

1. True or False questions (10 points total); circle 'T' if the item is true or 'F' if the item is false.

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

- a. (2 points) If the matrix A represents a rotation through $\pi/2$ and the matrix B a rotation through $\pi/4$, then A and B are similar.

$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} \frac{1}{2}a + \frac{1}{2}b & -\frac{1}{2}a + \frac{1}{2}b \\ \frac{1}{2}c + \frac{1}{2}d & \frac{1}{2}c + \frac{1}{2}d \end{bmatrix}$$

$$\begin{aligned} \frac{1}{\sqrt{2}}(a+b)^T &= -c \\ \frac{1}{\sqrt{2}}(-a+b) &= -d \\ \frac{1}{\sqrt{2}}(c+d) &= a \end{aligned}$$

(F)

- b. (2 points) If A and B are similar, and A is invertible, then B must be invertible as well.

$$AS = SB$$

$$A^{-1}A = I$$

(T)

F

- c. (2 points) If A is an invertible matrix, then the equation $(A^{-1})^T = (A^T)^{-1}$ must hold.

(T)

F

- d. (2 points) For all 4×4 matrices A , $\det(4A) = 4 \det A$.

T

(F)

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \det A = 1 \quad \begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix} = 16^2$$

16
16

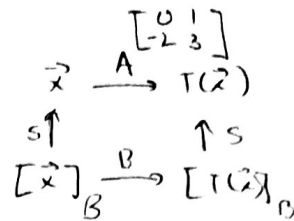
- e. (2 points) If A is an $n \times n$ matrix such that $A = SBS^{-1}$, then $\det A^5 = \det B^5$.

$$\det(A) = \det(B)$$

if similar

(T)

F

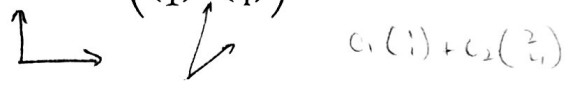


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2. (10 points) Suppose that

$$T(\vec{x}) = A\vec{x} = \begin{pmatrix} 0 & 1 \\ -2 & 3 \end{pmatrix} \vec{x}$$

is a linear transformation expressed as the matrix A with respect to the standard basis $\mathcal{S} = (\vec{e}_1, \vec{e}_2)$. Let $\mathcal{B} = (\vec{v}_1, \vec{v}_2) = \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 4 \end{pmatrix} \right)$ be another basis for \mathbb{R}^2 .



a. (7 points) Find the matrix $B = [T]_{\mathcal{B}}$, which expresses the linear transformation T as a matrix with respect to the basis \mathcal{B} .

$\mathcal{S} = \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right)$ $\mathcal{B} = \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 4 \end{pmatrix} \right)$ $A\mathcal{S} = \mathcal{S}B$

$$[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$\left[\begin{array}{c|c} 1 & 2 \\ \hline 0 & 0 \end{array} \right] \xrightarrow{-(I)} \left[\begin{array}{c|c} 1 & 2 \\ \hline 0 & -2 \end{array} \right] \xrightarrow{\div 2} \left[\begin{array}{c|c} 1 & 2 \\ \hline 0 & -1 \end{array} \right] \xrightarrow{+2(I)} \left[\begin{array}{c|c} 1 & 0 \\ \hline 0 & -1 \end{array} \right]$$

$$\left[\begin{array}{c|c} 1 & 1 \\ \hline 0 & 3 \end{array} \right] \xrightarrow{-(I)} \left[\begin{array}{c|c} 1 & 1 \\ \hline 0 & 2 \end{array} \right] \xrightarrow{\div 2} \left[\begin{array}{c|c} 1 & 1 \\ \hline 0 & 1 \end{array} \right] \xrightarrow{-2(I)} \left[\begin{array}{c|c} 1 & -1 \\ \hline 0 & 1 \end{array} \right]$$

$$B = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

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b. (3 points) Find A^5 . (Hint: your work in part 'a.' might be useful.)

$$\begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} -2 & 3 \\ -6 & 7 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} -6 & 7 \\ -14 & 15 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} -14 & 15 \\ -30 & 31 \end{bmatrix}$$

$$\begin{bmatrix} -14 & 15 \\ -30 & 31 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} -30 & 31 \\ -62 & 63 \end{bmatrix}$$

✓

3. (10 points total) Let $A = \begin{pmatrix} 3 & 3 & 0 \\ 4 & 4 & 0 \\ 0 & 3 & -4 \\ 0 & 4 & 3 \end{pmatrix}$.

a. (7 points) Find the QR-decomposition of A . Make sure to show your work.

work. $\vec{v}_1 = \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix}$ $\vec{v}_2 = \begin{bmatrix} 3 \\ 4 \\ 3 \\ 4 \end{bmatrix}$ $\vec{v}_3 = \begin{bmatrix} 0 \\ 3 \\ -4 \\ 3 \end{bmatrix}$

$\vec{u}_1 = \frac{1}{5} \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix}$

$\vec{v}_2^\perp = \vec{v}_2 - (\vec{u}_1 \cdot \vec{v}_2) \vec{u}_1$

$= \begin{bmatrix} 3 \\ 4 \\ 3 \\ 4 \end{bmatrix} - \left(\frac{1}{5} \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 4 \\ 3 \\ 4 \end{bmatrix} \right) \frac{1}{5} \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix}$

$= \begin{bmatrix} 3 \\ 4 \\ 3 \\ 4 \end{bmatrix} - \left(\frac{1}{5} (25) \right) \left(\frac{1}{5} \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix} \right)$

$= \begin{bmatrix} 0 \\ 0 \\ 5 \\ 5 \end{bmatrix}$

$\vec{u}_2 = \frac{1}{\sqrt{50}} \begin{bmatrix} 0 \\ 0 \\ 5 \\ 5 \end{bmatrix}$

$\vec{v}_3^\perp = \vec{v}_3 - (\vec{u}_1 \cdot \vec{v}_3) \vec{u}_1 - (\vec{u}_2 \cdot \vec{v}_3) \vec{u}_2$

$= \begin{bmatrix} 0 \\ 3 \\ -4 \\ 3 \end{bmatrix} - \left(\frac{1}{5} \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 3 \\ -4 \\ 3 \end{bmatrix} \right) \frac{1}{5} \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix} - \left(\frac{1}{\sqrt{50}} \begin{bmatrix} 0 \\ 0 \\ 5 \\ 5 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 3 \\ -4 \\ 3 \end{bmatrix} \right) \frac{1}{\sqrt{50}} \begin{bmatrix} 0 \\ 0 \\ 5 \\ 5 \end{bmatrix}$

$= \begin{bmatrix} 0 \\ 3 \\ -4 \\ 3 \end{bmatrix} - \left(\frac{1}{5} \begin{bmatrix} 0 \\ 12 \\ -12 \\ 12 \end{bmatrix} \right) \frac{1}{5} \begin{bmatrix} 3 \\ 4 \\ 0 \\ 0 \end{bmatrix} - \left(\frac{1}{\sqrt{50}} \begin{bmatrix} 0 \\ 15 \\ -25 \\ 15 \end{bmatrix} \right) \frac{1}{\sqrt{50}} \begin{bmatrix} 0 \\ 0 \\ 5 \\ 5 \end{bmatrix}$

$= \begin{bmatrix} 0 \\ 3 \\ -4 \\ 3 \end{bmatrix} - \begin{bmatrix} 0 \\ 12 \\ -12 \\ 12 \end{bmatrix} - \begin{bmatrix} 0 \\ 15 \\ -25 \\ 15 \end{bmatrix}$

$\vec{u}_3 = \frac{1}{\sqrt{14}} \begin{bmatrix} 0 \\ 3 \\ -4 \\ 3 \end{bmatrix}$

$\begin{bmatrix} 3 & 3 & 0 \\ 4 & 4 & 0 \\ 0 & 3 & -4 \\ 0 & 4 & 3 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 3 & 0 & 0 \\ 4 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 5 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & -4 \\ 0 & 0 & 5 \end{bmatrix}$

b. (3 points) Find the matrix which represents orthogonal projection onto the subspace of \mathbb{R}^4 which is defined by the columns of A .

3 $Q Q^T$ $Q^T = \frac{1}{5} \begin{bmatrix} 3 & 4 & 0 & 0 \\ 0 & 0 & 3 & 4 \\ 0 & 0 & -4 & 3 \end{bmatrix}$

$\frac{1}{25} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 3 & -4 \\ 0 & 4 & 3 \end{bmatrix} \begin{bmatrix} 3 & 4 & 0 & 0 \\ 0 & 0 & 3 & 4 \\ 0 & 0 & -4 & 3 \end{bmatrix} = \frac{1}{25} \begin{bmatrix} 9 & 12 & 0 & 0 \\ 0 & 16 & 0 & 0 \\ 0 & 0 & 20 & 0 \\ 0 & 0 & 0 & 25 \end{bmatrix}$

4. (10 points) Find the equation of the line which best fits, in the least squares sense, the following points in the 'x, y'-plane: (-1, -1), (0, 1), (1, 4).

$$c_0 + c_1 t \quad (-1, -1) \quad (0, 1) \quad (1, 4)$$

$$\begin{cases} c_0 - c_1 = -1 \\ c_0 = 1 \\ c_0 + c_1 = 4 \end{cases} \quad A = \begin{bmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} c_0^* \\ c_1^* \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix}$$

$$(A^T A)^{-1} A^T \vec{b}$$

$$A^T A = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 0 & : & 1 & 0 \\ 0 & 2 & : & 0 & 1 \\ 1 & 0 & : & 1/2 & 0 \\ 0 & 1 & : & 0 & 1/2 \end{bmatrix} \begin{matrix} \div 3 \\ \div 2 \\ \\ \end{matrix}$$

$$(A^T A)^{-1} = \frac{1}{6} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$$

$$(A^T A)^{-1} A^T = \frac{1}{6} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 2 & 2 & 2 \\ -3 & 0 & 3 \end{bmatrix}$$

$$(A^T A)^{-1} A^T \vec{b} = \frac{1}{6} \begin{bmatrix} 2 & 2 & 2 \\ -3 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 12 \\ 9 \end{bmatrix} = \begin{bmatrix} 2 \\ 3/2 \end{bmatrix}$$

$$\boxed{y = \cancel{2} + 3/2 t}$$

(-1)