(\frac{\Gamma_-}{\Gamma_+} \right)^{\frac{\Gamma_-}{\Gamma_+ - \Gamma_-}}}$$

4. Using the hint, we can write:

$$x(t) = \int dt' \frac{F(t')}{m\omega_1} e^{-\beta(t-t')} \sin[\omega_1(t-t')] \quad \text{[scribble]}$$

taking $\beta \rightarrow 0$ and using the fact that the force is on for a period $T = 2\pi/\omega_0$

$$x(t) = \int_{-T/2}^{T/2} dt' \frac{F_0 \sin(\omega_0 t')}{m\omega_0} \sin[\omega_0(t-t')]$$

expand the sine:

$$x(t) = \frac{F_0}{m\omega_0} \int_{-T/2}^{T/2} dt' \sin(\omega_0 t') \{ \sin(\omega_0 t) \cos(\omega_0 t') - \omega_0 t \sin(\omega_0 t') \}$$

$$x(t) = 0 - \frac{F_0}{m\omega_0} \cos(\omega_0 t) \int_{-T/2}^{+T/2} dt' \sin^2(\omega_0 t') = - \frac{F_0 \cos(\omega_0 t)}{m\omega_0} \frac{T}{2}$$

\Rightarrow for $t > T/2$ we have

$$x(t) = - \frac{F_0}{m\omega_0} \left(\frac{\pi}{\omega_0} \right) \cos(\omega_0 t)$$

Note that the amplitude will grow linearly with time of force application \Rightarrow resonance with no damping makes x blow up eventually.