

1. **Bayes rule [6pt]**

A packet arrives at a router and will be sent to 2 outgoing links. Link 1 is lossy so the probability of packet-loss is $\frac{2}{3}$. Link 2 is loss free. Suppose the packet will go to link 1 with probability $\frac{1}{4}$ and link 2 with $\frac{3}{4}$. What is the conditional probability that the packet goes to link 2 given that it is not lost?

Answer

$$P(K|C) = \frac{P(KC)}{P(C)} = \frac{P(C|K)P(K)}{P(C|K)P(K) + P(C|K^C)P(K^C)}$$
$$P(K|C) = \frac{9}{10}$$

2. TCP Window Size [6pt]

In a certain version of TCP congestion control schemes, the congestion window size X is doubled every time a packet is delivered successfully. Let n denote the number of packets delivered successfully before packet loss occurs. Initially the window size X is set to be 1 (before the first packet is sent). Assume that the probability of packet loss each time is 0.5.

- (a) [3pt] Find the pmf of n .

Solution:

The number of packets successfully delivered before loss occurs follows the geometry distribution.

$$p(n) = 0.5^n \cdot 0.5 = 0.5^{n+1}$$

where $n = 0, 1, 2, \dots$

- (b) [3pt] What is the expected window size $E[X]$?

Solution:

$$E[X] = \sum_{n=0}^{\infty} p(n) \cdot 2^n = \sum_{n=0}^{\infty} 0.5^{n+1} \cdot 2^n = \sum_{n=0}^{\infty} 0.5 = \infty$$

3. Probability Inequalities [8pt]

Label the following statements with either $=$, \leq or \geq . The statements can be labeled with $=$ if equality always holds, \leq or \geq if one of these hold. If no such inequality or equality holds, label the statement as NONE.

- (a) [2pt] $P(B)$ versus $1 - [P(B^c, A) + P(B^c, A^c)]$.
Answer: $P(B) = 1 - [P(B^c, A) + P(B^c, A^c)]$

- (b) [2pt] $p_Y(g(x))$ versus $p_X(x)$ if $Y = g(X)$, where X, Y are discrete random variable, $g(\cdot)$ is a function.
Answer: $p_Y(g(x)) \geq p_X(x)$ since $p_Y(g(x)) = \sum_{u:g(u)=g(x)} p_X(u)$

- (c) [2pt] Probability mass function $p_X(x)$ versus $p_{XY}(x, y)$ for discrete random variables.
Answer: $p_{XY}(x, y) = p_X(x)p_{Y|X}(y|x) \leq p_X(x)$

- (d) [2pt] Probability density function $f_X(x)$ versus $f_{XY}(x, y)$ for continuous random variables.
Answer: $f_{XY}(x, y) = f_X(x)f_{Y|X}(y|x)$. Since $f_{Y|X}(y|x)$ can be any value, so NONE.

4. Splitting Poisson Distribution [10pt]

The number of tasks arrive at a router is a Poisson (λ) variable. The router independently routes to computers A or B with probability p and $1 - p$ respectively. Let X_N be the total number of tasks, X_A the number of tasks at computer A, and X_B the number of tasks at computer B.

- (a) [4pt] Derive the pmf of X_A, X_B .
- (b) [1pt] State the condition for two random variables to be independent.
- (c) [3pt] Show that X_A and X_b are independent based on you answer on (a) and (b).
- (d) [2pt] Find the covariance of X_N and X_A .

Solution: (a) **Page 73 of Course Reader.**

$$P(A = a) = \frac{e^{-\lambda p} \lambda p^a}{(a)!}, P(B = b) = \frac{e^{-\lambda(1-p)} \lambda (1-p)^b}{(b)!}$$

(b)

$$P_{A,B}(a, b) = P_A(a)P_B(b)$$

(c)

$$\begin{aligned} P(A = a, B = b) &= \frac{e^{-\lambda} \lambda^{(a+b)}}{(a+b)!} \binom{a+b}{a} p^a (1-p)^b \\ &= P(A = a)P(B = b) = \frac{e^{-\lambda p} \lambda p^a}{(a)!} \frac{e^{-\lambda(1-p)} \lambda (1-p)^b}{(b)!} \end{aligned}$$

(d)

$$\begin{aligned} \text{cov}(N, A) &= \text{cov}(A + B, A) = \text{cov}(A, A) + \text{cov}(B, A) \\ &= \text{var}(A) = \lambda p \end{aligned}$$

5. Traffic of Wireless Communications [8pt]

We model the number of wireless connections to a base station as Geometric distribution with parameter p . The traffic per connection is Poisson(λ).

- (a) [4pt] Find the Z-transform of total traffic at the base station.
- (b) [4pt] Find the first and second moment of total traffic using the Z-transform you found. Calculate the numerical values when $p = 0.1$ and $\lambda = 100$.

Solution:

The Z-transform of total traffic is

$$G_Y(z) = G_N(G_X(z)) = \frac{pz}{1 - (1-p)z} \Big|_{z=e^{-\lambda(1-z)}} = \frac{pe^{-\lambda(1-z)}}{1 - (1-p)e^{-\lambda(1-z)}} = \frac{p}{e^{\lambda(1-z)} - (1-p)}$$

The first and second moment are

$$\begin{aligned} \frac{dG_Y(z)}{dz} \Big|_{z=1} &= \frac{\lambda pe^{-\lambda(1-z)}}{[e^{\lambda(1-z)} - (1-p)]^2} \Big|_{z=1} = \frac{\lambda}{p} = 1000 \\ \frac{d^2G_Y(z)}{dz^2} \Big|_{z=1} &= \frac{-\lambda^2 pe^{-\lambda(1-z)} [e^{\lambda(1-z)} - (1-p)]^2 + \lambda pe^{-\lambda(1-z)} 2\lambda [e^{\lambda(1-z)} - (1-p)] e^{\lambda(1-z)}}{[e^{\lambda(1-z)} - (1-p)]^4} \Big|_{z=1} \\ &= \frac{2\lambda^2}{p^2} - \frac{\lambda^2}{p} \\ E[X^2] &= \frac{\lambda}{p} + \frac{2\lambda^2}{p^2} - \frac{\lambda^2}{p} = 1901000 \end{aligned}$$