

1B?

UCLA DEPARTMENT OF ELECTRICAL ENGINEERING

EE102: SYSTEMS & SIGNALS


Midterm Examination II

Date: March 6, 2018

Duration: 1 hr. 50 min.

INSTRUCTIONS:

- The exam has 6 problems and 15 pages.
- The exam is closed-book.
- Two cheat sheets of A4 size are allowed.
- Calculator is NOT allowed.
- Put your discussion session in the top-right corner ↗↗

Your name:  _____

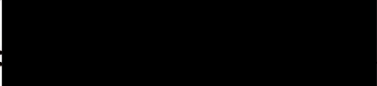
Student ID:  _____

Table 1: Score Table

Problem	a	b	c	d	Score
1	5	5	5		15
2	5	5	5		15
3	10	8			18
4	6	6			12
5	5	5	5		15
6	8	7			15
Total					90

9
12
16
~~12~~
10
8

67

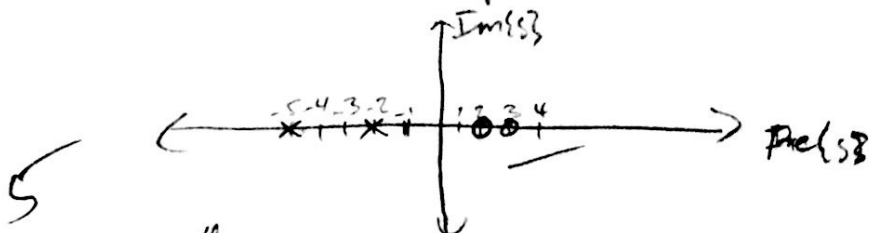
Problem 1 (15 pts)

Given the following transfer function of an LTI system

$$H(s) = \frac{s^2 - 5s + 6}{s^2 + 7s + 10}$$

- (a) (5 pts) Sketch pole-zero plot of $H(s)$. State whether the system is BIBO stable or not. Explain.
- (b) (5 pts) Compute the inverse Laplace transform to find a causal impulse response function $h(t)$.
- (c) (5 pts) Find the steady state output $y(t)$ when the input is $x(t) = 12 \cos(\sqrt{10} t)$.

a) zeros: $s=2, 3$ poles: $s=-2, -5$



yes, the system is BIBO stable b/c the $j\omega$ axis is included in the ROC ($\text{Re}\{s\} > -2$)

b)
$$H(s) = \frac{s^2 + 7s + 10}{s^2 + 7s + 10} + \frac{-7s - 10 - 5s + 6}{s^2 + 7s + 10} = 1 + \frac{-12s - 4}{s^2 + 7s + 10} = 1 - 4 \left(\frac{3s - 1}{s^2 + 7s + 10} \right)$$

$$\frac{3s - 1}{s^2 + 7s + 10} = \frac{A}{s + 5} + \frac{B}{s + 2}$$

$$A(s + 2) + B(s + 5) = 3s - 1$$

$$(A + B)s = 3s \Rightarrow A + B = 3$$

$$2A + 5B = -1$$

$$-2A - 2B = -6$$

$$3B = -7$$

$$B = -\frac{7}{3}$$

$$A = \frac{16}{3}$$

so
$$H(s) = 1 - 4 \left(\frac{\frac{16}{3}}{s + 5} + \frac{-\frac{7}{3}}{s + 2} \right)$$

$$h(t) = \delta(t) - \left(\frac{64}{3} e^{-5t} u(t) \right) + \left(\frac{28}{3} e^{-2t} u(t) \right)$$

c)
$$X(s) = 12 \left(\frac{s}{s^2 + 10} \right)$$

$$Y(s) = X(s)H(s) = 12 \left(\frac{s}{s^2 + 10} \right) \left(1 - \frac{64}{3} \frac{1}{s + 5} + \frac{28}{3} \frac{1}{s + 2} \right)$$

Problem 2 (15 pts)

The input-output relationship for an LTI system is given by the following differential equation

$$\frac{d^2y(t)}{dt^2} + 2\frac{dy(t)}{dt} + 5y(t) = \frac{dx(t)}{dt} + 5x(t), t \geq 0$$

with initial conditions $y'(0) = y(0) = 0, x(0) = 0$.

- (a) (5 pts) Find the transfer function $H(s)$.
- (b) (5 pts) Find the impulse response function $h(t)$.
- (c) (5 pts) Find the output $y(t)$ when the input is $x(t) = e^{-5(t-4)}u(t-4)$.

a) $s^2 Y(s) - sy(0) - y'(0) + 2(sY(s) - y(0)) + 5Y(s) = sX(s) + 5X(s)$

$(s^2 + 2s + 5)Y(s) = (s+5)X(s)$

$H(s) = \frac{Y(s)}{X(s)} = \frac{s+5}{s^2 + 2s + 5}$

b) $h(t) = \mathcal{L}^{-1}\{H(s)\}$

$H(s) = \frac{s+5}{s^2 + 2s + 5} = \frac{A}{s+1+2j} + \frac{B}{s+1-2j}$

$s = \frac{-2 \pm \sqrt{4-20}}{2} = -1 \pm 2j$

$h(t) = Ae^{-(1+2j)t}u(t) + Be^{-(1-2j)t}u(t)$

$A(s+1-2j) + B(s+1+2j) = s+5$

$(A+B)s = s \Rightarrow A+B=1$
 $A(1-2j) + B(1+2j) = 5 \Rightarrow B=1-A$

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$A(1-2j) + (1-A)(1+2j) = 5$
 $A - 2jA + 1 + 2j - A - 2jA = 5$
 $1 + 2j - 4jA = 5$
 $2j - 4jA = 4$

$A = \frac{4-2j}{-4j} = \frac{-2+j}{2j} = \frac{2j+1}{2}$
 $B = A^* = \frac{-2-j}{2}$

$h(t) = (j + \frac{1}{2})e^{-(1+2j)t}u(t) + (-j + \frac{1}{2})e^{-(1-2j)t}u(t)$

$$c) Y(s) = X(s) H(s) \quad e^{-st} u(t)$$

$$X(s) = e^{-4s} \frac{1}{s+5}$$

$$Y(s) = e^{-4s} \left(\frac{1}{s+5} \right) \left(\frac{s+5}{s^2+2s+5} \right) = e^{-4s} \left(\frac{1}{(s^2+2s+1)+4} \right)$$

$$Y(s) = \frac{1}{2} e^{-4s} \left(\frac{2}{(s+1)^2+2^2} \right)$$

$$\frac{2}{(s+1)^2+2^2} \xrightarrow{\mathcal{L}^{-1}} e^{-t} \sin(2t)$$

$$\boxed{y(t) = \frac{1}{2} e^{-(t-4)} \sin(2(t-4))} u(t-4)$$

5 &

$$e^{-\pi t} u(t) \rightarrow \frac{1}{s + \pi}$$

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Problem 3 (18 pts)

Consider an LTI system with impulse response function

$$h(t) = e^{-\pi(t-2)} u(t-2).$$

When a periodic signal $x(t)$ with period 2 is applied to this system, we get the following periodic output

$$y(t) = 1 + \cos(\pi t) + \sin(3\pi t).$$

(a) (10 pts) Find the exponential Fourier series coefficients of the input $x(t)$.

(b) (8 pts) Sketch magnitude and phase spectra of X_k .

Hint: Use the following while plotting phase spectrum: $\tan^{-1}(1) = \frac{\pi}{4}$, $\tan^{-1}(-1) = -\frac{\pi}{4}$, $\tan^{-1}(\frac{1}{3}) \approx \frac{\pi}{10}$, and $\tan^{-1}(-\frac{1}{3}) \approx -\frac{\pi}{10}$.

$$\Omega_0 = \pi$$

$$y(t) = 1 + \frac{1}{2}(e^{j\pi t} + e^{-j\pi t}) + \frac{1}{2j}(e^{j3\pi t} - e^{-j3\pi t})$$

$$y(t) = 1 + \frac{1}{2}e^{j\pi t} + \frac{1}{2}e^{-j\pi t} - \frac{j}{2}e^{j3\pi t} + \frac{j}{2}e^{-j3\pi t}$$

$$Y_0 = 1 \quad Y_1 = Y_{-1} = \frac{1}{2} \quad Y_3 = -\frac{j}{2} \quad Y_{-3} = \frac{j}{2}$$

$$H(s) = e^{-2s} \left(\frac{1}{s + \pi} \right)$$

$$H(jk\Omega_0) = e^{-2jk\pi} \left(\frac{1}{jk\pi + \pi} \right) = \frac{1}{\pi(1 + jk)} \leftarrow \text{never 0, so if } X_k \neq 0, Y_k \neq 0$$

$$Y_k = H(jk\Omega_0) X_k$$

$$Y_1 = H(j\pi) X_1 = \frac{1}{\pi(1+j)} X_1 = \frac{1}{2}$$

$$Y_{-1} = \frac{1}{\pi(1-j)} X_{-1} = \frac{1}{2}$$

$$Y_0 = \frac{1}{\pi} X_0 = 1$$

$$Y_3 = \frac{1}{\pi(1+3j)} X_3 = -\frac{j}{2}$$

$$Y_{-3} = \frac{1}{\pi(1-3j)} X_{-3} = \frac{j}{2}$$

$$X_1 = \frac{\pi(1+j)}{2}$$

$$X_{-1} = \frac{\pi(1-j)}{2}$$

$$X_0 = \pi$$

$$X_3 = \frac{j\pi(1+3j)}{2}$$

$$X_{-3} = \frac{j\pi(1-3j)}{2}$$

$$X_k = 0 \text{ otherwise}$$

$$b) |X_1| = \frac{\pi}{2} \sqrt{1^2 + 1^2} = \pi \frac{\sqrt{2}}{2}$$

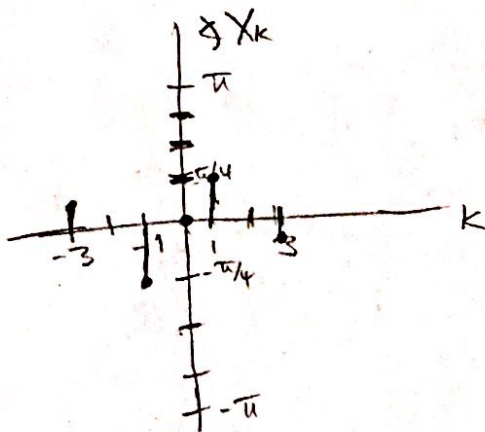
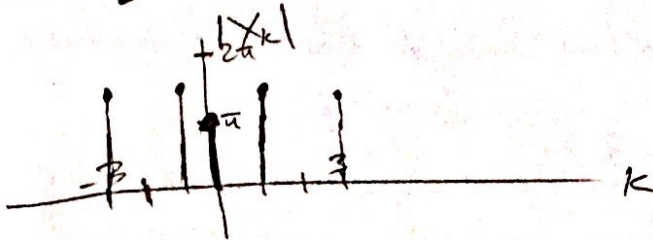
$$|X_{-1}| = \pi \frac{\sqrt{2}}{2}$$

$$|X_3| = \left| \frac{-j\pi + 3}{2} \right| = \frac{1}{2} \sqrt{\pi^2 + 3^2} \quad -2$$

$$|X_{-3}| = \frac{1}{2} \sqrt{\pi^2 + 3^2}$$

$$\frac{\sqrt{18}}{2}$$

$$\frac{3\sqrt{2}}{2}$$



$$\phi X_k = \tan^{-1} \left(\frac{\text{Im} \{ X_k \}}{\text{Re} \{ X_k \}} \right)$$

$$\phi X_0 = \tan^{-1}(0) = 0$$

$$\phi X_1 = \tan^{-1}(1) = \frac{\pi}{4} \quad \checkmark$$

$$\phi X_{-1} = \tan^{-1}(-1) = -\frac{\pi}{4} \quad \checkmark$$

$$\phi X_3 = \tan^{-1}\left(-\frac{1}{3}\right) \approx -\frac{\pi}{10} \quad \checkmark$$

$$\phi X_{-3} = \tan^{-1}\left(\frac{1}{3}\right) \approx \frac{\pi}{10} \quad \checkmark$$

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Problem 4 (12 pts) Consider the following periodic signal $x(t)$

$$x(t) = 2 \cos(\pi t/2) - \sin(\pi t/4)$$

$$T_0 = 8$$

$$\Omega_0 = \frac{2\pi}{T_0} = \frac{\pi}{4}$$

(a) (6 pts) Find the exponential Fourier series coefficients of $x(t)$.

(b) (6 pts) Find the exponential Fourier series coefficients of

a) $x(t) = e^{j\pi t/2} + e^{-j\pi t/2} - \frac{1}{2j} (e^{j\pi t/4} - e^{-j\pi t/4})$

$y(t) = \frac{dx(t)}{dt}$

$x(t) = e^{j\pi t/2} + e^{-j\pi t/2} + \frac{j}{2} e^{j\pi t/4} - \frac{j}{2} e^{-j\pi t/4}$

$X_1 = \frac{j}{2}$ $X_{-1} = -\frac{j}{2}$ $X_2 = 1$ $X_{-2} = 1$

$X_k = 0$ otherwise

b) $Y_k = jk \Omega_0 X_k$

So $Y_1 = \frac{j\pi}{4} \cdot \frac{j}{2} = -\frac{\pi}{8}$

$Y_{-1} = -\frac{j\pi}{4} \cdot -\frac{j}{2} = -\frac{\pi}{8}$

$Y_2 = \frac{j \cdot 2\pi}{4} \cdot 1 = \frac{j\pi}{2}$

$Y_{-2} = \frac{j(-2\pi)}{4} \cdot 1 = -\frac{j\pi}{2}$

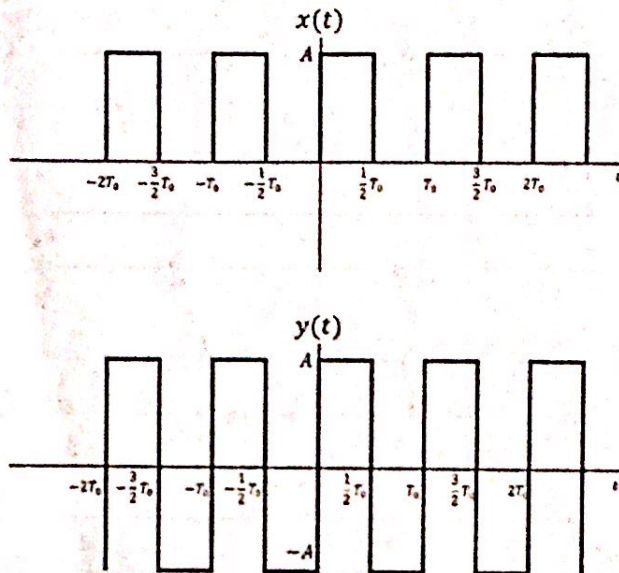
$Y_k = 0$ otherwise

$y(t) = \frac{d}{dt} \left(\sum_{k=-\infty}^{\infty} X_k e^{jk\omega_0 t} \right)$

$y(t) = \sum_{k=-\infty}^{\infty} X_k \frac{d}{dt} (e^{jk\omega_0 t})$

$y(t) = \sum_{k=-\infty}^{\infty} \underbrace{jk\omega_0 X_k}_{Y_k} e^{jk\omega_0 t}$

10 Problem 5 (15 pts) Consider the following periodic signals $x(t)$ and $y(t)$



4 (a) (5 pts) Determine the complex exponential Fourier series of $x(t)$, i.e., find the coefficients X_k that satisfy

$$x(t) = \sum_{k=-\infty}^{\infty} X_k e^{j\omega_0 kt}$$

4 (b) (5 pts) Determine the trigonometric Fourier series of $x(t)$, i.e., find the coefficients a_k and b_k that satisfy

$$x(t) = X_0 + 2 \sum_{k=1}^{\infty} a_k \cos(k\omega_0 t) - b_k \sin(k\omega_0 t)$$

2 (c) (5 pts) Using part (a), determine the complex exponential Fourier series of $y(t)$, i.e., find the coefficients Y_k that satisfy

$$y(t) = \sum_{k=-\infty}^{\infty} Y_k e^{j\omega_0 kt}$$

$$a) X_0 = \frac{A}{2}$$

$$X_k = \frac{1}{T_0} \int_0^{T_0} x(t) e^{-jk\omega_0 t} dt$$

$$X_k = \frac{1}{T_0} \int_0^{T_0/2} A e^{-jk\omega_0 t} dt$$

$$X_k = \frac{A}{T_0} \int_0^{T_0/2} e^{-jk\omega_0 t} dt$$

$$X_k = \frac{A}{T_0} \left(\frac{1}{-jk\omega_0} \right) e^{-jk\omega_0 t} \Big|_0^{T_0/2}$$

$$X_k = \frac{A}{2\pi k} \left(\frac{j}{k} \right) [-1 - 1]$$

$$X_k = \frac{-A}{\pi} \left(\frac{j}{k} \right) \text{ odd}$$

b)

$$a_k = \text{Re}\{X_k\} = 0$$

$$b_k = \text{Im}\{X_k\} = -\frac{A}{\pi k} \text{ odd}$$

$$x(t) = \frac{A}{2} + 2 \sum_{k=1}^{\infty} \frac{A}{\pi k} \sin(k\omega_0 t)$$

$$\omega_0 = \frac{2\pi}{T_0} \quad \therefore \frac{1}{T_0} \cdot \frac{1}{\omega_0} = \frac{1}{2\pi}$$

$$c) y(t) = x(t) + x(t - \frac{T_0}{2})$$

for $k \neq 0$

$$Y_k = X_k - X_k e^{-j\pi} = 2X_k$$

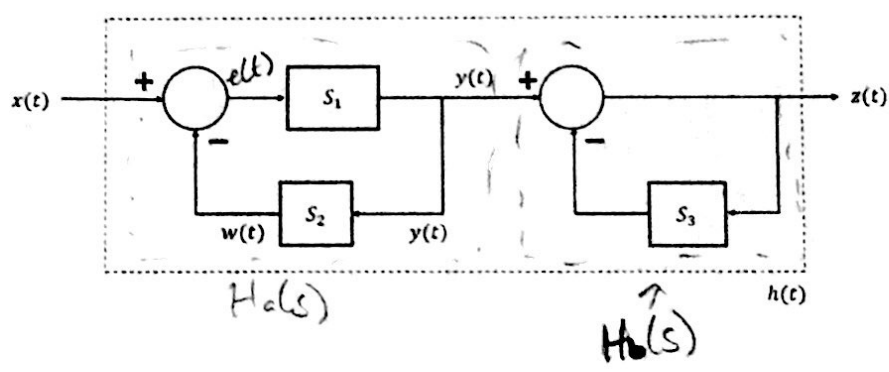
$$Y_0 = 0$$

Time-shifting: $x(t - \tau) \rightarrow e^{-j\omega_0 \tau} X_k$

8 **Problem 6** (15 pts) Consider the following LTI system with input $x(t)$, output $z(t)$, and impulse response function (IRF) $h(t)$. Systems S_1 , S_2 and S_3 are LTI systems as well with the following characteristics

1. IRF of S_1 is $h_1(t) = e^{-2t}u(t)$.
2. Input-output relation for S_2 is $w(t) = \frac{d}{dt}y(t)$
3. IRF of S_3 is $h_3(t) = e^{-t}u(t)$.

(Assume all the signals at $t = 0$ are zero, i.e., all initial conditions are zero).



- 5 (a) (8 pts) Compute the IRF of entire system $h(t)$ and its Laplace transform $H(s)$.
- 3 (b) (7 pts) Find the output $z(t)$ if the following input is applied to the system:

$$x(t) = e^{-2t} \cos(8t - 24)u(t - 3) \quad (1)$$

a) $z(t) = y(t) - h_3(t) * y(t)$ $Z(s) = Y(s) - H_3(s)Y(s)$

$H_0(s) = \frac{Z(s)}{Y(s)} = 1 - H_3(s) = 1 - \frac{1}{s+1} = \frac{s}{s+1}$

$e(t) = x(t) - w(t)$ $w(t) = \frac{d}{dt}y(t)$ $y(t) = e(t) * h_1(t)$

$W(s) = sY(s) - y(0)$

$H_1(s) = \frac{1}{s+2}$ $Y(s) = E(s)H_1(s)$

$H_0(s) = \frac{Y(s)}{X(s)} = H_1(s) - \frac{sY(s)H_1(s)}{X(s)}$ $Y(s) = (X(s) - sY(s))H_1(s)$

$(1 + sH_1(s))H_0(s) = H_1(s)$

$H_0(s) = \frac{H_1(s)}{1 + sH_1(s)} = \frac{\frac{1}{s+2}}{1 + \frac{s}{s+2}} = \frac{1}{s+2+s} = \frac{1}{2s+2}$

$$H(s) = H_a(s)H_b(s) = \frac{1}{2(s+1)} \left(\frac{s}{s+1} \right) = \frac{s}{2(s+1)^2}$$

$$h(t) = \mathcal{L}^{-1}\{H(s)\}$$

$$H(s) = \frac{1}{2} \left(\frac{s+1}{(s+1)^2} - \frac{1}{(s+1)^2} \right) = \frac{1}{2} \left(\frac{1}{s+1} - \frac{1}{(s+1)^2} \right)$$

$$h(t) = \left(\frac{1}{2} e^{-t} u(t) - \frac{1}{2} e^{-t} r(t) \right)$$

$$b) x(t) = e^{-2t} \cos(8(t-3)) u(t-3)$$

$$X(s) = e^{-3s} \frac{s+2}{s^2+4s+68}$$

$$Z(s) = X(s)H(s) = e^{-3s} \left(\frac{s+2}{s^2+4s+68} \right) \left(\frac{s}{2(s+1)^2} \right)$$

$$Z(s) = \frac{1}{2} e^{-3s} \left(\frac{s+2}{s^2+4s+68} \right) \left(\frac{1}{s+1} - \frac{1}{(s+1)^2} \right) = \frac{1}{2} e^{-3s} \left(\frac{1}{s^2+4s+68} + \frac{s+1}{s^2+4s+68} \right) \left(\frac{1}{s+1} - \frac{1}{(s+1)^2} \right)$$

$$Z(s) = \frac{1}{2} e^{-3s} \left(\frac{1}{s^2+4s+68} \left(\frac{1}{s+1} - \frac{1}{(s+1)^2} \right) + \frac{1}{s^2+4s+68} \left(1 - \frac{1}{s+1} \right) \right)$$

$$z(t) = h(t) * x(t)$$

$$z(t) = \frac{1}{2} \int_0^t (e^{-\tau} u(t-\tau) - e^{-\tau} r(t-\tau)) (e^{-2(t-\tau)} \cos(8(t-\tau-3)) u(t-\tau-3)) d\tau$$

$$z(t) = \frac{1}{2} \int_0^{t-3} (e^{-\tau} - \tau e^{-\tau}) (e^{-2(t-\tau)} \left(\frac{1}{2} (e^{8j(t-\tau-3)} + e^{-8j(t-\tau-3)}) \right)) d\tau$$

$$z(t) = \frac{1}{4} e^{-2t} \int_0^{t-3} (e^{\tau} - \tau e^{\tau}) (e^{8j(t-\tau-3)} + e^{-8j(t-\tau-3)}) d\tau$$

$$z(t) = \frac{1}{4} e^{-2t} u(t) \left(e^{8j(t-3)} \int_0^{t-3} e^{-\tau(1-8j)} - \tau e^{-\tau(1-8j)} d\tau + e^{-8j(t-3)} \int_0^{t-3} e^{-\tau(1+8j)} - \tau e^{-\tau(1+8j)} d\tau \right)$$