

Midterm 1  
Linear Algebra and Applications  
(Math 33A-001)

Answer the questions in the space provided. If you run out of room for an answer, continue on the back of the page. Show your work.

Name: Christian Loanzon U ID: 005 109 250

TA's Name: Albert Zheng TA Meeting Day: Tues

Question:	1	2	3	4	Total
Points:	5	5	5	5	20
Score:	5	5	3	5	18

1. 5 points Let  $T$  be a linear transformation from  $\mathbb{R}^3$  to  $\mathbb{R}^3$  such that

$$T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \quad T \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ -6 \end{pmatrix} \quad \text{and} \quad T \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 4 \end{pmatrix}.$$

Compute the matrix of  $T$ .

$$T = \begin{pmatrix} \cdot & \cdot & \cdot \\ -1 & v_2 & v_3 \\ 0 & \cdot & \cdot \end{pmatrix} \quad T \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix} = - \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} v_2 \\ \cdot \\ \cdot \end{pmatrix} - \begin{pmatrix} v_3 \\ \cdot \\ \cdot \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ -6 \end{pmatrix}$$

$$= \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + v_2 - v_3$$

$$T \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} - v_2 + 2v_3 = \begin{pmatrix} -1 \\ 0 \\ 4 \end{pmatrix}$$

$$v_2 x_1 - v_3 x_1 - 1 = 3 \Rightarrow v_2 x_1 = v_3 x_1 + 4 \rightarrow v_3 x_1 = 4$$

$$2v_3 x_1 - v_2 x_1 - 1 = -1 \quad 2v_3 x_1 - v_3 x_1 - 4 - 1 = -1 \rightarrow v_2 x_1 = 8$$

$$v_2 x_2 - v_3 x_2 + 1 = 2 \rightarrow v_2 x_2 = v_3 x_2 + 1 \rightarrow v_3 x_2 = 0$$

$$2v_3 x_2 - v_2 x_2 + 1 = 0 \quad 2v_3 x_2 - v_3 x_2 + 1 = 0 \rightarrow v_2 x_2 = 1$$

$$v_2 x_3 - v_3 x_3 + 0 = -6 \rightarrow v_2 = v_3 - 6 \rightarrow v_3 x_3 = -2$$

$$2v_3 x_3 - v_2 x_3 = 4 \quad 2v_3 x_3 = v_3 x_3 + 6 = 4 \rightarrow v_2 x_3 = -8$$

$$T \begin{pmatrix} 1 & 8 & 4 \\ -1 & 1 & 0 \\ 0 & -8 & -2 \end{pmatrix} \vec{x}$$

$$\begin{bmatrix} 1 & 8 & 4 \\ -1 & 1 & 0 \\ 0 & -8 & -2 \end{bmatrix}$$

the matrix

← ANSWER

$$\begin{bmatrix} 1 & 8 & 4 \\ -1 & 1 & 0 \\ 0 & -8 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 8 & 4 \\ -1 & 1 & 0 \\ 0 & -8 & -2 \end{bmatrix}$$

2. 5 points Find a  $3 \times 3$  matrix  $A$  such that  $A\vec{x}$  is parallel to the vector  $\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$  for all  $\vec{x} \in \mathbb{R}^3$ .

Find proj matrix along  $\vec{w} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$

$$|\vec{w}| = \sqrt{1+1+1} = \sqrt{3}$$

$$\vec{u} = \left( \frac{\sqrt{3}}{3}, -\frac{\sqrt{3}}{3}, \frac{\sqrt{3}}{3} \right)$$

unit vec along line  $L$

$$\text{Proj}_L = (\vec{x} \cdot \vec{u}) \vec{u} = (x_1 u_1 + x_2 u_2 + x_3 u_3) \vec{u}$$

$$= \begin{pmatrix} x_1 u_1^2 + x_2 u_1 u_2 + x_3 u_1 u_3 \\ x_1 u_1 u_2 + x_2 u_2^2 + x_3 u_2 u_3 \\ x_1 u_1 u_3 + x_2 u_2 u_3 + x_3 u_3^2 \end{pmatrix}$$

$$A = \begin{bmatrix} \frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \\ -\frac{1}{3} & \frac{1}{3} & -\frac{1}{3} \\ \frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

← answer

$$A \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

3. 5 points Let  $A$  be a  $4 \times 4$  matrix,  $\vec{b}$  is a non-zero vector in  $\mathbb{R}^4$ , and  $\vec{0}$  is the zero vector in  $\mathbb{R}^4$ . We are told that the linear system  $A\vec{x} = \vec{0}$  has *infinitely* many solutions. What can you say about the number of solutions of the system  $A\vec{x} = \vec{b}$ ? You must explain your answer.

If  $A\vec{x} = \vec{0}$  has  $\infty$  solutions,  $\text{rank}(\text{rref}A) < 4$

so  $\text{rref}A$  looks smth like:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

or any variant of a  $4 \times 4$

$\text{rref}$  matrix w/ 3 pivots, w/ at least one row of all zeroes

Thus  $A\vec{x} = \vec{0} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & : & 0 \\ 0 & 1 & 0 & 0 & : & 0 \\ 0 & 0 & 1 & 1 & : & 0 \\ 0 & 0 & 0 & 0 & : & 0 \end{bmatrix}$  has infinite solutions.

answer  $\rightarrow$  However,  $A\vec{x} = \vec{b}$  has either no solutions or infinite solutions, dependent on if

~~the~~  $\vec{b}$  has a nonzero component in ~~the~~ a ~~same~~ row w/ no leading 1 (thus a row of all zeroes), as that creates an inconsistent row with  $0 = b_i$ , where  $b_i \neq 0$ .

In given example,  $\vec{b} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix}$  would have infinite solutions since  $b_4 = 0$ , so  $0 = 0$ , but  $\vec{b} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$  would have no solutions since the 4th row simplifies to  $0 = 1$ , inconsistent.

4. 5 points Let  $A$  be a  $m \times n$  matrix and  $B$  a  $n \times p$  matrix. If  $\ker(A) = \{\vec{0}\}$  and  $\ker(B) = \{\vec{0}\}$ , then prove that  $\ker AB = \{\vec{0}\}$ .

$$\text{Let } T(\vec{x}) = AB\vec{x}$$

$$\ker AB = \left\{ \vec{x} \mid AB\vec{x} = \vec{0} \right\}$$

$$\text{Let } AB\vec{x} = \vec{0} = A(B\vec{x}) \quad \text{and let } B\vec{x} = \vec{c}$$

$$\text{thus } A\vec{c} = \vec{0}$$

For  $A\vec{c} = \vec{0}$ ,  $\vec{c}$  must be an element of  $\ker A$ .

Thus for  $A\vec{c} = \vec{0}$ ,  $\vec{c} \in \{\vec{0}\}$  always, using  $\ker A = \{\vec{0}\}$

Thus since  $\vec{c} \in \{\vec{0}\}$ ,  $B\vec{x} \in \{\vec{0}\}$  always.

For  $B\vec{x} \in \{\vec{0}\}$ ,  $\vec{x} \in \ker B \rightarrow \vec{x} \in \{\vec{0}\}$

thus  $\vec{x} \in \{\vec{0}\}$  for  $AB\vec{x} = \vec{0}$

Thus  $\ker AB = \{\vec{0}\}$  since  $\vec{0}$  is the only vector that causes  $AB\vec{x}$  to equal  $\vec{0}$

since  $x \in \{\vec{0}\}$

for  $AB\vec{x} = \vec{0}$

10/10

Quiz 3  
Math 33A-001  
(Tuesday)  
(10 minutes)

Show your work to receive partial credits. Use of calculator is not allowed for this quiz.

Name: Christian Lorenzen U ID: 005 109 250

TA's Name: Albert TA Meeting Day: Tues

1. **10 points** Find a  $2 \times 2$  matrix  $A$  such that  $A \neq I_2$  but  $A^2 = I_2$ , where  $I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ .

(Hint: Think geometrically!)

Let  $T(\vec{x}) = A\vec{x}$  be a transformation.

Thus  $T(T(\vec{x})) = A(A\vec{x}) = A^2\vec{x}$ . For  $T(T(\vec{x})) = \cancel{A\vec{x}} \cdot \cancel{I_2}\vec{x} = \vec{x}$ ,

the transformation must 'reverse' itself.  $T$  can be a rotational transformation of  $\pi$  radian, thus  $T(T(\vec{x}))$  would rotate  $2\pi$  radians, essentially not modifying  $\vec{x}$ .

Thus if  $A = \begin{bmatrix} \cos \pi & -\sin \pi \\ \sin \pi & \cos \pi \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$

is a valid  $2 \times 2$  matrix to fulfill conditions.

Proof:  $A \cdot A = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} -1 \cdot -1 + 0 \cdot 0 & -1 \cdot 0 + 0 \cdot -1 \\ 0 \cdot -1 + -1 \cdot 0 & 0 \cdot 0 + -1 \cdot -1 \end{bmatrix}$   
 $= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$