

1. Consider the matrix

$$A = \begin{pmatrix} 1 & 4 & -2 \\ 1 & 4 & -2 \end{pmatrix}_{2 \times 3}$$

Recall that A corresponds to a linear transformation T_A .

(a) [2 pts] What are the domain and range of T_A ?

$\text{range} = \text{im}(T_A)$
 $\text{domain} = \text{ker}(T_A)$
 The domain is \mathbb{R}^3
 The range is \mathbb{R}^2

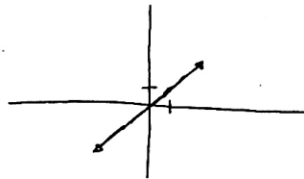
$$\begin{bmatrix} 1 & 4 & -2 & 0 \\ 1 & 4 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$\text{image} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$
 $x_1 = -4x_2 - 2x_3 \quad \text{span} \left(\begin{bmatrix} -4 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \end{bmatrix} \right)$

(b) [2 pts] Describe the image of T_A as a span of vector(s).

$\text{im}(T_A) = \text{span}(\text{columns})$
 The image of T_A is $\text{span} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$

(c) [4 pts] Describe the image of T_A geometrically. Is it a line? A plane? Draw it.



The image of T_A is
the span of the line

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

2. [6 pts] Is the vector $\vec{b} = \begin{pmatrix} -4 \\ -3 \\ 2 \end{pmatrix}$ a linear combination of the vectors $\vec{v} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ and $\vec{w} = \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}$? If so, write down the linear combination in the format $\vec{b} = c_1\vec{v} + c_2\vec{w}$. If not, explain why not.



$$c_1\vec{v} + c_2\vec{w} = \vec{b}$$

$$c_1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -4 \\ -3 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 1 & -4 \\ 0 & 1 & 1 & -3 \\ 1 & 1 & 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 1 & -4 \\ 1 & 1 & 1 & 2 \\ 0 & 1 & 1 & -3 \end{bmatrix} \begin{array}{l} -3(\text{II}) \\ -(\text{II}) \end{array}$$

$$\begin{bmatrix} 1 & 0 & 1 & 5 \\ 1 & 0 & 1 & 5 \\ 0 & 1 & 1 & -3 \end{bmatrix} -\text{I}$$

$$\begin{bmatrix} 1 & 0 & 1 & 5 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & -3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 1 & 5 \\ 0 & 1 & 1 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

if $c_2 = -3$, then

$$c_1 = ?$$

$$c_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + -3 \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}$$

$$c_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} -9 \\ -3 \\ -3 \end{pmatrix} = \begin{pmatrix} -4 \\ -3 \\ 2 \end{pmatrix}$$

$$\text{if } c_1 = 5$$

$$\vec{b} = 5\vec{v} - 3\vec{w}$$

3. [5 pts] Consider the following matrix:

$$A = \begin{pmatrix} 1 & 2 & -1 & 1 \\ -1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 3 & 4 & -3 & 1 \\ 1 & 1 & -1 & 0 \end{pmatrix} \begin{matrix} +5 \\ +3(\text{II}) \\ +\text{IV} \end{matrix}$$

$$\begin{pmatrix} 1 & 2 & -1 & 1 \\ 0 & 2 & 0 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & 4 \\ 0 & 1 & 0 & 1 \end{pmatrix} \begin{matrix} \\ \\ \\ \\ -2 \end{matrix}$$

$$\begin{pmatrix} 1 & 2 & -1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} -2 \\ \\ \\ \\ \end{matrix}$$

$\begin{cases} x_1 = x_3 + x_4 \\ x_2 = -x_4 \end{cases}$

Circle all of the following vectors which are members of $\ker(A)$.

$\vec{v} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$,
 $\vec{w} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$,
 $\vec{x} = \begin{pmatrix} 2 \\ 0 \\ 2 \\ 0 \end{pmatrix}$,
 $\vec{y} = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 1 \end{pmatrix}$,
 $\vec{z} = \begin{pmatrix} 1 \\ -1 \\ 0 \\ 1 \end{pmatrix}$

$$\left[\begin{array}{cccc|cccc} 1 & 2 & -1 & 1 & 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & -3 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\left[\begin{array}{cccc|cccc} 1 & 2 & -1 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 3 & 4 & -3 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{matrix} +\text{II} \\ +3(\text{II}) \end{matrix}$$

$$\left[\begin{array}{cccc|cccc} 1 & 2 & -1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ -1 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & 4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{matrix} -\text{I} \\ -4(\text{II}) \end{matrix}$$

$$\left[\begin{array}{cccc|cccc} 1 & 2 & -1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{matrix} -2(\text{II}) \\ +\text{II} \end{matrix}$$

$$\left[\begin{array}{cccc|cccc} 1 & 0 & -1 & -1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$\begin{cases} x_1 = x_3 + x_4 \\ x_2 = -x_4 \end{cases}$

$$s \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

4. Suppose you know that $A^{-1} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$ and $B^{-1} = \begin{pmatrix} -1 & 1 \\ 3 & 2 \end{pmatrix}$.

6 (a) [6 pts] Find $(AB)^{-1}$.

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$\begin{pmatrix} -1 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -2+1 & -1+1 \\ 6+2 & 3+2 \end{pmatrix} \\ = \begin{pmatrix} -1 & 0 \\ 8 & 5 \end{pmatrix}$$

6 (b) [6 pts] Find B .

$$(B^{-1})^{-1} = B$$

$$\frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \rightarrow \frac{1}{-2 - 3} \begin{bmatrix} 2 & -1 \\ -3 & -1 \end{bmatrix} = \begin{bmatrix} \frac{2}{5} & \frac{1}{5} \\ \frac{3}{5} & \frac{1}{5} \end{bmatrix}$$

2 (c) [2 pts] What was the rank of A ? (this should require no computations)

The rank of A is 2. If it is invertible,
then the rank of a 2×2 matrix is 2.

5. (a) [2 pts] Write down the 2x2 matrix for rotation by an angle θ .

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

- (b) [2 pts] Use the determinant to show that this matrix is invertible.

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The determinant is $ad - bc$

$$\begin{aligned} \cos^2 \theta + \sin^2 \theta \\ = 1 \end{aligned}$$

Since the determinant is not zero, the matrix is invertible.

- (c) [3 pts] Explain geometrically what the inverse matrix should do, and write the inverse matrix down.

The inverse matrix should rotate, so that the original orientation is returned to. It is a clockwise rotation by angle θ .

$$\frac{1}{\cos^2 \theta + \sin^2 \theta} \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \quad \cos^2 \theta + \sin^2 \theta = 1, \text{ so}$$

$$= \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \quad \text{is the inverse matrix}$$

6. [4 pts] Suppose you know that \vec{w} is in $\ker(B)$, and you also know that $B\vec{v} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$. Use this information to find $B(3\vec{w} - 2\vec{v})$.

$$B(3\vec{w} - 2\vec{v}) = 3B(\vec{w}) - 2B(\vec{v})$$

$$B(\vec{w}) = 0 \text{ because it is in the kernel of } B.$$

$$0 - 2 \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

$$B(3\vec{w} - 2\vec{v}) = \begin{pmatrix} -2 \\ -4 \\ -6 \end{pmatrix}$$

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7. True or false (circle your answer; no justification needed). In all of the problems below, A is an $n \times n$ square matrix.

- (a) [2 pts] If A is the coefficient matrix for some linear system, and $\text{rank}(A) = n$, then the system has a unique solution.

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TRUE

FALSE

- (b) [2 pts] If A is the coefficient matrix for some linear system, and $\text{rank}(A) < n$, then the system must have infinitely many solutions.

TRUE

FALSE

- (c) [2 pts] If A is the coefficient matrix for some linear system, and the system had a unique so-

lution, then the RREF of A must be precisely the identity matrix $I_n = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & & 0 \\ 0 & 0 & 1 & & 0 \\ \vdots & & & \ddots & \\ 0 & 0 & 0 & \cdots & 1 \end{pmatrix}$.

TRUE

FALSE