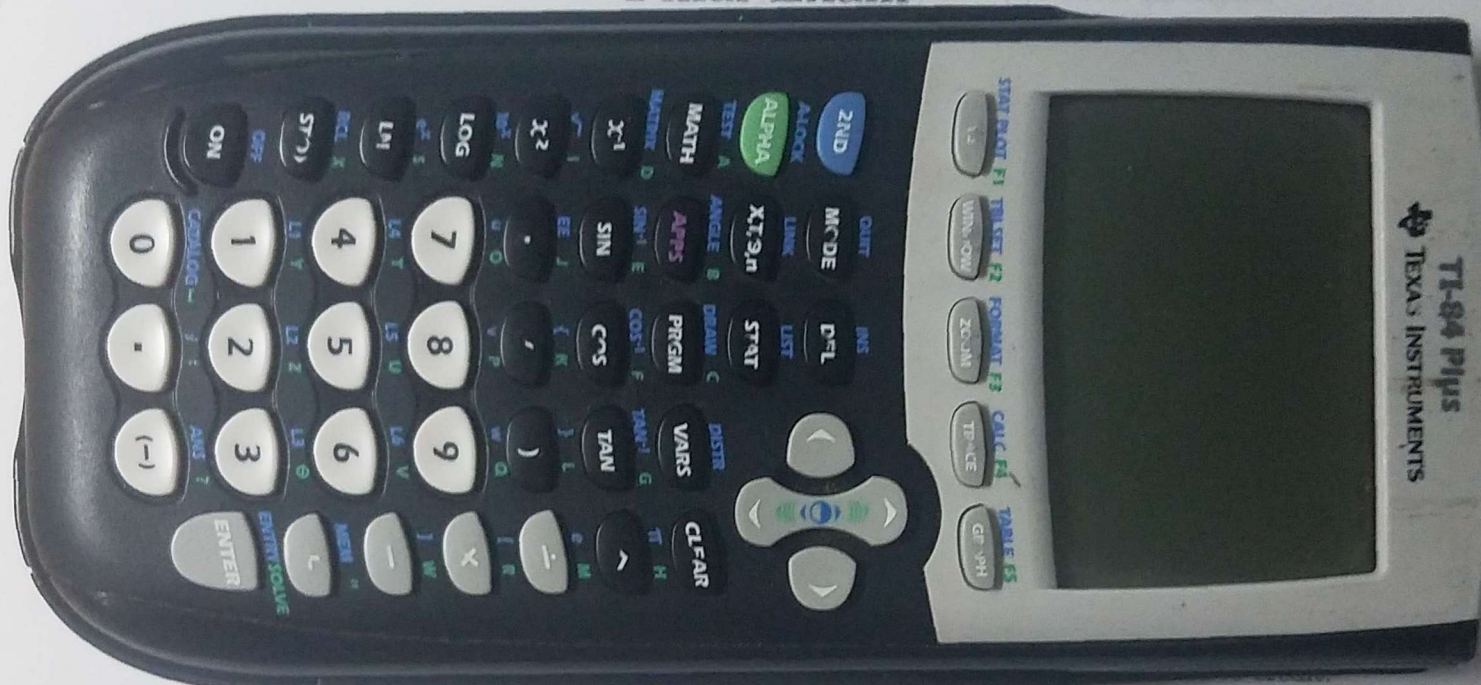


# Final Exam



Please circle or box your final answers. You may not use any other resources, including collaborating with other students. The use of any such additional resources is a form of academic dishonesty and may result in your exam being void. When uploading to Gradescope, please submit each question on a separate page.

Please do not write below this line.

Question	Points	Score
1	5	
2	5	
3	10	
4	20	
5	16	
6	10	
7	14	
8	20	
Total:	100	

1. (5 points) Suppose the first order linear differential equation  $x' + p(t)x = f(t)$  has an integrating factor  $v(t) = \sec(t)$ . What is  $p(t)$ ?

$$v(t) = \sec(t) = e^{\int p(t) dt}$$

$$\ln(\sec(t)) = \int p(t) dt$$

$$\frac{d}{dt}(\ln(\sec(t))) = \frac{d}{dt}\left(\int p(t) dt\right)$$

$$p(t) = \frac{1}{\sec(t)} \cdot \frac{-\sin(t)}{-\cos^2(t)} = \frac{\sin(t)}{\cos(t)} = \tan(t)$$

2. (5 points) A recipe calls for a gallon of salt water solution containing 5 ounces of a salt. In your 5 gallon container, you accidentally create a solution with twice that concentration. Suppose you can pour pure water into your container at a rate of 1 gallon per minute while draining it at the same rate. How long will you have to do this to bring your container to the correct concentration? (You may use a calculator to round your answer to one decimal place).

$x(t)$  = total oz salt in 5 gallon container

$$x'(t) = \frac{-x(t)}{5}$$

$$x(t) = A e^{\int -\frac{1}{5} dt} = A e^{-\frac{1}{5}t}$$

$$\text{initial: } \frac{5 \text{ oz}}{1 \text{ gal}} \cdot 5 \text{ gal} \cdot 2 = 50 \text{ oz} \quad x(0) = A = 50$$

$$\text{goal: } \frac{5 \text{ oz}}{1 \text{ gal}} \cdot 5 \text{ gal} = 25 \text{ oz}$$

$$x(t) = 50 e^{-\frac{1}{5}t}$$

$$25 = 50 e^{-\frac{1}{5}t}$$

$$\frac{1}{2} = e^{-\frac{1}{5}t}$$

$$\ln\left(\frac{1}{2}\right) = -\frac{1}{5}t$$

$$t = 5 \ln(2) \approx 3.5 \text{ minutes}$$

3. (a) (5 points) Consider the differential equation

$$y'' + 2y' - y = -5 \sin(2t)$$

Let  $y_p(t) = A \cos(2t) + B \sin(2t)$  and use the method of undetermined coefficients to calculate  $A$  and  $B$ . State the particular solution.

$$y_p'(t) = -2A \sin(2t) + 2B \cos(2t) \quad y_p''(t) = -4A \cos(2t) - 4B \sin(2t)$$

$$y_p'' + 2y_p' - y_p = -4A \cos(2t) - 4B \sin(2t) - 4A \sin(2t) + 4B \cos(2t) - A \cos(2t) - B \sin(2t)$$

$$= (-4A + 4B - A) \cos(2t) + (-4B - 4A - B) \sin(2t)$$

$$= (-5A + 4B) \cos(2t) + (-4A - 5B) \sin(2t) = -5 \sin(2t)$$

$$\begin{bmatrix} -5 & 4 \\ -4 & -5 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 0 \\ -5 \end{bmatrix} \quad \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} -5 & 4 \\ -4 & -5 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ -5 \end{bmatrix} = \frac{1}{41} \begin{bmatrix} -5 & -4 \\ 4 & -5 \end{bmatrix} \begin{bmatrix} 0 \\ -5 \end{bmatrix} = \begin{bmatrix} \frac{20}{41} \\ \frac{25}{41} \end{bmatrix}$$

$$A = \frac{20}{41} \quad B = \frac{25}{41} \quad y_p(t) = \frac{20}{41} \cos(2t) + \frac{25}{41} \sin(2t)$$

(b) (5 points) Consider the differential equation

$$z'' + 2z' - z = -5e^{2it}$$

Let  $z_p = ae^{2it}$  and use the method of undetermined coefficients to calculate  $a$  (simplify so that  $a$  has real denominator, if necessary). State the (complex) particular solution in the form  $x(t) + iy(t)$ .

$$z_p' = 2aie^{2it} \quad z_p'' = -4ae^{2it}$$

$$z_p'' + 2z_p' - z_p = -4ae^{2it} + 4aie^{2it} - ae^{2it} = -5ae^{2it} + 4aie^{2it} = -5e^{2it}$$

$$a(-5 + 4i) = -5$$

$$a = \frac{-5}{-5 + 4i} = \frac{-5(-5 - 4i)}{(-5 + 4i)(-5 - 4i)} = \frac{25 + 20i}{41}$$

$$z_p = \left( \frac{25 + 20i}{41} \right) e^{2it} = \left( \frac{25 + 20i}{41} \right) (\cos(2t) + i \sin(2t))$$

$$= \frac{25}{41} \cos(2t) + \frac{25}{41} i \sin(2t) + \frac{20}{41} i \cos(2t) - \frac{20}{41} \sin(2t)$$

$$= \left( \frac{25}{41} \cos(2t) - \frac{20}{41} \sin(2t) \right) + i \left( \frac{20}{41} \cos(2t) + \frac{25}{41} \sin(2t) \right)$$

4. (20 points) For each the systems below:

$$x' = \begin{pmatrix} 3 & -1 \\ 0 & 1 \end{pmatrix} x, \quad y' = \begin{pmatrix} 6 & -5 \\ 1 & 2 \end{pmatrix} y$$

- (a) (4 points) Give the characteristic polynomial and calculate the eigenvalues of the matrix.  
 (b) (4 points) Draw the phase plane portrait. Label the direction of motion (forward time), all eigenvectors, and the direction of rotation, if applicable.  
 (c) (2 point) Classify the equilibrium solution.

a.  $x' = \begin{pmatrix} 3 & -1 \\ 0 & 1 \end{pmatrix} x$

$T=4 \quad D=3$

$p(\lambda) = \lambda^2 - 4\lambda + 3 = 0$

$\lambda = 1, 3$

$\lambda_1 = 1 \quad \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix} \quad v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

$\lambda_2 = 3 \quad \begin{bmatrix} 0 & -1 \\ 0 & -2 \end{bmatrix} \quad v_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

a.  $y' = \begin{pmatrix} 6 & -5 \\ 1 & 2 \end{pmatrix} y$

$T=8 \quad D=17$

$p(\lambda) = \lambda^2 - 8\lambda + 17 = 0$

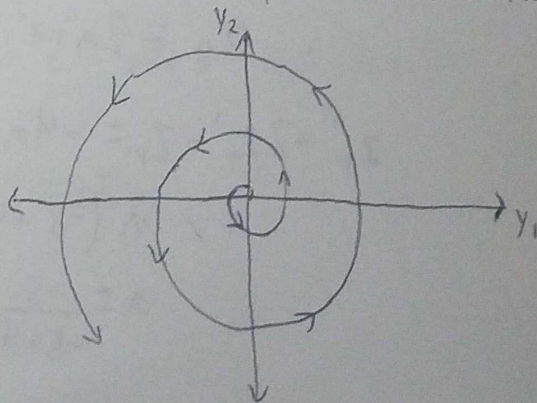
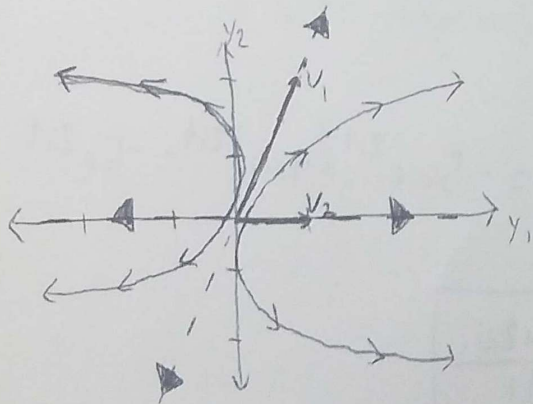
$\lambda = \frac{8 \pm \sqrt{64 - 4(17)}}{2} = \frac{8 \pm \sqrt{-4}}{2}$

$= 4 \pm i$

$\alpha = 4 > 0$

b. at  $y = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, y' = \begin{bmatrix} 6 \\ 1 \end{bmatrix}$

will spin counter-clockwise



c. nodal source

c. spiral source

5. Let  $c$  be a real number and consider the system

$$y' = \begin{pmatrix} c & 0 \\ 1 & 1 \end{pmatrix} y$$

- (a) (4 points) For what values of  $c$  will the equilibrium solution be a saddle point?
- (b) (4 points) For what values of  $c$  will the equilibrium solution be a nodal source?
- (c) (4 points) What values of  $c$  give *nongeneric* equilibrium solutions?
- (d) (4 points) Explain why no value of  $c$  will give a nodal or spiral sinks.

$$T = c + 1 \quad D = c$$

a. saddle points:  $D < 0$ , so  $c < 0$

b. nodal source:  $T > 0$ ,  $0 < D < \frac{1}{4} T^2$

$$\begin{aligned} \text{so } c + 1 > 0, \quad c > 0, \quad c &< \frac{1}{4} (c + 1)^2 \\ c &< \frac{1}{4} c^2 + \frac{1}{2} c + \frac{1}{4} \\ 0 &< \frac{1}{4} c^2 - \frac{1}{2} c + \frac{1}{4} \\ 0 &< c^2 - 2c + 1 = (c - 1)^2 \\ &c \neq 1 \end{aligned}$$

will be nodal source for all  $c > 0$  where  $c \neq 1$

c. nongeneric equilibrium solutions:  $D = 0$ ,  $T = 0$  and  $D \geq 0$ ,  $D = \frac{1}{4} T^2$

$c = 0$

↑  
impossible

$c = 1$

$c = 0$  and  $c = 1$  give nongeneric equilibrium solutions

d. for nodal or spiral sinks to be even possible,  $T < 0$  and  $D > 0$ , so  $T < D$ , but  $T = c + 1$  and  $D = c$ , so  $T = D + 1$ , so it is impossible for  $T < D$  so nodal or spiral sinks are impossible

6. Consider the system

$$y' = \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix} y$$

- (a) (3 points) Show that the system has infinitely many equilibrium (i.e. constant) solutions.  
 (b) (3 points) What is the dimension of the nullspace of  $A$ ?  
 (c) (4 points) Find a fundamental set of solutions (write your final answers explicitly, without exponential matrices).

a.  $y' = 0 = \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix} y$      $y = \begin{bmatrix} c \\ c \end{bmatrix}$  where  $c$  is any constant  
 so any multiple of  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is an equilibrium solution, thus there are infinite equilibrium solutions

b.  $\left[ \begin{array}{cc|c} 1 & -1 & 0 \\ 1 & -1 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$      $v = \begin{bmatrix} c \\ c \end{bmatrix}$  nullspace of  $A$  is span  $\left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$ , so has dimension 1

c.  $p(\lambda) = \lambda^2 = 0$      $\lambda = 0$

$\lambda_1 = 0$      $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$      $y_1(t) = e^{0t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$y_2(t) = e^{0t} (v_2 + t v_1) = v_2 + t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$(A - \lambda I) v_2 = v_1$      $\begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\left[ \begin{array}{cc|c} 1 & -1 & 1 \\ 1 & -1 & 1 \end{array} \right] \rightarrow \left[ \begin{array}{cc|c} 1 & -1 & 1 \\ 0 & 0 & 0 \end{array} \right]$      $v_2 = \begin{bmatrix} c+1 \\ c \end{bmatrix}$   
 $v_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$y_2(t) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1+t \\ t \end{bmatrix}$

$y(t) = C_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + C_2 \begin{bmatrix} 1+t \\ t \end{bmatrix}$

7. Consider the following matrix

$$A = \begin{pmatrix} 1 & 1 & 1 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

- (a) (4 points) Give the characteristic polynomial of  $A$  and calculate the eigenvalues of  $A$ .
- (b) (4 points) Determine the dimension of the nullspace of  $(A - \lambda_i I)$  for each eigenvalue  $\lambda_i$  found above.
- (c) (6 points) Find a fundamental set of solutions to the system  $y' = Ay$  (write your final answers explicitly, without exponential matrices)

a.  $p(\lambda) = -\lambda \left( (1-\lambda)(-1-\lambda) + 1 \right) = -\lambda (-1-\lambda+\lambda+\lambda^2+1) = -\lambda^3 = 0$

$\lambda = 0$

b.  $\lambda = 0$   $\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ -1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$   $v = \begin{bmatrix} c \\ c \\ 0 \end{bmatrix}$  nullspace of  $A$  is span  $\left( \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \right)$ , so it is of dimension 1

c.  $\lambda_1 = 0$   $v_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$   $y_1 = e^{0t} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$

$A^2 = \begin{bmatrix} 1 & 1 & 1 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$   $\left[ \begin{array}{ccc|c} 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$

$v = \begin{bmatrix} c_1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ c_2 \\ 0 \end{bmatrix}$

$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  are in nullspace of  $A^2$ , but both of them together

are not linearly independent with  $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$ , can only use one, use  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$v_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$   $y_2 = e^{A^2 t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1+t \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$

$A^3 = \begin{bmatrix} 1 & 1 & 1 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

all vectors are in nullspace of  $A^3$ , choose  $v_3$  linearly independent from  $v_1$  and  $v_2$

$v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$   $y_3 = e^{A^3 t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \frac{t^2}{2} \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}$

$y(t) = c_1 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 1+t \\ -t \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 1+t \\ -t \\ \frac{t^2}{2} \end{bmatrix}$

8. (20 points) True or False (2 points each). All matrices are assumed to have real entries.

- (a) (True or False) The differential equation  $P(x, y)dx - Q(x, y)dy = 0$  is exact if

$$\frac{\partial P}{\partial y} = -\frac{\partial Q}{\partial x}$$

- (b) (True or False) If the eigenvalues of a  $2 \times 2$  matrix  $A$  are both positive, then the nonequilibrium solutions to  $x' = Ax$  all satisfy  $\lim_{t \rightarrow \infty} x(t) = 0$ .

- (c) (True or False) If  $x_0$  is an equilibrium solution for an autonomous equation  $x' = f(x)$ , then  $x_0$  is stable if  $f'(x_0) > 0$ .

- (d) (True or False) A  $3 \times 3$  matrix cannot have all complex eigenvalues.

- (e) (True or False) The function  $v(t) = e^{-\int p(t)dt}$  is an integrating factor for

$$\frac{dx}{dt} + p(t)x = f(t)$$

- (f) (True or False) There is a polynomial solution to  $y' = 4 - y^2$ .

- (g) (True or False) If  $A$  is any  $n \times n$  matrix and  $v$  is any  $n$ -vector, then  $y(t) = e^{tA}v$  is a solution to the linear system  $y' = Ay$ .

- (h) (True or False) If  $A, B$  are  $2 \times 2$  matrices with  $\det(A) = -\det(B)$  and  $\text{trace}(A) = -\text{trace}(B)$ , then either  $x' = Ax$  or  $x' = Bx$  has a saddle point equilibrium solution.

- (i) (True or False) If  $A$  is a  $2 \times 2$  matrix with  $\det(A) = 0$ , then  $x' = Ax$  has infinitely many equilibrium solutions.

- (j) (True or False) The level set  $xy + y^2 = c$  solves the differential equation

$$ydx + (2y + x)dy = 0$$