CS M146 Midterm

MARK GUEVARA

TOTAL POINTS

80 / 100

QUESTION 1

- **1** True/false **15 / 18**
	- **0 pts** Correct
	- **✓ 3 pts (a) incorrect (e.g., saying p(x) is probability)**
		- **3 pts** (b) incorrect
		- **3 pts** (c) incorrect
		- **3 pts** (d) incorrect
		- **3 pts** (e) incorrect
		- **3 pts** (f) incorrect

 - 2 pts (a) partial points for showing how to use integral to get probability from p(x) and arguing 0 \leq integral p(x) \leq 1 (but we are asking p(x), not integral $p(x)$)

QUESTION 2

Short Question 23 pts

2.1 (a)-(d) **13 / 13**

✓ - 0 pts Correct

- **4 pts** (a) incorrect
- **3 pts** (b) incorrect
- **3 pts** (c) incorrect
- **3 pts** (d) incorrect
- **2 pts** (a) partially correct
- **1.5 pts** (b) partially correct
- **1.5 pts** (c) partially correct
- **1.5 pts** (d) partially correct
- **0 pts** (b) should specify tuning "hyper-parameter"

2.2 (e) **5 / 10**

 - 0 pts Correct

 - 1 pts Answer correct but missed one/two steps while proving

 - 2 pts Some minor mistakes/missed a important step

✓ - 5 pts Major mistakes, but mentioned some

important points like solving a linear system Xw. E.g., trying to solve Xw = 0 instead of Xw = y or mention X is invertible

 - 8 pts only mentioned definition of linear

independence

 - 10 pts incorrect

QUESTION 3

Decision tree 15 pts

3.1 (a) i, ii **7 / 7**

- **✓ 0 pts Correct**
	- **2 pts** a) i. incorrect
	- **0.5 pts** a) i. partially incorrect
	- **5 pts** a) ii. incorrect
	- **2.5 pts** a) ii. partially incorrect

3.2 (a) iii **3 / 3**

- **✓ 0 pts Correct**
	- **1.5 pts** a) iii. Partially incorrect
	- **3 pts** a) iii) incorrect

3.3 (b) **5 / 5**

- **✓ 0 pts Correct**
	- **2.5 pts** partially incorrect
	- **5 pts** incorrect

QUESTION 4

Perceptron 23 pts

4.1 (a) (answer 2,4,5,6; 4,5,6; 2,4,6; 4,6; are

all okay) **2 / 4**

- **4 pts** Totally wrong
- **✓ 2 pts Partially Correct**
	- **0 pts** Correct

4.2 (b) **4 / 8**

✓ - 4 pts did mention yx or mention learning rate, but got totally wrong with the constraint of the learning rate

 - 0 pts correct

 - 2 pts made tiny mistakes on the constraint of the learning rate

 - 8 pts did not mention yx or learning rate (yx is the basic and necessary component when updating the weights)

4.3 (c),(d) **6 / 6**

- **3 pts** c is wrong
- **3 pts** d is wrong
- **6 pts** both c and d are wrong

✓ - 0 pts all correct

 - 1 pts c is partially correct: mention "adding dimension" without specific solutions or with wrong solutions

 - 1 pts d is partially correct: A. wrong w0w1w2 B.neglect the question "only solution"

4.4 (e) **0 / 5**

- **2 pts** partially correct, e.g. draw a correct diagram
- **0 pts** correct

✓ - 5 pts wrong

QUESTION 5

19 pts

5.1 (a) **2 / 3**

 - 0 pts Correct

✓ - 1 pts No Y prediction

- **1 pts** Incorrect Prediction
- **1.5 pts** Wrong calculation & not finished; no Y prediction
- **1.5 pts** Incomplete & wrong calculation
- **0.5 pts** Wrong calculation

 - 0.5 pts No Y prediction after calculating probabilities

- **1.5 pts** Wrong calculation & wrong prediction
- **1 pts** Wrong formula is used
- **0 pts** Slight mistake in calculation
- **1.5 pts** Not finished; no Y prediction
- **1 pts** Your calculation is wrong & how you get Y?

See solution

- **0.5 pts** You need to show how you get Y
- **1 pts** Wrong calculation & prediction is wrong
- **3 pts** No answer
- **2 pts** Unfinished

5.2 (b) **6 / 6**

- **✓ 0 pts Correct**
	- **2 pts** But you need to prove it.

 - 1 pts You need to show that the other form of this classifier is w^Tx= 0

- **6 pts** Wrong answer
- **0.5 pts** See the solution in CCLE
- **1 pts** See the solution in CCLE
- **2 pts** Your proof is not correct
- **3 pts** Wrong perception ; see the solution on CCLE

 - 2 pts I did not understand what have you written. Assuming you have written 'linear classifier' I have graded. You need to prove it. Please the the solution on CCLE

5.3 (c) **10 / 10**

- **0 pts** Correct
- **0 pts** You forgot to mention the sum
- **2 pts** Please see the solution on CCLE
- **10 pts** No answer
- **5 pts** Unfinished
- **8 pts** Wrong answer
- **✓ 0 pts Slight mistake**
	- **2 pts** How??
	- **9 pts** No answer
	- **8 pts** Not finished
	- **0 pts** Mistake
	- **3 pts** Please see the solution on CCLE
	- **5 pts** Not correct.

QUESTION 6

6 name **2 / 2**

 \checkmark - 0 pts Correct

Fall 2018 CM146: Introduction to Machine Learning Midterm Nov. 5^{th} , 2018

- This is a closed book exam. Everything you need in order to solve the problems is supplied in the body of this exam.
- $\bullet\,$ This exam booklet contains Five problems.
- $\bullet\,$ You have 90 minutes to earn a total of 100 points.
- \bullet Besides having the correct answer, being concise and clear is very important. For full credit, you must show your work and explain your answers.

Good Luck!

Name and ID: (2 Point) Mark Guevara

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 \mathbb{R}^d

 $\label{eq:1.1} \mathcal{D}_{\mathcal{C}}(t) = \mathcal{D}_{\mathcal{C}}(t)$

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True/False Questions (Add a 1 sentence justification.) [18 pts] 1

(a) (3 pts) For a continuous random variable x and its probability density function $p(x)$, it holds that $0 \leq p(x) \leq 1$ for all x. Ĥ \overline{A}

(b) (3 pts) K-NN is a linear classification model.

False ;
$$
lc-NN
$$
 is non-linear

- (c) (3 pts) Logistic regression is a probabilistic model and we use the maximum likelihood principle to learn the model parameters.
	- Tre : however, most models will use the minimum negative
- (d) (3 pts) Suppose you are given a dataset with 990 cancer-free images and 10 images from cancer patients. If you train a classifier which achieves 98% accuracy on this dataset, it is a reasonably good classifier.

(e) (3 pts) A classifier that attains 100% accuracy on the training set is always better than a classifier that attains 70% accuracy on the training set. ğ

(f) (3 pts) A decision tree is learned by minimizing information gain.

Forlse; it is learned by maximizing information gain

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Short Questions [23 pts] $\boldsymbol{2}$

(a) (4 pts) What is the main difference between gradient descent and stochastic gradient descent (in one sentence)? Which one require more iterations to converge, why?

Gradient descent calculates the gradient of the entire set
which determining a step, while stochastic estimates it
by using a single data point. Stochastic is slower to in the correct direction.

- (b) (3 pts) What is the motivation to have a development set? Many models have hyperperrancements that need to
be chosen. Howing a dev set allows for those
parameters to be chosen independent of the data set to prevent overfitting.
- (c) (3 pts) Describe the differences between linear regression and logistic regression (in less than two sentences).

Logistic regression involves finding the probability of
y having a certain value given x; while linear
regression is a method for finding an opproximate least-onem squares

(d) (3 pts) Consider the models that we have discussed in lecture: decision trees, k-NN, logistic regression, Perceptrons. If you are required to train a model that predicts the probability that the patient has cancer, which of these would you prefer, and why?

Logistic regression uouid be best because it
is the best at modeling probabilistic models.
The other models are better for categorization.
(although a devision tree could be used to an extent)

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 $\label{eq:2.1} \mathcal{L}(\mathcal{L}) = \mathcal{L}(\mathcal{L}) \mathcal{L}(\mathcal{L}) = \mathcal{L}(\mathcal{L}) \mathcal{L}(\mathcal{L}) = \mathcal{L}(\mathcal{L}) \mathcal{L}(\mathcal{L}) = \mathcal{L}(\mathcal{L}) \mathcal{L}(\mathcal{L})$

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 $\label{eq:2.1} \frac{1}{2} \int_{\mathbb{R}^3} \left| \frac{d\mu}{d\mu} \right|^2 \, d\mu = \frac{1}{2} \int_{\mathbb{R}^3} \left| \frac{d\mu}{d\mu} \right|^2 \, d\mu = \frac{1}{2} \int_{\mathbb{R}^3} \left| \frac{d\mu}{d\mu} \right|^2 \, d\mu.$

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 $\label{eq:2.1} \mathcal{Q}(\mathcal{A}) = \mathcal{Q}(\mathcal{A})$

(e) (10 pts) Given n linearly independent feature vectors in n dimensions, show that for any assignment to the binary labels you can always construct a linear classifier with weight vector w which separates the points. Assume that the classifier has the form $sign(w \cdot x)$. Hint: a set of vectors are linearly independent if no vector in the set can be defined as a linear combination of the others.

Select two points with opposite classification. + can be used to define a hyposplane The that separates it from -. Ald another + (or by symmetry -) and create hyperplane using points of the same as a banis Because H_{L} points are linearly, independent, the - point does not lie on this Inperplane. Reposit, adding endre + to one hyperplane and each another. All of the points on the + hyperplane
commot define the - points, so this imperplane behave as a linear dassifier.

 $\label{eq:2.1} \frac{1}{2} \sum_{i=1}^n \frac{1}{2} \sum_{j=1}^n \frac{$ $\frac{a}{a}$ $\label{eq:2.1} \mathcal{L}(\mathcal{L}^{\text{max}}_{\mathcal{L}}(\mathcal{L}^{\text{max}}_{\mathcal{L}}))\leq \mathcal{L}(\mathcal{L}^{\text{max}}_{\mathcal{L}}(\mathcal{L}^{\text{max}}_{\mathcal{L}}))$ $\label{eq:2.1} \mathcal{L}(\mathbf{r}) = \mathcal{L}(\mathbf{r}) \mathcal{L}(\mathbf{r}) = \mathcal{L}(\mathbf{r}) \mathcal{L}(\mathbf{r})$ $\mathcal{L}(\mathcal{A})$ and $\mathcal{L}(\mathcal{A})$ are the set of the set of the set of the $\mathcal{L}(\mathcal{A})$ $\label{eq:2.1} \frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2\pi}}\int_{\mathbb{R}^3}\frac{1$ $\label{eq:2.1} \begin{split} \mathcal{L}_{\text{max}}(\mathcal{L}_{\text{max}}) = \mathcal{L}_{\text{max}}(\mathcal{L}_{\text{max}}) \end{split}$

 $\label{eq:1.1} \mathbf{u} = \mathbf{u} + \mathbf{u}$

3 Decision Trees [15 pts]

For this problem, you can write your answers using log_2 , but it may be helpful to note that $log_2 3 \approx 1.6$ and entropy $H(S) = -\sum_{v=1}^{K} P(S = v) log_2 P(S = v)$. The information gain of an attribute A is $G(S, A) = H(S) - \sum_{v \in Value(A)} \frac{|S_v|}{|$ has value v .

(a) We will use the dataset below to learn a decision tree which predicts the output Y, given by the binary values of A, B, C.

i. (2 pts) Calculate the entropy of the label y .

$$
H(Y) = -\frac{2}{4} \log \frac{2}{4} - \frac{2}{4} \log \frac{2}{4}
$$

= $-\log \frac{1}{2}$ = 1

- ii. (5 pts) Draw the decision tree that will be learned using the ID3 algorithm that achieves zero training error.
	- the most A reduces entrepay

 $\label{eq:1} \frac{1}{\sqrt{2}}\sum_{i=1}^{n} \frac{1}{\sqrt{2}}\sum_{$

 \sim

 $\frac{1}{2}$

 \sim

iii. (3 pts) Is this tree optimal (i.e. does it get minimal training error with minimal depth?) explain in two sentences, and if it isn't optimal draw the optimal tree.

No; there is a solution that doesn't use the 103 abouthings method but only has a
depth of 2 instead of 3. $\overline{\beta}$ $\frac{3}{2}$

(b) (5 pts) You have a dataset of 400 positive examples and 400 negative examples. Now suppose you have two possible splits. One split results in $(300+, 100)$ and $(100+, 300)$. The other choice results in $(200+, 400)$, and $(200+, 0)$. Which split is most preferable and why?

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$$
\frac{32a}{6a^{2}-1} \text{ exists of } |1| \le 3
$$
\n
$$
6a^{2}-100 \text{ terms of } |1| \le 3
$$
\n
$$
1 - \frac{100}{600} \left(\frac{300}{400} \log \frac{300}{100} - \frac{100}{100} \log \frac{100}{400} \right) - \frac{100}{600} \left(\frac{100}{100} \log \frac{300}{100} - \frac{300}{100} \log \frac{300}{100} \right) + \frac{300}{100} \log \frac{300}{100} - \frac{300
$$

The second split results in a barger

 $\label{eq:2.1} \begin{split} \mathcal{L}_{\text{max}}(\mathbf{r}) & = \frac{1}{2} \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r}) \\ & = \frac{1}{2} \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r}) \mathcal{L}_{\text{max}}(\mathbf{r})$

 $\label{eq:2.1} \mathcal{E} = \mathcal{E} \left(\mathcal{E} \right)$ \mathcal{B} . In the set of \mathcal{B}

 $\label{eq:2.1} \mathcal{A}(\mathcal{A}) = \mathcal{A}(\mathcal{A}) \otimes \mathcal{A}(\mathcal{A}) \otimes \mathcal{A}(\mathcal{A})$

Perceptron Algorithm [23 pts] 4

(a) (4 pts) Assume that you are given training data $(x, y) \in R^2 \times \{\pm 1\}$ in the following order:

We run the Perceptron algorithm on all the samples once, starting with an initial set of weights $w = (1, 1)$ and bias $b = 0$. On which examples, the model makes an update?

(b) (8 pts) Suggest a variation of the Perceptron update rule which has the following property: If the algorithm sees two consecutive occurrences of the same example, it will never make a mistake on the second occurrence. (Hint: determine an appropriate learning rate that guarantees this property). Prove your answer is correct.

The update rule is :

 $w \leftarrow w + \frac{\|w - \mathcal{V}\|}{\|w - \mathcal{V}\|}$ Let x , y be such that $y(w^T x) \ge 0$.
Therefore (x, y) create an incorrect prediction and
the model is updated s.t. $w \leftarrow w$ the summer.
I w-x | is always greater than $||w||$, as x is opposite
the direction of w , so add

 $\label{eq:2.1} \frac{1}{\sqrt{2}}\int_{0}^{\pi} \frac{1}{\sqrt{2\pi}}\left(\frac{1}{\sqrt{2\pi}}\right)^{2} \frac{1}{\sqrt{2\pi}}\int_{0}^{\pi}\frac{1}{\sqrt{2\pi}}\left(\frac{1}{\sqrt{2\pi}}\right)^{2} \frac{1}{\sqrt{2\pi}}\int_{0}^{\pi}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\int_{0}^{\pi}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\frac{1}{\sqrt{2\pi}}\int_{0}^{\pi$

 $\label{eq:2.1} \mathcal{L}(\mathcal{L}(\mathcal{L})) = \math$

(c) (3 pts) Linear separability is a pre-requisite for the Perceptron algorithm. In practice, data is almost always inseparable, such as XOR.

Provide a solution to convert the inseparable data to be linearly separable. The XOR can be used for the illustration.

 $\frac{1}{3}$ $x_{i}x_{i}$ $|e$ _{$>$} $\frac{\partial}{\partial \mathbf{a}}$ The data set of (x_1, x_2, x_3) is then dinearly
separable using $y = -x_3$ or $w^T = (0, 0, -1)$ -1 | -1 100

(d) (3 pts) Design (specify w_0, w_1, w_2 for) a two-input Perceptron (with an additional bias or offset term) that computes "OR" Boolean functions. Is your answer the only solution?

$$
w^{\top} = \left(1, 1, 1\right)
$$

It is not the only solution, we any
$$
0 < w_3 < 2
$$

will work with $w_0 = 1$ $w_2 = 1$

(e) (5 pts) What is the maximal margin γ in the above OR dataset.

8

 $\label{eq:2.1} \frac{1}{2} \int_{\mathbb{R}^3} \frac{1}{\sqrt{2}} \, \mathrm{d} x \, \mathrm{d$

 $\mathcal{L}(\mathcal{L}(\mathcal{L}))$ and the contribution of the contribution

 $\label{eq:2.1} \mathcal{L} = \frac{1}{2} \sum_{i=1}^n \frac{1}{2} \sum_{j=1}^n \frac{1}{2} \sum_{j=$

 $\label{eq:2.1} \frac{1}{\sqrt{2}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^2\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^2\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^2\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^2\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^2\frac{1}{\sqrt{2}}\frac{1}{\sqrt{2}}\frac{1}{\sqrt{2}}\frac{1}{\sqrt{2}}\frac{1}{\sqrt{2}}\frac{1}{\sqrt{2}}$

 \sim 100 $^{\prime\prime}$

 $\label{eq:3.1} \mathcal{O}(\mathcal{E}) = \mathcal{O}(\mathcal{E})$

5 Logistic Regression [19 pts]

Considering the following model of logistic regression for a binary classification, with a sigmoid function $\sigma(z) = \frac{1}{1+e^{-z}}$:

$$
P(Y = 1|X, w_0, w_1, w_2) = \sigma(w_0 + w_1X_1 + w_2X_2)
$$

(a) (3 pts) Suppose we have learned that for the logistic regression model, (w_0, w_1, w_2) $(-\ln(4), \ln(2), -\ln(3))$. What will be the prediction $(y = 1 \text{ or } y = -1)$ for the given $x=(1,2)$?

$$
\rho = \sigma(-\ln 4 + (\ln 2 - (2))\sqrt{3})
$$

= $\sigma(\ln(\frac{1}{4}) + \ln(1) + \ln(\frac{1}{4}))$
= $\sigma(\ln(\frac{1}{18}))$
= $\frac{1}{1 + e^{-\frac{1}{18}}} = \frac{1}{1 + \frac{1}{e^{\frac{1}{18}}}} = \frac{1}{1 + \frac{1}{e^{\frac{1}{18}}}}$

(b) (6 pts) Is logistic regression a linear or non-linear classifier? Prove your answer.

Logistic regression is a fineur classifier
because its algorithm scoles to find a use of P
scales with $w^T z$, but fundamentally the data
could be categorized into \rightarrow and \rightarrow if, say, $P \ge 0.5$
and $P < 0.5$ respectivel

 $\label{eq:2.1} \frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac{1}{\sqrt{2}}\sum_{i=1}^n\frac$ $\label{eq:1} \mathbf{x} = \mathbf{y} + \mathbf{y}$

 $\label{eq:2.1} \frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\left(\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{2\pi}}\sum_{i=1}^n\frac{1}{\sqrt{$

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(c) (10 pts) In the hoemwork, we mention an alternative formulation of learning a logistic regression model when $y \in \{1, 0\}$ \sim \mathcal{L}

$$
\mathcal{V} = \begin{bmatrix}\n\text{arg}\min_{w} \sum_{i=1}^{m} y_i \log \sigma(w^T x_i) + (1 - y_i) \log(1 - \sigma(w^T x_i)) \\
\text{Derive its gradient.} \\
\downarrow \downarrow \downarrow \\
\downarrow \downarrow \downarrow \\
\downarrow \downarrow \downarrow\n\end{bmatrix}
$$
\n
$$
\begin{bmatrix}\n\mathcal{J} = \begin{bmatrix}\n\mathcal{J} \\
\mathcal{J} \mathcal{W} \\
\downarrow \mathcal{W} \\
\downarrow \downarrow\n\end{bmatrix} & \mathcal{W}, \mathcal{X}, + \cdots + \mathcal{W}, \mathcal{X} \sim \mathcal{W}, \\
\downarrow \downarrow \downarrow \downarrow\n\end{bmatrix}
$$

 $\overline{1}$

 $\frac{1}{4\pi}$

Where
$$
\frac{\partial J}{\partial w_{d}} = \sum_{i=1}^{m} y_{i} \frac{1}{\sigma(w^{T}x_{i})} [\sigma(w^{T}x_{i})|x_{j} + (1-y_{i})\frac{1}{\sigma(w^{T}x_{i})}(-1)(\sigma(w^{T}x_{i})|x_{j})x_{j} + (1-y_{i})\frac{1}{\sigma(w^{T}x_{i})}(-1)(\sigma(w^{T}x_{i})|x_{j})x_{j})x_{j}}
$$

\n
$$
= \sum_{i=1}^{m} y_{i}x_{i} - x_{j}(\sigma(w^{T}x_{i}))
$$

\n
$$
= \sum_{i=1}^{m} y_{i}x_{i} - x_{j}(\sigma(w^{T}x_{i}))
$$

 $10\,$

 $\label{eq:R1} \mathbf{X} = \mathbf{X} \mathbf{X} + \mathbf{X} \mathbf{$

 \bar{a}

 \mathbf{z}

 $\label{eq:2.1} \frac{1}{\sqrt{2}}\int_{\mathbb{R}^3}\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^2\left(\frac{1}{\sqrt{2}}\right)^2\left(\frac{1}{\sqrt{2}}\right)^2\left(\frac{1}{\sqrt{2}}\right)^2\left(\frac{1}{\sqrt{2}}\right)^2\left(\frac{1}{\sqrt{2}}\right)^2.$

 \mathcal{L}^{max}