

1. Consider the matrix 4×3 matrix A with linearly independent columns

$$\begin{matrix} & v_1 & v_2 & v_3 \\ \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \\ 1 & 1 & 1 \end{pmatrix} \end{matrix}$$

- (a) (5 points) Let \mathcal{A} be the basis of $\text{im}(A)$ consisting of the columns of A . Find the orthonormal basis \mathcal{B} obtained by applying Gram-Schmidt to \mathcal{A} .
- (b) (5 points) Use the previous part to write down the QR factorization of A , being careful to justify your work.

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2. (a) (6 points) Suppose that A is a 3×3 matrix given by

$$A = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix}$$

Let \mathcal{B} be the basis of \mathbb{R}^3 given by

$$\mathcal{B} = \{(1, 0, 1), (1, 0, 0), (0, 1, 0)\}.$$

Find the \mathcal{B} -matrix of A ; that is find the matrix B satisfying

$$[T(\vec{v})]_{\mathcal{B}} = B[\vec{v}]_{\mathcal{B}}$$

for all \vec{v} in \mathbb{R}^3 . Show all your steps.

- (b) (4 points) (Unrelated to part (a)). Suppose that A is an $m \times n$ matrix corresponding to a linear transformation that is injective, and suppose \vec{b} is a vector contained in $(\text{im}(A))^{\perp}$. Show that the least squares solution \vec{x}^* to the system $A\vec{x} = \vec{b}$ is $\vec{x}^* = \vec{0}$.

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3. (a) (5 points) Let A be the 100×100 matrix that has all -1 's below the diagonal, is 1 for every entry in the first row, and is 0 for all diagonal entries except for the first, depicted below.

$$A = \begin{pmatrix} 1 & -1 & 1 & 1 & \cdots & 1 & 1 \\ -1 & 0 & 0 & 0 & \cdots & 0 & 0 \\ -1 & -1 & 0 & 0 & \cdots & 0 & 0 \\ -1 & -1 & -1 & 0 & \cdots & 0 & 0 \\ \vdots & & & & & \vdots & \vdots \\ -1 & -1 & -1 & -1 & \cdots & 0 & 0 \\ -1 & -1 & -1 & -1 & \cdots & -1 & 0 \end{pmatrix}$$

Find the determinant of the matrix A , being sure to justify your work. (Hint: There is a trick that makes this much easier. Are there certain things we can do to a matrix that preserve determinants?)

- (b) (5 points) Let A be an $n \times n$ matrix such that $A^m = 0$ for some positive integer m . (Here the 0 denotes the zero matrix, i.e. the $n \times n$ matrix that has 0 in every entry, and the notation A^m means m copies of A multiplied together.) Prove that A is noninvertible.

4. Let A be the matrix

$$\begin{pmatrix} 0 & 2 & 1 \\ 1 & 4 & 1 \\ 1 & 2 & 0 \end{pmatrix}$$

- (a) (3 points) Find the eigenvalues of A .
- (b) (3 points) Find the corresponding eigenspaces of A . List the algebraic and geometric multiplicities of each eigenvalue.
- (c) (4 points) Explain why part b) tells you that A is diagonalizable. Diagonalize A by finding S, B so that $A = SBS^{-1}$ and B is diagonal.

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