

**This exam is DUE Wednesday, June 10th at 8AM Pacific Time on CCLE.**

You have 24 hours to complete and submit this exam, from 8:00 AM Pacific Time on Tuesday, June 9th, to 8:00 AM Pacific Time on Wednesday, June 10th. I have designed this exam to have the same length as if you only had 3 hours to complete it; it is your responsibility to save time for uploading. If you encounter technical difficulties, please email me immediately.

If you have any questions, email me at rousden@math.ucla.edu

Good luck!

Your Name: \_\_\_\_\_

Your Student ID: \_\_\_\_\_

1. (10 points) Indicate which of the following are true or false; no justification is required:

- (a) (1 point) Every  $2 \times 2$  reflection matrix is positive definite. (T/F) **(F)**
- (b) (1 point) 0-dimensional subspaces do not exist. (T/F) **(F)**
- (c) (1 point) The equation  $(A + B)(A - B) = A^2 - AB + BA - B^2$  is true for all  $2 \times 2$  matrices A and B. (T/F) **(T)**
- (d) (1 point) Every diagonalizable matrix with real coefficients is symmetric. (T/F) **(F)**
- (e) (1 point) Every  $2 \times 2$  shearing matrix is diagonalizable over  $\mathbb{R}$ . (T/F) **(F)**
- (f) (1 point) The list  $\left( \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right)$  is linearly independent. (T/F) **(F)**
- (g) (1 point) The equation  $\det(A) = \det(\text{rref}(A))$  is true for all  $5 \times 5$  matrices A. (T/F) **(F)**
- (h) (1 point) Every  $2 \times 2$  matrix with 2 distinct eigenvalues is diagonalizable. (T/F) **(T)**
- (i) (1 point) The equation  $(A^T)^{-1} = (A^T)(A^{-1})$  is true for every invertible  $3 \times 3$  matrix A. (T/F) **(F)**
- (j) (1 point) Every  $2 \times 2$  reflection matrix is orthogonal. (T/F) **(F)**

$$A^2 - AB + BA - B^2$$

2. (10 points) Let  $T$  be the linear transformation  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  with matrix

$$A = \begin{bmatrix} 3 & -\sqrt{3} \\ -\sqrt{3} & 5 \end{bmatrix}$$

(a) (2 points) Without doing any computations, we know  $A$  is diagonalizable. Why?

$A$  is symmetric and all symmetric matrices are (orthogonally) diagonalizable by the Spectral Theorem.

(b) (4 points) Find the eigenvalues of  $A$ . (You must show your steps to receive credit.)

$$\begin{aligned} f_A(\lambda) &= \det \begin{bmatrix} 3-\lambda & -\sqrt{3} \\ -\sqrt{3} & 5-\lambda \end{bmatrix} \\ &= (3-\lambda)(5-\lambda) - 3 \\ &= 15 - 3\lambda - 5\lambda + \lambda^2 - 3 \\ &= \lambda^2 - 8\lambda + 12 \\ &= (\lambda - 6)(\lambda - 2) \end{aligned}$$

$$\lambda = 6, 2$$

(c) (4 points) Find an eigenbasis of  $A$ . (You must show your steps to receive credit.)

$$\begin{aligned} E_6 &= \ker(A - 6I_2) \\ &= \ker \begin{bmatrix} -3 & -\sqrt{3} \\ -\sqrt{3} & -1 \end{bmatrix} \\ &= \text{span} \left( \begin{bmatrix} 1 \\ -\sqrt{3} \end{bmatrix} \right) \end{aligned}$$

$$\begin{aligned} E_2 &= \ker(A - 2I_2) \\ &= \ker \begin{bmatrix} 1 & -\sqrt{3} \\ -\sqrt{3} & 3 \end{bmatrix} \\ &= \text{span} \left( \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix} \right) \end{aligned}$$

$$\left( \begin{bmatrix} 1 \\ -\sqrt{3} \end{bmatrix}, \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix} \right)$$

3. (10 points) Consider the quadratic form:

$$q(x_1, x_2, x_3) = 6x_1x_2 + x_3^2$$

(a) (4 points) Write the (symmetric) matrix,  $A$ , of this quadratic form.

$$A = \begin{bmatrix} 0 & 3 & 0 \\ 3 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(b) (4 points) Find the eigenvalues of  $A$ . (You must show your steps to receive credit.)

$$\begin{aligned} f_A(\lambda) &= \det \begin{bmatrix} -\lambda & 3 & 0 \\ 3 & -\lambda & 0 \\ 0 & 0 & 1-\lambda \end{bmatrix} \\ &= (-\lambda)^2(1-\lambda) - 9(1-\lambda) \\ &= (1-\lambda)(\lambda^2 - 9) \\ &= (1-\lambda)(\lambda+3)(\lambda-3) \\ &\lambda = 1, \pm 3 \end{aligned}$$

(c) (2 points) Which of the following adjectives describe  $A$ ? Circle all that apply.

- Positive Definite
- Positive Semidefinite
- Indefinite
- Negative Semidefinite
- Negative Definite

4. (10 points) Find the curve of the form  $f(x) = c_0 + c_1x + c_2x^2$  that best fits the points  $(-2,-1)$ ,  $(0,-1)$ ,  $(1,1)$ , and  $(1,3)$ . (You must show your steps to receive credit.)

$$c_0 + c_1(-2) + c_2(4) = -1$$

$$c_0 + c_1(0) + c_2(0) = -1$$

$$c_0 + c_1(1) + c_2(1) = 1$$

$$c_0 + c_1(1) + c_2(1) = 3$$

$$\begin{bmatrix} 1 & -2 & 4 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 1 \\ 3 \end{bmatrix}$$

$A \quad \vec{x} \quad \vec{b}$

$$A^T A \vec{x} = A^T \vec{b}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ -2 & 0 & 1 & 1 \\ 4 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 & 4 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -2 & 0 & 1 & 1 \\ 4 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ -1 \\ 1 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 1+1+1+1 & -2+1+1 & 4+1+1 \\ -2+1+1 & 4+1+1 & -8+1+1 \\ 4+1+1 & -8+1+1 & 16+1+1 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -1-1+1+3 \\ 2+1+3 \\ -4+1+3 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 0 & 6 \\ 0 & 6 & -6 \\ 6 & -6 & 18 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 6 \\ 0 \end{bmatrix}$$

$$f(x) = -1 + 2x + x^2$$

$$\begin{bmatrix} 4 & 0 & 6 & | & 2 \\ 0 & 6 & -6 & | & 6 \\ 6 & -6 & 18 & | & 0 \end{bmatrix} \begin{array}{l} \frac{1}{2}R1 \\ \frac{1}{6}R2 \\ \frac{1}{3}R3 \end{array} \rightarrow \begin{bmatrix} 2 & 0 & 3 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 2 & -2 & 6 & | & 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 & 3 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 0 & -2 & 3 & | & -1 \end{bmatrix}$$

$R3 + 2R2$

$$\begin{bmatrix} 2 & 0 & 3 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 0 & 0 & 1 & | & 1 \end{bmatrix}$$

$R2 + R3$

$$\begin{bmatrix} 2 & 0 & 3 & | & 1 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \end{bmatrix}$$

$R1 - 3R3$

$$\begin{bmatrix} 2 & 0 & 0 & | & -2 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \end{bmatrix}$$

$\frac{1}{2}R1$

$$\begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \end{bmatrix}$$

$$\begin{bmatrix} c_0 \\ c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

5. (10 points) Find a Singular Value Decomposition for:

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

You must show your steps to receive credit.

$$A^T A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 4+1 & 2+2 \\ 2+2 & 1+4 \end{bmatrix} = \begin{bmatrix} 5 & 4 \\ 4 & 5 \end{bmatrix}$$

$$\begin{aligned} f_{A^T A}(\lambda) &= \det \begin{bmatrix} 5-\lambda & 4 \\ 4 & 5-\lambda \end{bmatrix} \\ &= (5-\lambda)^2 - 16 \\ &= 25 - 10\lambda + \lambda^2 - 16 \\ &= \lambda^2 - 10\lambda + 9 \\ &= (\lambda - 9)(\lambda - 1) \end{aligned}$$

$$\begin{aligned} E_9 &= \ker(A^T A - 9I_2) \\ &= \ker \begin{bmatrix} -4 & 4 \\ 4 & -4 \end{bmatrix} \end{aligned}$$

$$\vec{v}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \text{span} \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$$

$$\vec{v}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$E_1 = \ker(A^T A - I_2)$$

$$= \ker \begin{bmatrix} 4 & 4 \\ 4 & 4 \end{bmatrix}$$

$$= \text{span} \left( \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right)$$

$$V = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$V^T = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\lambda = 9, 1$$

$$\sigma_1^2 = 9 \quad \sigma_1 = 3$$

$$\sigma_2^2 = 1 \quad \sigma_2 = 1$$

$$\Sigma = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\vec{u}_1 = \frac{1}{\sigma_1} A \vec{v}_1$$

$$= \frac{1}{3} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \frac{1}{3\sqrt{2}} \begin{bmatrix} 2+1 \\ 1+2 \end{bmatrix} = \frac{1}{3\sqrt{2}} \begin{bmatrix} 3 \\ 3 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\vec{u}_2 = \frac{1}{\sigma_2} A \vec{v}_2 = \frac{1}{1} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$= \frac{1}{\sqrt{2}} \begin{bmatrix} 2-1 \\ 1-2 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$A = U \Sigma V^T$$

$$= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

6. (10 points) Find all solutions to the system:

$$\begin{aligned} \frac{1}{\sqrt{3}}x_1 + \frac{1}{\sqrt{3}}x_2 + \frac{1}{\sqrt{3}}x_3 &= \sqrt{3} \\ \frac{1}{\sqrt{6}}x_1 + \left(-\frac{2}{\sqrt{6}}\right)x_2 + \frac{1}{\sqrt{6}}x_3 &= \sqrt{6} \\ \frac{1}{\sqrt{2}}x_1 + 0x_2 + \left(-\frac{1}{\sqrt{2}}\right)x_3 &= \sqrt{2} \end{aligned}$$

You must show your steps to receive credit. If there are no solutions, write "No Solutions."

$$\begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{6}} & -\frac{2}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \sqrt{3} \\ \sqrt{6} \\ \sqrt{2} \end{bmatrix}$$

$A \qquad \vec{x} \qquad \vec{b}$

$$\left\| \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \right\| = \sqrt{\frac{1}{3} + \frac{1}{6} + \frac{1}{2}} = \sqrt{\frac{2+1+3}{6}} = 1$$

The length of each column of  $A$  is 1 and the dot product of any two different columns of  $A$  is 0.

So the columns of  $A$  form an orthonormal basis of  $\mathbb{R}^3$ .

So  $A$  is orthogonal.

So  $A^{-1} = A^T$ .

$$\text{So } \vec{x} = A^{-1}\vec{b} = A^T\vec{b} = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{2}{\sqrt{6}} & 0 \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \sqrt{3} \\ \sqrt{6} \\ \sqrt{2} \end{bmatrix}$$

$$= \begin{bmatrix} 1+1+1 \\ 1-2+0 \\ 1+1-1 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

$$x_1 = 3$$

$$x_2 = -1$$

$$x_3 = 1$$

7. (10 points) Let  $A$  be the matrix:

$$A = \begin{bmatrix} \frac{1}{4} & \frac{3}{4} \\ \frac{3}{4} & \frac{1}{4} \end{bmatrix}$$

Compute  $\lim_{t \rightarrow \infty} A^t$ . (You must show your steps to receive credit.)

$$\begin{aligned} E_1 &= \ker(A - I_2) \\ &= \ker \begin{bmatrix} -\frac{3}{4} & \frac{3}{4} \\ \frac{3}{4} & -\frac{3}{4} \end{bmatrix} & \vec{x}_{\text{equ}} &= \frac{1}{1+1} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ &= \text{span} \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) & &= \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \lim_{t \rightarrow \infty} A^t &= \begin{bmatrix} | & | \\ \vec{x}_{\text{equ}} & \vec{x}_{\text{equ}} \\ | & | \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \end{aligned}$$

8. (10 points) Let  $A$  be the matrix:

$$A = \begin{bmatrix} \cos\left(\frac{\pi}{7}\right) & -\sin\left(\frac{\pi}{7}\right) \\ \sin\left(\frac{\pi}{7}\right) & \cos\left(\frac{\pi}{7}\right) \end{bmatrix}$$

(a) (4 points) What is  $|\det(A)|$ ? (You must explain your reasoning to receive credit.)

$$\begin{aligned} \det A &= \cos^2\left(\frac{\pi}{7}\right) - \left(-\sin^2\left(\frac{\pi}{7}\right)\right) \\ &= \cos^2\left(\frac{\pi}{7}\right) + \sin^2\left(\frac{\pi}{7}\right) = 1 \end{aligned}$$

$$|\det A| = |1| = 1$$

(b) (2 points) Is  $A$  invertible? (You must explain your reasoning to receive credit.)

Yes, since  $\det(A) \neq 0$ .

(c) (4 points) Is  $A$  diagonalizable over  $\mathbb{R}$ ? (You must explain your reasoning to receive credit.)

No, because  $A$  is the matrix of rotation by  $\frac{\pi}{7}$ , which does not preserve the direction of any nonzero vector in  $\mathbb{R}^2$  (i.e.  $A\vec{v}$  is not parallel to  $\vec{v}$  for any nonzero  $\vec{v} \in \mathbb{R}^2$ )



9. (10 points) A  $3 \times 3$  matrix,  $A$ , has eigenvectors  $v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}$  and  $v_3 = \begin{bmatrix} 7 \\ 2 \\ 1 \end{bmatrix}$  all of which have eigenvalue  $-1$ .

Find  $A$ . Simplify to a single  $3 \times 3$  matrix. (You must show your steps to receive credit.)

$$\begin{aligned}
 A &= S B S^{-1} \\
 &= S (-I_3) S^{-1} \\
 &= -S I_3 S^{-1} \\
 &= -S S^{-1} \\
 &= -I_3
 \end{aligned}$$

$$\begin{aligned}
 B &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \\
 &= -I_3
 \end{aligned}$$

$$= \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

10. (10 points) Let  $\mathcal{B} = (\vec{v}_1, \vec{v}_2, \vec{v}_3)$  be basis of  $\mathbb{R}^3$  with:

$$\begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix}_{\mathcal{B}} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix}_{\mathcal{B}} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \text{ and } \begin{bmatrix} 4 \\ 3 \\ -1 \end{bmatrix}_{\mathcal{B}} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}.$$

Find  $\vec{v}_1, \vec{v}_2,$  and  $\vec{v}_3$ . (You must show your steps to receive credit.)

$$\begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix} = \vec{v}_1 - \vec{v}_3 \quad \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix} = \vec{v}_2 \quad \begin{bmatrix} 4 \\ 3 \\ -1 \end{bmatrix} = -\vec{v}_1 + 2\vec{v}_3$$

$$\begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix} + \begin{bmatrix} 4 \\ 3 \\ -1 \end{bmatrix} = \vec{v}_1 - \vec{v}_3 - \vec{v}_1 + 2\vec{v}_3$$

$$\begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix} = \vec{v}_3$$

$$\begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix} + \vec{v}_3 = \vec{v}_1$$

$$\begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix} + \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix} = \vec{v}_1$$

$$\begin{bmatrix} 2 \\ 3 \\ 7 \end{bmatrix} = \vec{v}_1$$