| STUDENT NAME: | | · | |
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| STUDENT ID NUMBER: | | | · · · · · · · · · · · · · · · · · · · |
| DISCUSSION SECTION NUMBER | 3F | ∞ ∞ | · · |

Directions

Answer each question in the space provided. Please write clearly and legibly. Show all of your work—your work must both justify and clearly identify your final answer. No books, notes or calculators are allowed. You must simplify results of function evaluations when it is possible to do so.

For instructor use only

| Page | Points | Score |
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| 2 | 8 | 8 |
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| Total: | 50 | 46 |

1. Consider the matrix

$$A = \begin{pmatrix} 1 & 5 & -3 \\ 2 & 0 & 4 \\ 2 & 2 & 2 \end{pmatrix}.$$

(a) [4 pts] Find a basis for ker(A), which is one-dimensional.

Solve
$$A\vec{x}=0$$
:
 $\begin{pmatrix} 1 & 5 & 3 & 0 \\ 2 & 0 & 4 & 0 & -2 & 0 \end{pmatrix}$ $\begin{pmatrix} 1 & 5 & -3 & 0 & -5 & 0 \\ 0 & -10 & 10 & 0 & 0 & 0 \end{pmatrix}$ $\begin{pmatrix} 1 & 5 & -3 & 0 & -5 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 \end{pmatrix}$ $\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -8 & 8 & 0 & 0 \end{pmatrix}$ $\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -8 & 8 & 0 & 0 \end{pmatrix}$ Let $r=x_3$. Then: $x_1+2r=0 \implies x_1=-2r$

$$x_2-r=0 \implies x_2=r$$

$$x_2-r=0 \implies x_2=r$$

$$x_1=\begin{pmatrix} -2r \\ r \end{pmatrix} = r\begin{pmatrix} -2r \\ 1 \end{pmatrix} \implies basis 15 \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

(b) [2 pts] Using your kernel computation, or otherwise, write down a linear relation between the columns of A that shows that the third column can be viewed as redundant. No further explanation necessary.

$$\begin{pmatrix} -\frac{3}{4} \\ \frac{1}{2} \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} - 1 \begin{pmatrix} 5 \\ 0 \\ 2 \end{pmatrix}, \quad \Rightarrow \quad \overrightarrow{\nabla}_3 = 2 \overrightarrow{\nabla}_2 - \overrightarrow{\nabla}_1$$

$$\text{if } A = \begin{pmatrix} 3 \\ 1 \\ 2 \\ 1 \end{pmatrix}, \quad \overrightarrow{\nabla}_2 = 3 \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}.$$

(c) [2 pts] Write down a basis for im(A). You may use any of the previous parts of the problem with no further explanation, even if you couldn't solve them. Or you may solve this problem from scratch using row reduction.

From part (b),
$$\begin{pmatrix} -\frac{3}{4} \end{pmatrix}$$
 is redundant, so:
bossis of in(A) is $\left\{ \begin{pmatrix} 1\\2\\2 \end{pmatrix}, \begin{pmatrix} 5\\2\\2 \end{pmatrix} \right\}$

(d) [8 pts] Convert your answer from the previous part of the problem into an orthonormal basis for im(A). (Keep your work well-organized!)

$$\vec{\mathcal{U}}_{1} = \frac{1}{||\vec{\mathcal{V}}_{1}||} = \frac{1}{\sqrt{1^{2}+2^{2}+2^{2}}} \left(\frac{1}{2}\right) = \left(\frac{1$$

(e) [4 pts] Use your work from the previous part of the problem to write a M = QR factorization for a relevant matrix M. (Part of the problem is deciding what M should be!)

M=
$$\begin{pmatrix} 1 & 5 \\ 2 & 0 \\ 2 & 2 \end{pmatrix}$$

Note that
$$\vec{V}_{1} = \begin{pmatrix} 1/3 \\ 2/3 \\ 2/3 \end{pmatrix}, \vec{V}_{2} = \begin{pmatrix} 2/35 \\ -1/35 \\ 2/3 \end{pmatrix}$$
from (d).
$$||\vec{V}_{1}|| = \sqrt{1^{2} + 2^{2} + 2^{2}} = 3$$

$$||\vec{V}_{2}|| = \sqrt{1^{2} + 2^{2} + 2^{2}} = 3$$

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$$||\vec{V}_{3}|| = \sqrt{$$

2. Suppose we have a linear transformation $T:\mathbb{R}^m\to\mathbb{R}^n$, and suppose further that we have a subspace V in the range \mathbb{R}^n . We will define a new subset of the domain \mathbb{R}^m called the pre-image of V as follows:

 $\operatorname{PreIm}(V) := \{ \overrightarrow{\mathbf{x}} \text{ in } \mathbb{R}^m \mid T(\overrightarrow{\mathbf{x}}) \text{ is in } V \}.$

That is, PreIm(V) consists of all vectors in \mathbb{R}^m that get mapped by T to a vector that is in V.

(a) [8 pts] Prove that PreIm(V) is a subspace of the domain \mathbb{R}^m by checking all three necessary conditions.

Condition 1: OFPRETURE (V)

Since Tis a linear transformation, then TO = 0, and DEV since Vis a subspace & DEPreIn(V).

Condition 2: V+We PreIn (V) if & E PreIn (V) (For any rectors) and we PreIm (1)

Since Tisalinear transformation, T(+++)=T(+)+T(+).

TEPreIn(V)

T(Z) EV

and ZePreIn(V)

implies

T(Z) EV.

Thus, T(=) + T(=) EV by definition of the subspace and T(2+2) eV \ it + it & Pre Im(V) V

Condition 3: If \(\text{CPreIm(V)}, \(\text{kt} \) \(\text{ePreIm(V)} \) for any Since T is a linear transformation, \(T(\text{kt}) = \text{kT(t)}. \)

JE PreIn (v) implies T(t) EV and by definition of the subspace, K-T(2) EV.

⇒ T(kt) ∈ V ⇒ kt ∈ PreIm (V).

(b) [2 pts] If we had chosen the subspace V to be all of the range \mathbb{R}^n , what subspace would $\operatorname{PreIm}(V)$ be? No explanation necessary.



(c) [2 pts] If we had chosen the subspace V to be the zero subspace $\{\overrightarrow{0}\}$ in the range \mathbb{R}^n , what subspace would $\operatorname{PreIm}(V)$ be? No explanation necessary.



- \mathcal{L} (d) [2 pts] Circle the one correct statement out of the four choices below (hint: think about $T: \operatorname{PreIm}(V) \to V$ rather than $T: \mathbb{R}^m \to \mathbb{R}^n$).
 - $\dim(\operatorname{PreIm}(V)) = \dim(V)$ regardless of V and/or T.
 - $\dim(\operatorname{PreIm}(V)) \ge \dim(V)$ regardless of V and/or T.
 - $\oint \dim(\operatorname{PreIm}(V)) \leq \dim(V) \text{ regardless of } V \text{ and/or } T.$
 - In some cases $\dim(\operatorname{PreIm}(V)) > \dim(V)$. In other cases $\dim(\operatorname{PreIm}(V)) < \dim(V)$. Finally, there are also cases where $\dim(\operatorname{PreIm}(V)) = \dim(V)$.

3. Let $\mathcal{B} = \{\overrightarrow{\mathbf{v}}_1, \overrightarrow{\mathbf{v}}_2\}$ be a basis for \mathbb{R}^2 , and let $T : \mathbb{R}^2 \to \mathbb{R}^2$ and $S : \mathbb{R}^2 \to \mathbb{R}^2$ be two linear transformations that treat this basis in the following manner:

$$T(\overrightarrow{\mathbf{v}}_1) = \overrightarrow{\mathbf{v}}_2, \quad T(\overrightarrow{\mathbf{v}}_2) = \overrightarrow{\mathbf{v}}_1, \qquad S(\overrightarrow{\mathbf{v}}_1) = \overrightarrow{\mathbf{v}}_1 - \overrightarrow{\mathbf{v}}_2, \quad S(\overrightarrow{\mathbf{v}}_2) = \overrightarrow{\mathbf{v}}_2$$

(a) [4 pts] Write down the matrix B for the composition $T \circ S$ in \mathcal{B} -coordinates.

$$B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$$

(b) [6 pts] Prove that, if we assume that S was an orthogonal transformation, then the basis vectors \overrightarrow{v}_1 and \overrightarrow{v}_2 cannot be orthogonal to each other.

Assume by contradiction that \overrightarrow{v}_1 Ly $_2$. Then:

S was an orthogonal transformation \longleftrightarrow

$$(\overrightarrow{V}_{1}-\overrightarrow{V}_{2})\cdot\overrightarrow{V}_{2}=0$$

Thus it isn't orthogonal to it, if Sis orthogonal.

- 4. Multiple choice and/or true and false (circle one answer only; no justification needed). In all of the problems below, A is an nxm matrix.
 - (a) [2 pts] What can we say about $\dim(\operatorname{im}(A)) + \dim(\ker(A))$?

Always = n

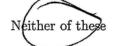


Neither of these

(b) [2 pts] What can we say about $\dim(\ker(A))$?

Always < n

Always > n



(c) [2 pts] If B is a pxn matrix, then we must have $rank(BA) \le rank(A)$.

TRUE

FALSE