

1. (10 points) (a) Solve the following system of linear equations:

$$\begin{cases} 2x - 2y + 22z = 40 \\ -x + 5y - 15z = -8 \\ -x + y - 7z = -12 \end{cases}$$

- (b) How many solutions does the system

$$\begin{cases} 2x - 2y + 22z = 0 \\ -x + 5y - 15z = 0 \\ -x + y - 7z = 0 \end{cases}$$

have?

- (c) For each of the following statements, circle T for True, F for False.

✓ T F The matrix

$$\begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

✓ T F is in reduced row echelon form.

If A^2 is an invertible matrix then so is A^3 .

✓ T F There exists a 2×2 matrix A such that $A^2 - A = I_2$.

✓ (I) F

There exists a 2×2 matrix A such that $A^2 - A = I_2$.

a) $\begin{bmatrix} 2 & -2 & 22 & | & 40 \\ -1 & 5 & -15 & | & -8 \\ -1 & 1 & -7 & | & -12 \end{bmatrix} \div 2 \xrightarrow{\substack{+\frac{1}{2}(I) \\ +\frac{1}{2}(I)}}} \begin{bmatrix} 1 & -1 & 11 & | & 20 \\ 0 & 4 & -4 & | & 12 \\ 0 & 0 & 4 & | & 8 \end{bmatrix} \xrightarrow{\substack{+\frac{1}{4}(II) \\ \div 4}}}$

$\begin{bmatrix} 1 & 0 & 10 & | & 23 \\ 0 & 1 & -1 & | & 3 \\ 0 & 0 & 1 & | & 2 \end{bmatrix} \xrightarrow{\substack{-10(III) \\ +(III)}}$

$\rightarrow \begin{bmatrix} 1 & 0 & 0 & | & 3 \\ 0 & 1 & 0 & | & 5 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}$

$\boxed{\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \\ 2 \end{bmatrix}}$

✓

b) ~~one~~

one

(since the rank of the 3×3 coeff matrix is just 3)

✓

$A^2 \quad (AA)^{-1} \quad A^3 \quad (AAA)^{-1}$
 $A^{-1}A^{-1} \quad A^{-1}A^{-1}A^{-1}$

$\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$
 $\begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix}$

$A(A-I) = I$

2. (10 points) Let $T, U: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the linear transformations satisfying

$$T \left(\begin{bmatrix} 2 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 2 \\ 1 \end{bmatrix},$$

$$T \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

and

$$U \left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix},$$

$$U \left(\begin{bmatrix} 1 \\ 3 \end{bmatrix} \right) = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

- Find the representing matrix A of T , and the representing matrix B of U .
- Compute the products AB and BA .
- Describe the transformation represented by $BA - AB$ geometrically.

a) Let $T = [\vec{v}_1 \ \vec{v}_2]$ with \vec{v}_1, \vec{v}_2 being column vectors

$$[\vec{v}_1 \ \vec{v}_2] \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$[\vec{v}_1 \ \vec{v}_2] \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$2\vec{v}_1 + \vec{v}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 + \vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 + (\vec{v}_1 + \vec{v}_2) = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} - \vec{v}_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} -4 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 + \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & -4 \\ 0 & 1 \end{bmatrix} \quad \checkmark$$

$$\vec{v}_1 + (\vec{v}_1 + \vec{v}_2) = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} - \vec{v}_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} -4 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 + \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & -4 \\ 0 & 1 \end{bmatrix} \checkmark$$

$U = [\vec{w}_1 \vec{w}_2]$ with \vec{w}_1, \vec{w}_2 column vectors

$$[\vec{w}_1 \vec{w}_2] \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$[\vec{w}_1 \vec{w}_2] \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$0 + \vec{w}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\vec{w}_1 + 3\vec{w}_2 = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\vec{w}_1 = \begin{bmatrix} -1 \\ 3 \end{bmatrix} - 3\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -4 \\ 0 \end{bmatrix}$$

MA

$$B = \begin{bmatrix} -4 & 1 \\ 0 & 1 \end{bmatrix}$$

~~$\vec{w}_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$~~
 ~~$\vec{w}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$~~

$$\begin{bmatrix} 8 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 12 \\ 8 \end{bmatrix}$$

$$b) AB = \begin{bmatrix} 3 & -4 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -4 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -12 + 0 & 3 + 4 \\ 0 + 0 & 0 + 1 \end{bmatrix} = \begin{bmatrix} -12 & 7 \\ 0 & 1 \end{bmatrix}$$

$$BA = \begin{bmatrix} -4 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & -4 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -12 + 0 & 16 + 1 \\ 0 + 0 & 0 + 1 \end{bmatrix} = \begin{bmatrix} -12 & 17 \\ 0 & 1 \end{bmatrix} = -1$$

c) $BA - AB = \begin{bmatrix} 0 & 16 \\ 0 & 0 \end{bmatrix}$ unit projection onto x axis, scaling by y component times 16 + rotation

3. (10 points) (a) Identify the redundant vectors in the following list:

$$\begin{matrix} \vec{v}_1 & \text{1st} & \text{2nd} & \vec{v}_2 & \text{3rd} \\ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} & \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} & \begin{bmatrix} -1 \\ -2 \\ -3 \end{bmatrix} & \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} & \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix} & \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{matrix}$$

$$\text{1st: } 0\vec{v}_1$$

$$\text{2nd: } -\vec{v}_1$$

$$\text{3rd: } 2\vec{v}_1 - 2\vec{v}_2$$

3/4
Others
not?

(b) For each of the following statements, circle T for True, F for False.

T F

Given two subspaces V and W of \mathbb{R}^n , the set of vectors

$$\vec{v} + \vec{w},$$

where $\vec{v} \in V$, $\vec{w} \in W$, is a subspace of \mathbb{R}^n .

~~T~~ F

There exists a 3×2 matrix whose image is \mathbb{R}^3 .

T F

If a subspace W of \mathbb{R}^2 contains neither $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ nor $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$, then W consists of the zero vector only.

T F

Given an $n \times n$ matrix A , the intersection

$$\ker(A) \cap \text{image}(A)$$

consists of the zero vector only.

T F

If an $n \times m$ matrix A has rank m then the column vectors of A are linearly independent.

T F

For every subspace V of \mathbb{R}^3 there exists a 3×3 matrix A such that $\text{image}(A) = V$.

??

$\begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix}$

4. (10 points) (a) Let L be a line in \mathbb{R}^2 spanned by a non-zero vector \vec{v} .

For each of the following transformations in the plane, determine the kernel and the image. If the transformation is invertible, also describe the inverse transformation geometrically.

1. proj_L followed by a scaling by a factor of 2;
2. proj_L followed by proj_{L^\perp} (recall that L^\perp is the orthogonal complement to L);
3. ref_L followed by a rotation through 180° ;
4. $A = \begin{bmatrix} 1 & 3 \\ 0 & 0 \end{bmatrix}$

(b) Let A be an $n \times n$ matrix and assume that $A^{2016} = 0$. Show that the matrix $I_n - A$ is invertible.

a) ① The kernel is the span of any vector \perp to \vec{v} ✓

The image is $\text{span}(\vec{v})$ ✓

② The kernel is any vector in \mathbb{R}^2 ✓

The image is the zero vector ✓

The image is the zero vector ✓

③ The kernel is the zero vector: $\{\vec{0}\}$ ✓

The image is any vector in \mathbb{R}^2 ✓

The inverse transformation is a 180° rotation followed by a refl ✓

④ $\begin{bmatrix} 1 & 3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ~~$\ker(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$~~

$x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$\ker(A) = \text{span} \begin{bmatrix} -3 \\ 1 \end{bmatrix}$ ✓

$x_1 + 3x_2 = 0$ $0x_1 + 0x_2 = 0$

$\text{im}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ ✓

$x_1 = -3x_2$ $x_2 = t, x_1 = -3t$

$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a^2+bc & ab+bd \\ ac+cd & bc+td \end{bmatrix}$

b) $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

If $A^{2016} = 0$ then $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ and $I - A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
which is invertible (generalize for $n \times n$)
 $\det(I - A) = 1$