

Last Name: _____

First Name: _____

Student ID number: _____

Instructions:

- You have 50 minutes for this exam.
- Show all work, clearly and in order, if you want to get full credit. I reserve the right to take off points if I cannot see how you arrived at your answer (even if your final answer is correct).
- Circle or otherwise indicate your final answers. If you use the back of a page please indicate that you have work on the reverse side.
- You may not use books, notes, calculators, mobile phones, or any outside help during this exam. You may not collaborate with other students in any way during this exam.

| Problem | Points | Score |
|---------|--------|-------|
| 1 | 10 | |
| 2 | 10 | |
| 3 | 10 | |
| 4 | 10 | |
| Total | 40 | |

1. (10 points total) Circle "T" if the statement is true and "F" if false. You need not show your work. No partial credit will be given.

a. (2 points) If A and B are matrices such that $C = AB$ exists and C^{-1} exists, then A and B are both invertible.

T F If $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$
 $AB = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = C$ & C^{-1} exists, but A & B aren't invertible

b. (2 points) If $AB = 0$ then it is always true that either $A = 0$ or $B = 0$. Here 0 is the zero matrix.

T F If $A = \begin{bmatrix} 1 & 0 \end{bmatrix}$ & $B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, then $AB = 0$, but neither A nor B is zero

c. (2 points) If A is an $n \times n$ matrix such that $A^2 = A$, and A is not the identity matrix I_n , then $\ker(I_n - A) = \text{im}(A)$.

T F $(I_n - A)A\vec{x} = (A - A^2)\vec{x} = (A - A)\vec{x} = 0\vec{x} = \vec{0}$
 $\Rightarrow A\vec{x} \in \ker(I_n - A)$. Hence $\text{im}(A) \subset \ker(I_n - A)$
 Now if $(I_n - A)\vec{x} = 0$, $\vec{x} = A\vec{x} \Rightarrow \ker(I_n - A) \subset \text{im}(A)$
 $\therefore \ker(I_n - A) = \text{im}(A)$

d. (2 points) There is a square matrix whose image equals its kernel.

T F $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} y \\ 0 \end{bmatrix}$ $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
 $\Rightarrow \text{im} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \text{span} \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$ $\Rightarrow \begin{bmatrix} y \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
 $\Rightarrow \ker \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \text{span} \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$

e. (2 points) $T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ x \\ y - 1 \end{pmatrix}$ is a linear transformation.

T F $T \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \Rightarrow T$ is not linear, since $T(\vec{0}) \neq \vec{0}$ for all linear transformations

2. (10 points total) The following problem has parts a) and b):

a. (5 points) Find the reduced row-echelon form of

$$M := \begin{pmatrix} 1 & 6 & 7 & 1 & 0 & 0 \\ 1 & 6 & 6 & 0 & 1 & 0 \\ 1 & 5 & 4 & 0 & 0 & 1 \end{pmatrix} \begin{array}{l} r_2 \rightarrow r_2 - r_1 \\ r_3 \rightarrow r_3 - r_1 \end{array}$$

$$\rightarrow \begin{pmatrix} 1 & 6 & 7 & 1 & 0 & 0 \\ 0 & 0 & -1 & -1 & 1 & 0 \\ 0 & -1 & -3 & -1 & 0 & 1 \end{pmatrix} \begin{array}{l} \text{swap} \\ r_2 \leftrightarrow r_3 \end{array} \rightarrow \begin{pmatrix} 1 & 6 & 7 & 1 & 0 & 0 \\ 0 & -1 & -3 & -1 & 0 & 1 \\ 0 & 0 & -1 & -1 & 1 & 0 \end{pmatrix} \begin{array}{l} r_2 \rightarrow -r_2 \\ r_3 \rightarrow -r_3 \end{array}$$

$$\rightarrow \begin{pmatrix} 1 & 6 & 7 & 1 & 0 & 0 \\ 0 & 1 & 3 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \end{pmatrix} \begin{array}{l} r_1 \rightarrow r_1 - 7r_3 \\ r_2 \rightarrow r_2 - 3r_3 \end{array} \rightsquigarrow \begin{pmatrix} 1 & 6 & 0 & -6 & 7 & 0 \\ 0 & 1 & 0 & -2 & 3 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \end{pmatrix} \begin{array}{l} r_1 \leftrightarrow r_1 - 6r_2 \end{array}$$

$$\rightsquigarrow \begin{pmatrix} 1 & 0 & 0 & 6 & 11 & 6 \\ 0 & 1 & 0 & -2 & 3 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \end{pmatrix} = \text{rref}(M)$$

Note that the process of computing $\text{rref}(M)$ gives $A = \begin{pmatrix} 1 & 6 & 7 \\ 1 & 6 & 6 \\ 1 & 5 & 4 \end{pmatrix}^{-1} \Leftrightarrow A^{-1} = \begin{pmatrix} 1 & 6 & 7 \\ 1 & 6 & 6 \\ 1 & 5 & 4 \end{pmatrix}$

b. (5 points) Solve the equation $A\vec{x} = \vec{b}$ for \vec{x} when

$$A = \begin{pmatrix} 6 & -11 & 6 \\ -2 & 3 & -1 \\ 1 & -1 & 0 \end{pmatrix} \text{ and } \vec{b} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}.$$

$$\text{Thus } \vec{x} = A^{-1}\vec{b} = \begin{pmatrix} 1 & 6 & 7 \\ 1 & 6 & 6 \\ 1 & 5 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 14 \\ 13 \\ 10 \end{pmatrix}$$

$$\therefore \vec{x} = \begin{pmatrix} 14 \\ 13 \\ 10 \end{pmatrix}$$

3. (10 points total) Let $V = \text{span}(v_1, v_2, v_3, v_4, v_5)$, where

$$v_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, v_2 = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix}, v_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, v_4 = \begin{pmatrix} 3 \\ 7 \\ 11 \end{pmatrix}, v_5 = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix}.$$

a. (2 points) Are the vectors whose span defines V linearly independent or linearly dependent? Explain why or why not.

$v_2 = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = v_1 + v_3$ so the vectors v_1, \dots, v_5 whose span define V are linearly dependent

b. (4 points) Find a basis for V .

Let $A = \begin{bmatrix} 1 & 2 & 1 & 3 & 3 \\ 2 & 3 & 1 & 7 & 4 \\ 3 & 4 & 1 & 11 & 5 \end{bmatrix}$ $r_2 \mapsto r_2 - 2r_1$
 $r_3 \mapsto r_3 - 3r_1$

$$\rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 3 & 3 \\ 0 & -1 & -1 & 1 & -2 \\ 0 & -2 & -2 & 2 & -4 \end{bmatrix} \begin{matrix} \\ \\ r_3 \mapsto r_3 - 2r_2 \end{matrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 3 & 3 \\ 0 & -1 & -1 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} \\ r_2 \mapsto -r_2 \\ \end{matrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 3 & 3 \\ 0 & 1 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} r_1 \mapsto r_1 - 2r_2 \\ \\ \end{matrix} \rightsquigarrow \begin{bmatrix} 1 & 0 & -1 & 5 & -1 \\ 0 & 1 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$\Rightarrow v_1$ & v_2 span V and are linearly independent, hence $\mathcal{B} = (v_1, v_2)$ is a basis for V .

c. (4 points) Find the kernel of the matrix $A = [v_1 \ v_2 \ v_3 \ v_4 \ v_5]$.

By the computation in part b)

$$\text{rref}(A) = \begin{bmatrix} 1 & 0 & -1 & 5 & -1 \\ 0 & 1 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} x_1 - x_3 + 5x_4 - x_5 = 0 \\ x_2 + x_3 - x_4 + 2x_5 = 0 \\ \end{matrix}$$

$$\Rightarrow x_1 = r - 5s + t \quad \text{and} \quad x_2 = -r + s - 2t \quad \text{with}$$

$$x_3 = r, \quad x_4 = s, \quad \text{and} \quad x_5 = t, \quad \text{so}$$

$$\begin{aligned} \text{ker } A &= \left\{ \begin{pmatrix} r - 5s + t \\ -r + s - 2t \\ r \\ s \\ t \end{pmatrix} \mid r, s, t \in \mathbb{R} \right\} = \left\{ r \begin{pmatrix} 1 \\ -1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} -5 \\ 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 1 \\ -2 \\ 0 \\ 0 \\ 1 \end{pmatrix} \mid r, s, t \in \mathbb{R} \right\} \\ &= \text{span} \left(\begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right) \end{aligned}$$

4. (10 points total) The following problem has parts a) and b):

a. (6 points) Find the 3×3 matrix which represents orthogonal

projection onto the line spanned by $v = \begin{pmatrix} 1 \\ 3 \\ 4 \end{pmatrix}$. $\|v\| = \sqrt{1+9+16} = \sqrt{26}$

Let $V = \text{span } v = \text{span} \left(\begin{pmatrix} 1 \\ 3 \\ 4 \end{pmatrix} \right)$

$$T := \text{Proj}_V x = \left(\frac{v \cdot x}{\|v\|^2} \right) \frac{v}{\|v\|} = \frac{1}{26} (v \cdot x) v$$

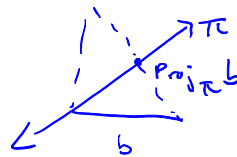
Recall that the matrix of a linear transformation has the form $[Te_1, Te_2, Te_3]$, so

$$A = \left[\frac{1}{26} (v \cdot e_1) v \quad \frac{1}{26} (v \cdot e_2) v \quad \frac{1}{26} (v \cdot e_3) v \right] = \frac{1}{26} \begin{bmatrix} 1 & 3 & 4 \\ 3 & 9 & 12 \\ 4 & 12 & 16 \end{bmatrix}$$

b. (4 points) Find the matrix which represents reflection across the plane in \mathbb{R}^3 defined by the equation $x + 3y + 4z = 0$.

Projection onto the plane π is $(I - A) = B$ for A as in part a). Reflection is related to projection

by
$$\begin{aligned} \text{Ref}_\pi &= I - 2(I - \text{Proj}_\pi) \\ &= 2\text{Proj}_\pi - I \end{aligned}$$



$$\begin{aligned} &= 2B - I = 2(I - A) - I = 2I - 2A - I \\ &= I - 2A \end{aligned}$$

$$\therefore \text{Ref}_\pi = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \frac{1}{13} \begin{bmatrix} 1 & 3 & 4 \\ 3 & 9 & 12 \\ 4 & 12 & 16 \end{bmatrix} \quad \checkmark$$