

For each pair (f,g) below indicate the relation between them in terms of  $O, \Omega, \Theta$ . For each missing entry, write-down Y (for YES) or N (for NO) to indicate whether the relation holds (no need to justify your answers here). For example, if f = O(g) but not  $\Omega(g)$ , then you should enter Y in the first box and N in the other two boxes. Similarly, if  $f = \Theta(g)$ , then you should enter Y in all the boxes. [5 points].

f	<i>g</i>	0	Ω	Θ
$\log_2 n$	$\log_{10} n$	Y	Y	Y
$2^{(\log_2 n)^4}$	$n^5$	X	N/	N
$n^3 \cdot 2^n$	$3^n$	A	X	N
$2^{\sqrt{\log_2\log_2 n}}$	$\log_2 n$	Y	X	Ń
n!	$n^n$	$\gamma$	n	r

Answer true or false for the following (no need for explanations) [10 points]:

• Consider an instance of the stable matching where a doctor  $D_1$ 's first choice is  $H_1$  and  $H_1$ 's first choice is  $D_1$ . Is it true that in every stable matching  $D_1$  should be matched to  $H_1$ ?

• Consider an instance of the stable matching problem and a candidate perfect matching M where one doctor gets her top choice and one hospital gets its top choice, while every other doctor and hospital get their second choice. Is M necessarily a stable matching?

• If  $\alpha$  is an *n*'th root of unity, then  $\sum_{j=0}^{2n-1} \alpha^j = 2n$ .

21.1 h

X

- False
- Dijkstra's algorithm when run on an unweighted undirected graph starting from a vertex s gives us (by looking at the graph formed by *Parent* links) the breadth-first-search tree starting from s.
- Any polynomial  $P : \mathbb{R} \to \mathbb{R}$  of degree d is uniquely determined by its evaluations at d distinct points  $x_1, \ldots, x_d$ .

False

True

Given a connected undirected graph G = (V, E) as input (in adjacency list representation), give an algorithm to check if G is a tree. You must analyze the time-complexity of your algorithm but don't need to prove correctness. For full credit, your algorithm should be correct and run in time O(|V| + |E|). [15 points]

15

For shaple connected  
graph G, 
$$|V| = |E| + |$$
 iff G is a free  
"Given Itst A, with  $A[i] = i^{th}$  vertice's adjurancy list  
"(Court vertices = A. count()  
"NumEdges = A. count()  
"Court edges  
for  $i = 0$ ;  $i \le numVertices$ ;  $i + t \in$   
numEdges  $+ = A[i].count()$   
3  
numEdges = numEdges  $/2$ ; "takes OCO to right shift  
return numVertices == numEdges  $+ |$   
It list.count() takes constant time (list size stored as  
property of list), then T(n) = O(|V|) from the for loop at(2)  
iterating |V| times and all other operations taking OCD.  
IF test.count() takes OCI is  $+$  count all edges where  
a single list.count() takes OCI list),  $\Rightarrow T(n) = O(|V| + |E|)$ 

Given the coefficients of a polynomial P of degree d and an integer k as input, give an algorithm to compute the coefficients of the polynomial  $P(x)^k$ . For example, if your input is (1, 1) (to denote the polynomial 1 + x) and k = 3, your output should be (1, 3, 3, 1) to denote the polynomial  $(1 + x)^3 = 1 + 3x + 3x^2 + x^3$ . Similarly, if the input is (1, -3) (to denote P = 1 - 3x), k = 3, your output should be (1, -9, 27, -27).

To get full credit, your algorithm should be correct, run in time  $O((k \cdot d) \log(k \cdot d))$  and you must analyze the time-complexity of your algorithm (no need to prove correctness). [25 points]

**Remark:** Here we measure time-complexity as in the fast-polynomial multiplication algorithm, where we count complex additions and multiplications as unit-cost.



() (2)



Let G = (V, E) be a directed graph with nodes  $v_1, \ldots, v_n$ . We say that G is an ordered graph if it has the following properties.

- 1. Each edge goes from a node with a lower index to a node with a higher index. That is, every directed edge has the form  $(v_i, v_j)$  with i < j.
- 2. Each node except  $v_n$  has at least one edge leaving it. That is, for every node  $v_i$ , i = 1, 2, ..., n-1, there is at least one edge of the form  $(v_i, v_j)$ .

Given an ordered graph G = (V, E) (in adjacency list representation), give an algorithm to compute the number of paths that begin at  $v_1$  and end at  $v_n$ .

You must analyze the time-complexity of your algorithm (no need to prove correctness). To get full-credit your algorithm must be correct and run in time O(|V| + |E|). [25 points]

*Remark:* You can assume that adding two numbers takes constant time in your time-complexity calculations.

10

Decide whether the following statement is true or false. If it is true, give a short explanation (no need for a formal proof - a high-level description is enough). If it is false, give a counter-example.

Suppose we are given an instance of the Minimum Spanning Tree Problem on a graph G, with edge costs that are all positive and distinct. Let T be a minimum spanning tree for this instance. Now suppose we replace each edge cost  $c_e$  by its square,  $c_e^2$ , thereby creating a new instance of the problem with the same graph but different costs.

True or false? T must still be a minimum spanning tree for this new instance. [10 points]

It weight  $(T) = \min \text{ ord } w(T) = \sum_{e \in T} C_e$ then when you replace ce with ce for tree T'  $w(T') = \sum_{r=1}^{\infty} (r - \sum_{r=1}^{\infty} c_r^2)$ = \N/I berause 2 = decting recently for x70 to if a cb, 2 cb? Va, b70

Given an undirected graph G = (V, E), a subset of vertices  $I \subseteq V$  is an independent set in G if no two vertices in I are adjacent to each other. Let  $\alpha(G) = \max\{|I| : I \text{ an independent set in } G\}$ . The goal of the following questions is to give an efficient algorithm for computing an independent set of maximum size in a tree. Recall that a *leaf* in a graph is a vertex of degree at most 1 and that every acyclic graph (graph without any cycles) has at least one leaf.

Let T = (V, E) be an acyclic graph on n vertices.

- 1. Prove that if u is a leaf in T, then there is a maximum-size independent set in T which contains u. That is, for every leaf u, there is an independent set I such that  $u \in I$  and  $|I| = \alpha(T)$ . [15 points]
- 2. Give the graph T as input (in adjacency edge representation), give an algorithm to compute an independent-set of maximum size,  $\alpha(T)$ , in T. To get full credit your algorithm should run in time  $O(|V| \cdot |E|)$  (or better) and you must prove correctness of your algorithm. You don't need to analyze the time-complexity of your algorithm and it is sufficient to solve this problem assuming part (1) (if you want) even if you don't solve it. [15 points]

Assume 
$$\exists$$
 non-size independent and  $I'$  in  $T$ . (Here durys evides  
If  $u \in I'$ , then  $Civ$  and  $I'$  in  $T$ . (Here durys evides  
If  $u \notin I'$ , then  $Civ$  and  $=$   $I'$ .  
If  $u \notin I'$ , then  $Civ$  and  $=$   $I'$ .  
If  $u \notin I'$ , then  $wc$  for replace  $V$  (such that  $V \in I'$   
and  $\exists$  edge  $(u, v)$ ) with  $u$  to make  $I$ .  
We can do this because  $u$  is only connected to  $V$   
because it is a track to replacing  $u$  with  $v$  doesn't odd  
or  $v$  eriges to  $I$  to make  $T$ .