

# EC ENRG 101A Midterm Winter 2018

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Student ID#: \_\_\_\_\_

- A. Please put all the work on the test paper.
- B. Show your work! Provide clear explanations and show calculations. You may not get credit for work that is not shown.

**Name of person on LEFT**  
even if "far" way.  
If wall, then write "Wall".  
If aisle, then write "Aisle".

Alex Sehnas

**ROW NUMBER:**  
(as measured from front)

5<sup>th</sup>

**Name of person on RIGHT**  
even if "far" way.  
If wall, then write "Wall".  
If aisle, then write "Aisle".

Wall

BE SURE TO ENTER THE FOLLOWING INFORMATION

Allowed:  
pen/pencil  
calculator

*formula sheet: one side of a 8 1/2" by 11" sheet of paper.*

### Score

1	14 / 20		
2	5 / 15		
3	29 / 30		
4	24 / 25		
5	19 / 40		
Total	91 / 130		

Table 3-1: Summary of vector relations.

	Cartesian Coordinates	Cylindrical Coordinates	Spherical Coordinates
Differential length $dl =$	$\hat{x} dx + \hat{y} dy + \hat{z} dz$	$\hat{r} dr + \hat{\phi} r d\phi + \hat{z} dz$	$\hat{R} dR + \hat{\theta} R d\theta + \hat{\phi} R \sin \theta d\phi$
Differential surface areas	$ds_x = \hat{x} dy dz$ $ds_y = \hat{y} dx dz$ $ds_z = \hat{z} dx dy$	$ds_r = \hat{r} r d\phi dz$ $ds_\phi = \hat{\phi} dr dz$ $ds_z = \hat{z} r dr d\phi$	$ds_R = \hat{R} R^2 \sin \theta d\theta d\phi$ $ds_\theta = \hat{\theta} R \sin \theta dR d\phi$ $ds_\phi = \hat{\phi} R dR d\theta$
Differential volume $dV =$	$dx dy dz$	$r dr d\phi dz$	$R^2 \sin \theta dR d\theta d\phi$

## GRADIENT, DIVERGENCE, CURL, & LAPLACIAN OPERATORS CARTESIAN (RECTANGULAR) COORDINATES $(x, y, z)$

$$\nabla V = \hat{x} \frac{\partial V}{\partial x} + \hat{y} \frac{\partial V}{\partial y} + \hat{z} \frac{\partial V}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla \times \mathbf{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \hat{x} \left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \hat{y} \left( \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \hat{z} \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right)$$

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$$

## CYLINDRICAL COORDINATES $(r, \phi, z)$

$$\nabla V = \hat{r} \frac{\partial V}{\partial r} + \hat{\phi} \frac{1}{r} \frac{\partial V}{\partial \phi} + \hat{z} \frac{\partial V}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$$

$$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{r} & \hat{\phi} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_r & r A_\phi & A_z \end{vmatrix} = \hat{r} \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) + \hat{\phi} \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) + \hat{z} \frac{1}{r} \left[ \frac{\partial}{\partial r} (r A_\phi) - \frac{\partial A_r}{\partial \phi} \right]$$

$$\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2}$$

## SPHERICAL COORDINATES $(R, \theta, \phi)$

$$\nabla V = \hat{R} \frac{\partial V}{\partial R} + \hat{\theta} \frac{1}{R} \frac{\partial V}{\partial \theta} + \hat{\phi} \frac{1}{R \sin \theta} \frac{\partial V}{\partial \phi}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{R^2} \frac{\partial}{\partial R} (R^2 A_R) + \frac{1}{R \sin \theta} \frac{\partial}{\partial \theta} (A_\theta \sin \theta) + \frac{1}{R \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

$$\nabla \times \mathbf{A} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \hat{R} & \hat{\theta} & \hat{\phi} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_R & R A_\theta & (R \sin \theta) A_\phi \end{vmatrix}$$

$$= \hat{R} \frac{1}{R \sin \theta} \left[ \frac{\partial}{\partial \theta} (A_\phi \sin \theta) - \frac{\partial A_\theta}{\partial \phi} \right] + \hat{\theta} \frac{1}{R} \left[ \frac{1}{\sin \theta} \frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (R A_\phi) \right] + \hat{\phi} \frac{1}{R} \left[ \frac{\partial}{\partial R} (R A_\theta) - \frac{\partial A_R}{\partial \theta} \right]$$

$$\nabla^2 V = \frac{1}{R^2} \frac{\partial}{\partial R} \left( R^2 \frac{\partial V}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2}$$

**Problem 1: (20 points) – Slab of current** (hopefully familiar, it's from problem set #3!)

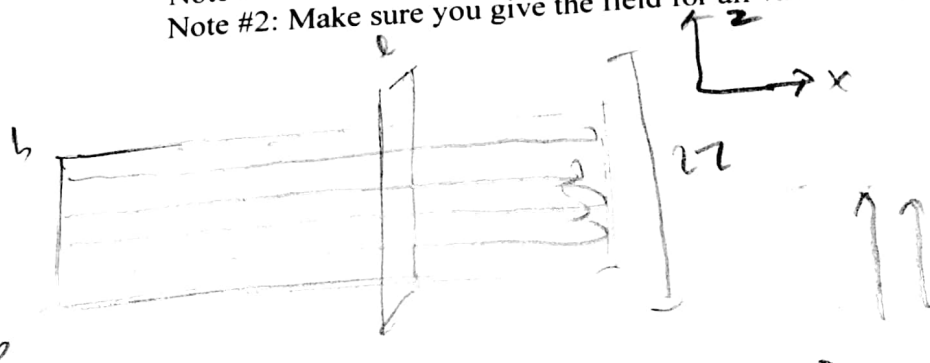
Find the B-field and H-field created by an infinite slab of current density extending in the x-y plane, whose density is given by

$$J(z) = \begin{cases} J_1 \hat{x}, & -b < z < b \\ 0, & |z| > b \end{cases}$$

Note #1:  $J_1$  is a constant bulk density with units A/m<sup>2</sup>.

Note #2: Make sure you give the field for all values of  $z$ , and don't forget the direction

$$P_0 = \frac{2 \mu J}{2 \pi}$$



$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu I_{enc}$$

$$I_{enc} = 2zJ_1$$

$$B(2z) = \mu 2zJ_1$$

$$B = \mu J_1 z$$

14

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu I_{enc}$$

$$B(2b) = \mu 2bJ_1$$

$$B = \mu bJ_1$$

add negative sign  
or abs. value

$$\mu J_1 b \hat{y} \quad z < -b$$

$$\mu J_1 z \hat{y} \quad -b < z < 0$$

$$\mu J_1 z \hat{y} \quad 0 < z < b$$

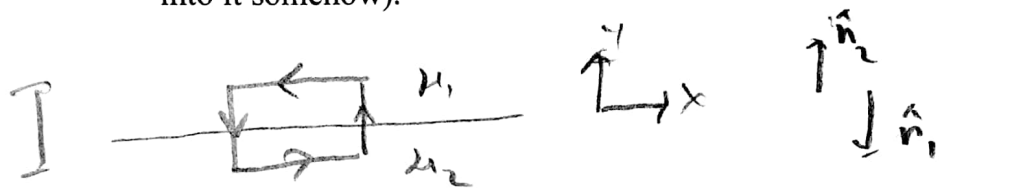
$$-\mu J_1 b \hat{y} \quad z > b$$

15?

**Problem 2: (15 points) Magnetic field boundary condition**

Derive the boundary condition for the normal components of the H-field across the boundary between medium 1 with  $\mu = \mu_1$  and medium 2 with  $\mu = \mu_2$ .

**NOTE:** Please make sure your derivation is as clear as possible. You probably have the answer on your cheat sheet, so I want to see on the paper that you obviously know where this boundary condition comes from (i.e., don't write down the answer and try to back into it somehow).



$$\oint \vec{B} \cdot d\vec{l} = I_{enc}$$

Only  $\gamma$  components matter for  $\vec{B}_n$

Take limit  $\Delta l \rightarrow 0 \Rightarrow I_{enc} = 0$

$$\Delta l (\vec{B}_{1n} \cdot \vec{n}_1 + B_{2n} \cdot \vec{n}_2) = 0$$

$$\vec{B}_{1n} \cdot \vec{n}_1 = -B_{2n} \cdot \vec{n}_2$$

$$\vec{B}_{1n} \cdot \vec{n}_1 = B_{2n} \cdot \vec{n}_2$$

$$B_{1n} = B_{2n}$$

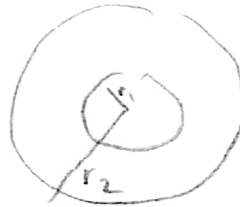
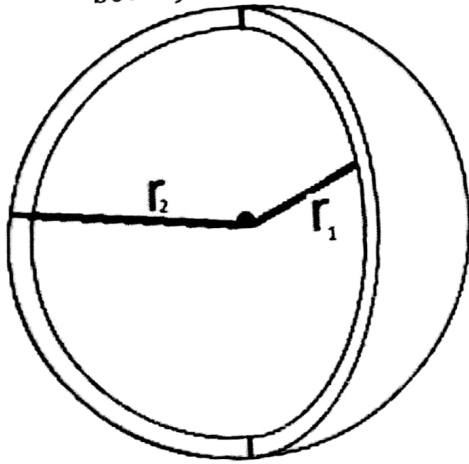


not in direction of  $d\vec{l}$

**Problem 3: (30 points) Shell of charge**

A suspended shell of charge in free space has inner radius  $r_1$  and outer radius  $r_2$ . The shell has a uniform charge density,  $\rho$ . You may assume there is empty space inside and outside the shell

- (1) Derive an expression for the electric field for all space (as a function of  $r$ ).
- (2) Sketch the electric field (as a function of  $r$ ).
- (3) What is the voltage between the points  $(3, 0, -4)$  and  $(0, 6, 8)$ ? You may assume both of these points fall in the space outside the outer edge of the shell.



1) Gauss's Law

$$0 < r < r_1$$

$$q_{enc} = 0$$

$$\oiint_S \vec{D} \cdot d\vec{s} = q_{enc}$$

$$\vec{E} = 0 \hat{r}$$

$$\oiint_S \vec{D} \cdot d\vec{s}$$

$$r_1 < r < r_2$$

$$\epsilon_0 E \cdot 4\pi r^2 = \frac{4}{3}\pi (r^3 - r_1^3) \rho$$

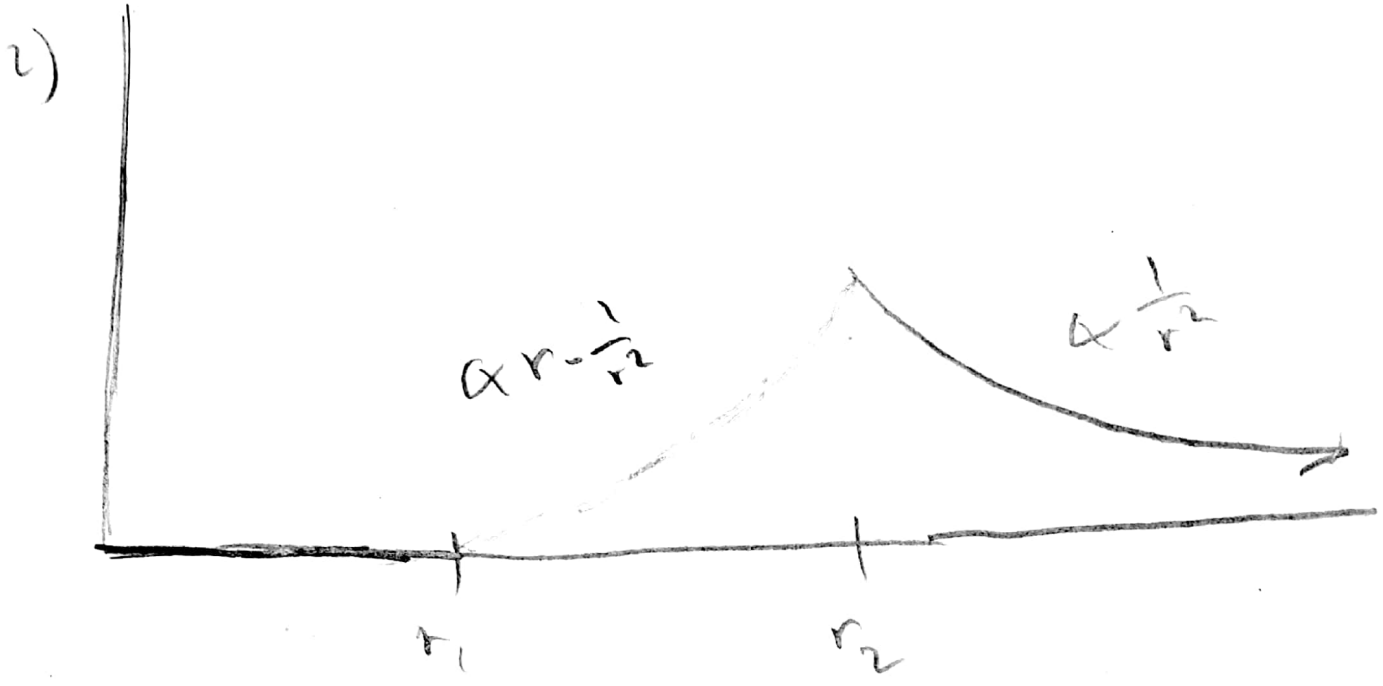
$$E = \frac{4\pi \rho (r^3 - r_1^3)}{4\pi \epsilon_0 r^2} = \frac{\rho (r^3 - r_1^3)}{3\epsilon_0 r^2} \hat{r}$$

$$r > r_2$$

$$\oiint_S \vec{D} \cdot d\vec{s} = q_{enc}$$

$$\epsilon_0 E \cdot 4\pi r^2 = \frac{4}{3}\pi (r_2^3 - r_1^3) \rho$$

$$E = \frac{(r_2^3 - r_1^3) \rho}{3\epsilon_0 r^2} \hat{r}$$



3) (3, 0, -4) (0, 6, 8)

Outside of sphere, E or V look like  $V = \frac{kq}{r}$   
 for point charge  $q = \frac{4}{3}\pi(r_2^3 - r_1^3)$

$$r_1 = \sqrt{3^2 + 4^2} = 5 \quad r_2 = \sqrt{6^2 + 8^2} = 10$$

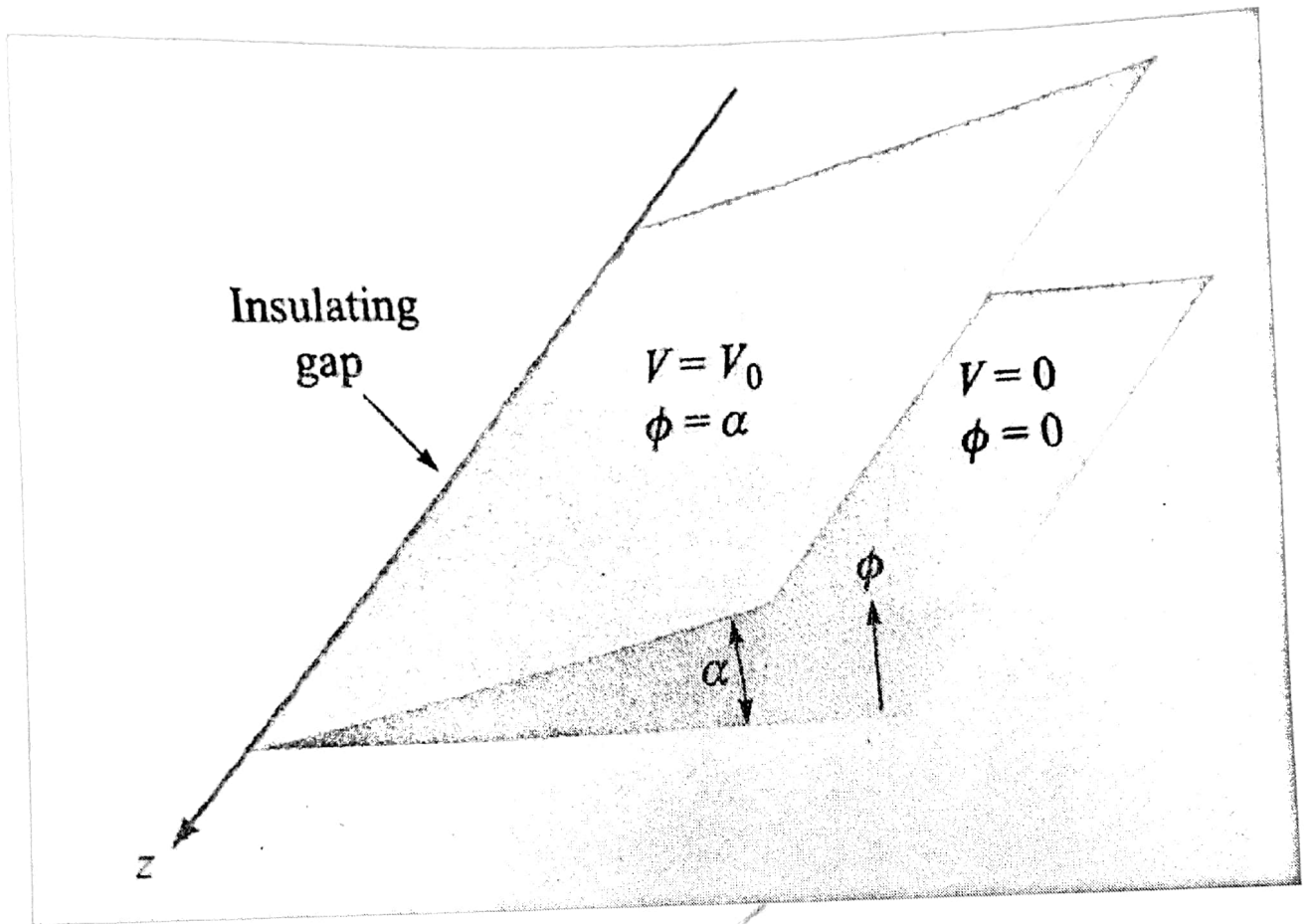
$$V = \frac{\frac{4}{3}\pi(r_2^3 - r_1^3)P}{4\pi\epsilon_0 r} = \frac{(r_2^3 - r_1^3)P}{3\epsilon_0 r}$$

$$V = \frac{(r_2^3 - r_1^3)P}{15\epsilon_0} - \frac{(r_2^3 - r_1^3)P}{30\epsilon_0} = \frac{(r_2^3 - r_1^3)P}{15\epsilon_0} \quad -1$$

30

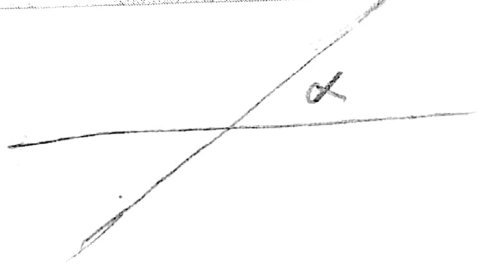
**Problem 4: (25 points)**

You have planes that extend into infinity in the radial and  $z$  directions as shown in the picture below. You know that the first plane, at angle  $\phi = 0$ , has potential  $V = 0$ , while the other plane at angle  $\phi = \alpha$  has potential  $V = V_0$ . Derive an expression for the E-field between the two planes.



$$E_{\text{plane}} = \pm \frac{\rho_s}{2\epsilon} \hat{n}$$

Cylindrical conductors



$$\nabla^2 V = 0$$

$$\frac{1}{r^2} \frac{d^2 V}{d\phi^2} = 0$$

$$\frac{d^2 V}{d\phi^2} = 0$$

$$\frac{dV}{d\phi} = C_1$$

$r, z$  independent of  $\phi$   $V$  independent of  $z$  and  $r$

$$V = C_1 \phi + C_2$$

$$C_2 = 0$$

$$C_1 = \frac{V_0}{\alpha}$$

$$V = \frac{V_0}{\alpha} \phi$$

$$E = -\nabla V$$

$$E = \hat{\phi} \frac{1}{r} \frac{dV}{d\phi}$$

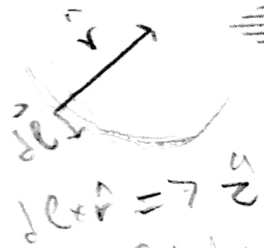
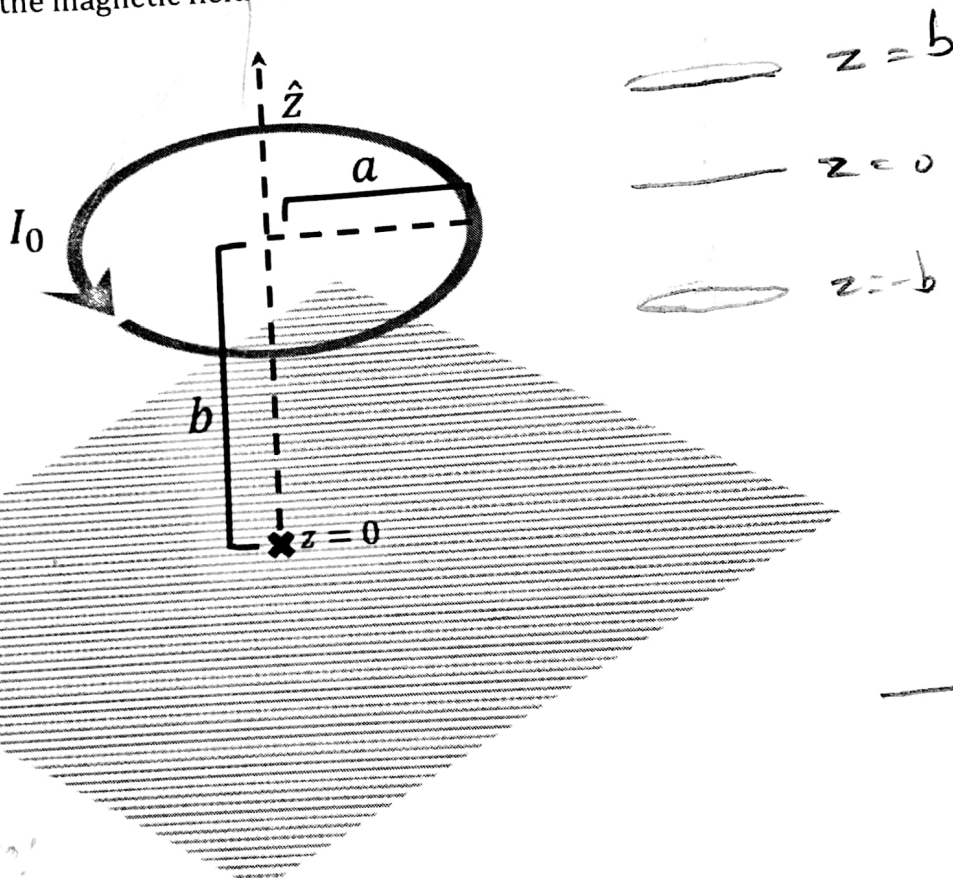
$$E = -\frac{V_0}{\alpha r} \hat{\phi}$$

- 2

**Problem 5 (40 points)**

A current loop with radius  $a$ , carrying current  $I_0$  (anti-clockwise), is placed at a height  $z = b$ .

- 1) Find the magnetic flux density  $\vec{B}$  caused by the current loop along the  $z$ -axis (through the center of the loop). For this part, you can assume this loop is in free space (i.e., with no conducting plane).
- 2) Now you can assume there is an infinite, perfectly conducting ground plane at  $z = 0$ . Where is the image current caused by the current loop in the ground plane? (Hint: to think about an image current, imagine an image charge that you move around.)
- 3) Which direction is the image current flowing (clockwise or anti-clockwise)?
- 4) What is the total magnetic flux density  $\vec{B}$  along the  $z$ -axis from the current loop and ground plane?
- 5) Where is the magnetic field zero?



$\oint \vec{C} \cdot d\vec{r} = \int \frac{q}{r^2}$   
 Cylindrical

$$A = \frac{\mu}{4\pi} \int \frac{I_0 d\vec{l} \times \hat{r}}{r^2}$$

$$A = \frac{\mu I_0}{4\pi} \int_0^{2\pi} \frac{a d\theta}{\sqrt{a^2 + (z-b)^2}} \hat{\theta}$$

$$A = \frac{\mu (2\pi a) I_0}{4\pi \sqrt{a^2 + (z-b)^2}} \hat{\theta}$$

$$\vec{A} = \frac{\mu I_0}{2\sqrt{a^2 + (z-b)^2}} \hat{\theta}$$

$$r^2 = \sqrt{a^2 + (z-b)^2}$$

$$\vec{B} = \nabla \times \vec{A} \quad X-15$$

to do this with vector potential, you must find  $\vec{A}$  everywhere, not just along  $z$ -axis!



$\vec{A}$  independent of  $\theta$  and  $R$  and only has  $\hat{\phi}$  component

$$\vec{B} = \nabla \times \vec{A} = -\frac{\partial A_{\phi}}{\partial z} \hat{r} + \frac{1}{r} \frac{\partial}{\partial r} (r A_{\phi}) \hat{z}$$

$$\vec{B} = -\frac{\mu I_0}{2} \cdot \left( -\frac{1}{z} \right) \frac{2(z-b)}{(a^2+(z-b)^2)^{3/2}} \hat{r} + \frac{\mu I_0}{2\sqrt{a^2+(z-b)^2}} \hat{z}$$

$$\frac{d}{dz} = \frac{d}{dz} \cdot \frac{1}{z}$$

$$\vec{B} = \frac{\mu I_0 (z-b)}{2(a^2+(z-b)^2)^{3/2}} \hat{r} + \frac{\mu I_0}{2\sqrt{a^2+(z-b)^2}} \hat{z}$$

$$\vec{H} = \frac{\vec{B}}{\mu}$$

2) There is an image current loop at  $z = -b$  with radius  $a$  ✓

3) The image current is flowing in the same orientation as the original loop, anti-clockwise. X-3

4) Replace  $z-b$  in original eqn for  $\vec{B}$  with  $z+b$  since the only thing that changed was  $z$ -intercept

$$\vec{B} = \frac{\mu I_0 (z+b)}{2(a^2+(z+b)^2)^{3/2}} \hat{r} + \frac{\mu I_0}{2\sqrt{a^2+(z+b)^2}} \hat{z}$$

Use superposition to solve problem

$\hat{r}$  and  $\hat{z}$  components are 0 when  $\vec{B} = 0$

$$\frac{\mu_0 I (z+b)}{2(a^2+(z+b)^2)^{3/2}} + \frac{\mu_0 I_0 (z-b)}{2(a^2+(z-b)^2)^{3/2}} = 0 \quad \text{for } \hat{r}$$

$$\frac{\mu I_0}{2\sqrt{a^2+(z-b)^2}} + \frac{\mu I_0}{2\sqrt{a^2+(z+b)^2}} = 0 \quad \text{for } \hat{z} \quad \checkmark -3$$

$$\Rightarrow \sqrt{a^2+(z-b)^2} = -\sqrt{a^2+(z+b)^2}$$

There is no point where the magnetic field is zero along the z-axis.  $\checkmark$