1. Consider the following two systems

$$y_1(n) = \frac{1}{3} \sum_{k=n-2}^n x(k),$$

$$y_2(n) = \begin{cases} x \left(\frac{n}{4}\right) & n = 4k, k \text{ integer} \\ 0 & n \neq 4k, k \text{ integer}. \end{cases}$$

(a) Determine whether the systems are linear, time-invariant, relaxed, BIBO stable, and causal. Justify your answer to receive full credit.

 $\underline{Solution}$:

Properties	$y_1(n)$	$y_2(n)$
Relaxed	Yes	No
Linear	Yes	Yes
Time-Invariant	Yes	No
BIBO Stable	Yes	Yes
Causal	Yes	No

- System $y_1(n)$:
 - $y_1(n) = \frac{1}{3} \sum_{k=n-2}^n x(k) = \frac{1}{3} [x(n-2) + x(n-1) + x(n)]$ can be considered as a relaxed constant coefficient difference equation. It is relaxed, linear, time-invariant, BIBO stable, and causal.
- System $y_2(n)$:
 - Not relaxed: Counter example: if the first non-zero sample of x(n) is at n = -1, then $y_2(-4)$ will be non-zero, which is before -1.
 - · Linear: Let two outputs be

$$y_2^a(n) = \begin{cases} x_a\left(\frac{n}{4}\right) & n = 4k, k \text{ integer} \\ 0 & n \neq 4k, k \text{ integer.} \end{cases},$$

and

$$y_2^b(n) = \begin{cases} x_b\left(\frac{n}{4}\right) & n = 4k, k \text{ integer} \\ 0 & n \neq 4k, k \text{ integer}, \end{cases}$$

for an input $x_a(n)$ and $x_b(n)$, respectively. The output y(n) for an input $Ax_a(n) + Bx_b(n)$ with some constants A and B is given by i) if n = 4k, k integer,

$$y(n) = Ax_a\left(\frac{n}{4}\right) + Bx_b\left(\frac{n}{4}\right)$$
$$= Ay_2^a(n) + By_2^b(n).$$

ii) if $n \neq 4k$, k integer,

$$y(n) = 0.$$

Based on i) and ii), y(n) for an input $Ax_a(n) + Bx_b(n)$ is

$$y(n) = Ay_2^a(n) + By_2^b(n),$$

which implies that system $y_2(n)$ is linear.

• BIBO Stable: For a bounded sequence $|x(n)| \le M < \infty$ with a finite positive number M,

$$|y_2(n)| = \begin{cases} |x\left(\frac{n}{4}\right)| \le M < \infty & n = 4k, k \text{ integer} \\ 0 < \infty & n \ne 4k, k \text{ integer.} \end{cases},$$

implying that $|y_2(n)|$ is bounded output.

- Not Time-Invariant: Consider inputs $\delta(n)$ and $\delta(n-1)$. The outputs are $\delta(n)$ and $\delta(n-4)$. This shows that $y_2(n)$ is not time-invariant.
- Not causal: For example, $y_2(-4)$ depends on x(-1), i.e., the output depends on the future value of the input.
- (b) Given $x(n) = nu(n) + \delta(n^2)$, compute and plot $y_1(n)$ and $y_2(n)$ for $0 \le n \le 5$.

n	0	1	2	3	4	5
$y_1(n)$	1/3	2/3	4/3	6/3=2	9/3=3	12/3=4
$y_2(n)$	1	0	0	0	1	0

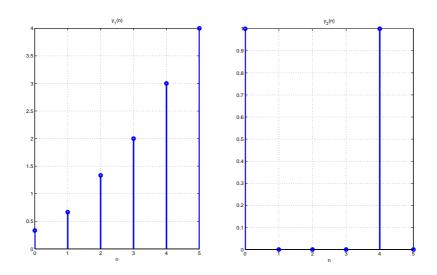


Figure 1: Plot for $y_1(n)$ and $y_2(n)$.

$\underline{Solution}$:

The corresponding plots are shown in Figure 1.

(c) Find the z-transform of $y_1(n)$ and $y_2(n)$ in terms of the z-transform of x(n).

Solution: z-transform for $y_1(n) = \frac{1}{3} \sum_{k=n-2}^n x(k) = \frac{1}{3} [x(n-2) + x(n-1) + x(n)]$ gives

$$Y_1(z) = \frac{1}{3} [z^{-2}X(z) + z^{-1}X(z) + X(z)]$$

= $\frac{z^{-2} + z^{-1} + 1}{3} X(z).$

z-transform for $y_2(n)$ is given by

$$Y_2(z) = \sum_{n=-\infty}^{\infty} y_2(n) z^{-n}$$
$$= \sum_{n=-\infty}^{\infty} x\left(\frac{n}{4}\right) z^{-n}$$
$$= \sum_{k=-\infty}^{\infty} x(k) z^{-4k}$$
$$= \sum_{k=-\infty}^{\infty} x(k) (z^4)^{-k}$$
$$= X(z^4).$$

It should also be correct if the students just use the property of the z-transform.

2. The difference equation of a relaxed system is:

$$y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n)$$

(a) Find a closed form for the impulse response h(n) (i.e., the zero state system output when the input is an impulse).

Solution:

By setting $x(n) = \delta(n)$, we have

$$h(n) - \frac{3}{4}h(n-1) + \frac{1}{8}h(n-2) = \delta(n) = \begin{cases} 1, & n = 0\\ 0, & n \neq 0 \end{cases}$$

Hence, for $n \ge 1$, h(n) can be found by solving homogeneous difference equation

$$h(n) - \frac{3}{4}h(n-1) + \frac{1}{8}h(n-2) = 0.$$
 (1)

The characteristic polynomial for (1) can be solved by

$$\left(\lambda - \frac{1}{2}\right)\left(\lambda - \frac{1}{4}\right) = 0,$$

thus, the modes are

$$\lambda_1 = \frac{1}{2}, \quad \lambda_2 = \frac{1}{4}.$$

Hence,

$$h(n) = C_1 \left(\frac{1}{2}\right)^n + C_2 \left(\frac{1}{4}\right)^n, \quad n \ge 0.$$

Since the system is relaxed, y(-1) = h(-1) = 0 and $h(0) = \delta(0) = 1$, which gives

$$C_1 = 2, \quad C_2 = -1.$$

Therefore,

$$h(n) = \left[2\left(\frac{1}{2}\right)^n - \left(\frac{1}{4}\right)^n\right]u(n).$$

(b) If the input to the system is x(n) = u(n-3), what is the output?

Solution:

The output y(n) of the system can be expressed as the convolution of x(n) and h(n), i.e.,

$$y(n) = x(n) * h(n)$$

= $u(n-3) * h(n)$.

Hence, using h(n) in part (a) gives us i) $n \leq 2, y(n) = 0$ ii) $n \geq 3$,

$$\begin{split} y(n) &= \sum_{k=-\infty}^{\infty} x(k)h(n-k) \\ &= \sum_{k=-\infty}^{\infty} u(k-3) \left[2\left(\frac{1}{2}\right)^{n-k} - \left(\frac{1}{4}\right)^{n-k} \right] u(n-k) \\ &= \sum_{k=3}^{n} \left[2\left(\frac{1}{2}\right)^{n-k} - \left(\frac{1}{4}\right)^{n-k} \right] \\ &= \sum_{k=0}^{n-3} \left[2\left(\frac{1}{2}\right)^{k} - \left(\frac{1}{4}\right)^{k} \right] \\ &= 2 \cdot \frac{1 - \left(\frac{1}{2}\right)^{n-2}}{1 - \frac{1}{2}} - \frac{1 - \left(\frac{1}{4}\right)^{n-2}}{1 - \frac{1}{4}} \\ &= \frac{8}{3} - 4\left(\frac{1}{2}\right)^{n-2} + \frac{4}{3}\left(\frac{1}{4}\right)^{n-2} \end{split}$$

(c) For what values of α is $g(n) = \alpha^n h(n)$ a finite energy sequence? Solution:

The energy E_g of g(n) is given by

$$E_g = \sum_{n=-\infty}^{\infty} |g(n)|^2$$

= $\sum_{n=-\infty}^{\infty} |\alpha^n h(n)|^2$
= $\sum_{n=0}^{\infty} \left| \alpha^n \left\{ 2\left(\frac{1}{2}\right)^n - \left(\frac{1}{4}\right)^n \right\} \right|^2$
= $\sum_{n=0}^{\infty} \left| 2\left(\frac{1}{2}\alpha\right)^n - \left(\frac{1}{4}\alpha\right)^n \right|^2$
= $\sum_{n=0}^{\infty} 4\left(\frac{1}{4}\alpha^2\right)^n + \sum_{n=0}^{\infty} \left(\frac{1}{16}\alpha^2\right)^n - \sum_{n=0}^{\infty} 4\left(\frac{1}{8}\alpha^2\right)^n$

To be a energy sequence, the energy must be finite, and hence,

•

$$\left|\frac{1}{4}\alpha^2\right| < 1, \quad \left|\frac{1}{16}\alpha^2\right| < 1, \text{ and } \left|\frac{1}{8}\alpha^2\right| < 1,$$

or equivalently,

$$|\alpha| < 2$$
, $|\alpha| < 4$, and $|\alpha| < \sqrt{8}$.

Hence, α should have a value in the range of $|\alpha|<2.$

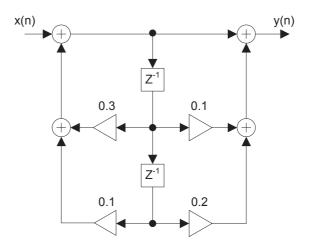


Figure 2: Block diagram.

- 3. A causal system is described by the above block diagram.
 - (a) Determine the constant coefficient difference equation that describes the system.
 <u>Solution</u>:

We denote the intermediate signal as w(n), shown in Fig. 3. The system in Fig. 3 is equivalent to the system in the block diagram shown in Fig. 4.

The system in Fig. 4 is a cascade of two sections. Interchanging the order of them gives us the block diagram shown in Fig. 5. In Fig. 5, the section on the left gives us

$$s(n) = x(n) + 0.1x(n-1) + 0.2x(n-2),$$

and the section on the right gives us

$$y(n) = s(n) + 0.3y(n-1) + 0.1y(n-2).$$

Combing the above two equations, we have

$$y(n) - 0.3y(n-1) - 0.1y(n-2) = x(n) + 0.1x(n-1) + 0.2x(n-2).$$

(b) Find the impulse response of the system.

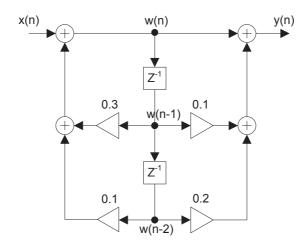


Figure 3: Block diagram with w(n).

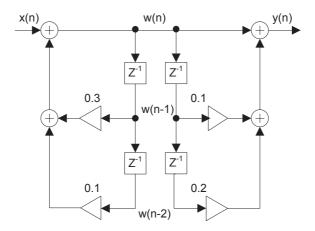


Figure 4: Equivalent block diagram.

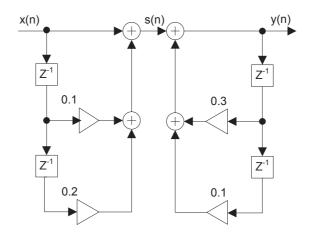


Figure 5: Equivalent block diagram with switched sections.

<u>Solution</u>:

The impulse response is the solution to the following equation:

$$h(n) - 0.3h(n-1) - 0.1h(n-2) = \delta(n) + 0.1\delta(n-1) + 0.2\delta(n-2)$$

When n > 2, the above difference equation is homogeneous, which has the following characteristic polynomial:

$$\lambda^2 - 0.3\lambda - 0.1 = 0.$$

Hence, the modes are

 $\lambda_1 = 0.5, \ \lambda_2 = -0.2.$

Thus, the solution is of the following form:

$$h(n) = C_1 \cdot (0.5)^n + C_2 \cdot (-0.2)^n$$

Note that the equation is homogeneous when n > 2. Since the system is causal, we have h(-2) = h(-1) = 0, $h(0) = \delta(0) = 1$, h(1) = 0.4, and h(2) = 0.42. According to the two initial conditions

$$h(1) = C_1 \cdot 0.5 + C_2 \cdot (-0.2)$$

and

$$h(2) = C_1 \cdot 0.25 + C_2 \cdot 0.04$$

we can solve for C_1 and C_2 :

$$C_1 = \frac{10}{7}, \quad C_2 = \frac{11}{7}.$$

Finally, the impulse response is

$$h(n) = \delta(n) + \left[\frac{10}{7} \cdot (0.5)^n + \frac{11}{7} \cdot (-0.2)^n\right] u(n-1).$$