

**Problem 1 (3+3+4+10)**

The displacement  $u(t)$  of a dynamic system is governed by the following second order, linear, differential equation (SLDE)

$$m\ddot{u} + c\dot{u} + ku = F(t) \quad u(0) = u_0, \dot{u}(0) = \dot{u}_0$$

where  $\left\{ \begin{array}{l} m \text{ is the mass,} \\ c \text{ is the damping constant,} \\ k \text{ is the spring constant, and} \\ F(t) \text{ is the externally applied force} \end{array} \right.$

- (a) Define the following in terms of the displacement  $u(t)$  and structural parameters  $m, c, k$
- steady state response of the system
  - critically damped system

(b) Using linearity of the solution, write down the general form of the solution in terms of  $u_0, \dot{u}_0$  and  $F(t)$

- (c) If  $m = 8 \text{ lb}$ ,  $k = 16 \frac{\text{lb}}{\text{ft}}$ ,  $c = \frac{1}{4} \frac{\text{lb-sec}}{\text{ft}}$ ,  $F(t) = 4 \cos(2t) \text{ lb}$ , find the amplitude of the steady state response. Do not use any formula.

$$\frac{1}{m} \ddot{u} + c \dot{u} + ku = F(t) \quad u(0) = u_0, \quad \dot{u}(0) = \dot{u}_0$$

a Steady State Response

$\lim_{t \rightarrow \infty} u(t)$  : steady state response =  $u_p(t)$

\* Critically damped system

$$m \ddot{u} + c \dot{u} + ku = f(t)$$

$$\ddot{u} + \frac{c}{m} \dot{u} + \frac{k}{m} u = \frac{F}{m}(t)$$

$$\ddot{u} + 2b \dot{u} + \omega^2 u = \frac{F}{m}(t) \quad \text{where } 2b = \frac{c}{m}$$

$$\omega^2 = \frac{k}{m}$$

Homog. equ.

$$\ddot{u} + 2b \dot{u} + \omega^2 u = 0$$

Let  $u = e^{rt}$

$$\text{AE } r^2 + 2br + \omega^2 = 0$$

$$r = \frac{-2b \pm \sqrt{4b^2 - 4\omega^2}}{2}$$

for critically damped<sup>2</sup> system,

$$4b^2 - 4\omega^2 = 0$$

$$\frac{c^2}{m^2} - 4 \frac{k}{m} = 0$$

$$c^2 = 4km$$

$$\& r_1 \& r_2 = -b, -b = -\frac{c}{2m}, -\frac{c}{2m}$$

$$u_h(t) = C_1 e^{-(c/2m)t} + C_2 t e^{-(c/2m)t}$$

$$u_{gen}(t) = C_1 e^{-(c/2m)t} + C_2 t e^{-(c/2m)t} + u_p(t)$$

$$b) u(t) = u_0 \phi_1(t) + \dot{u}_0 \phi_2(t) + \int_0^t F(\tau) \phi_3(t-\tau) d\tau$$

where  $\phi_1, \phi_2$  &  $\phi_3$  are structural functions

1c

$$m = 8 \text{ lb}$$

$$k = 16 \text{ lb/ft}$$

$$c = \frac{1}{4} \frac{\text{lb} \cdot \text{sec}}{\text{ft}}$$

$$F(t) = 4 \cos(2t)$$

$$m\ddot{u} + c\dot{u} + ku = F(t)$$

$$8\ddot{u} + \frac{1}{4}\dot{u} + 16u = 4 \cos 2t$$

Homog. eqn.

$$8\ddot{u} + \frac{1}{4}\dot{u} + 16u = 0$$

$$\text{or } 32\ddot{u} + \dot{u} + 64u = 0$$

Let  $u = e^{rt}$

$$\text{AE: } 32r^2 + r + 64 = 0$$

$$r = \frac{-1 \pm \sqrt{1 - 4 \cdot 32 \cdot 64}}{64} = \frac{-1 \pm \sqrt{-8191}}{64} = \frac{-1 \pm i90.5}{64}$$

$$= -0.016 \pm i1.41$$

$$u_h = C_1 e^{-0.016t} \cos(1.41t) + C_2 e^{-0.016t} \sin(1.41t)$$

$$g(t) = 4 \cos 2t$$

$$y_p(t) = A \cos 2t + B \sin 2t$$

$$y_p'(t) = -2A \sin 2t + 2B \cos 2t$$

$$y_p''(t) = -4A \cos 2t - 4B \sin 2t$$

Putting in the DE,

1.4

$$-32A \cos 2t - 32B \sin 2t - \frac{1}{2}A \sin 2t + \frac{1}{2}B \cos 2t$$

$$+ 16A \cos 2t + 16B \sin 2t = 4 \cos 2t$$

Comparing coeff

cos 2t

$$-32A + \frac{1}{2}B + 16A = 4$$

$$\therefore -16A + \frac{1}{2}B = 4$$

$$\therefore -32A + B = 8$$

$$\therefore B = 8 + 32A \quad \text{--- i}$$

sin 2t

$$-32B - \frac{1}{2}A + 16B = 0$$

$$\therefore -16B - \frac{1}{2}A = 0$$

$$\therefore -32B - A = 0$$

$$\therefore B = -\frac{A}{32} \quad \text{--- ii}$$

$$8 + 32A = -\frac{A}{32}$$

$$\therefore 256 + 1024A = -A$$

$$\therefore 1025A = -256$$

$$\therefore A = -0.25$$

$$\therefore B = 0.0078$$

$$u_p(t) = -0.25 \cos 2t + 0.0078 \sin 2t$$

Amplitude of steady state response

$$= \sqrt{(-0.25)^2 + (0.0078)^2} = 0.25$$

**Problem 2 (6+6+8)**

- a. Explain the method of undetermined coefficients used to determine the particular solution  $y_p$  of a given nonhomogeneous SLDE.

Is the method applicable to any general SLDE?

Does the form of  $y_p$  depend on the solution of the corresponding homogenous problem?

- b. **Write down the forms of the particular solution** of the differential equation

$y'' - 4y' + 4y = g(t)$  using the method of undetermined coefficients for the following cases

1.  $g(t) = t \sin(t) e^t$

2.  $g(t) = \sin(t) + t e^{2t}$

3.  $g(t) = t + \cos(t) + e^{2t}$

For the third case above, derive the **complete general solution** of the SLDE.

Problem 2.

- a.
- find homogeneous solution
  - "guess" particular solution given  $g(t)$ 
    - if there is repetition between guessed  $y_p$  & homogeneous solutions, multiply guessed  $y_p$  by  $t$  until there is no repetition.
  - differentiate final guessed  $y_p$  as many times as needed in order to plug in guessed  $y_p, y_p', y_p''$  into problem statement.
  - plug in  $y_p, y_p', y_p''$  into problem statement with  $g(t)$  on right hand side
  - compare left & right hand sides of equ to find coefficients of guessed  $y_p$ .
  - check that the guessed  $y_p$  (with coefficients) are valid

NOT applicable to any general SLDE.

YES,  $y_p$  depends on the corresponding homogeneous solution in that if a term is repeated, the guessed  $y_p$  is multiplied by  $t$  until it is in a form not represented in the homogeneous solution.

b.  $y'' - 4y' + 4y = g(t)$

C.E.  $r^2 - 4r + 4 = 0$   
 $(r-2)^2 = 0$

roots: 2, 2

$y_{\text{homogeneous}} = C_1 e^{2t} + C_2 t e^{2t}$

1.  $g(t) = t \sin(t) e^t$

$\therefore y_p(t) = [(A_0 + A_1 t) \cos(t) + (B_0 + B_1 t) \sin(t)] e^t$

## Problem 2

b. 2.  $g(t) = \sin(t) + te^{2t}$

$$\therefore y_p(t) = A_1 \cos(t) + A_2 \sin(t) + t^2(A_3 + A_4 t)e^{2t}$$

3.  $g(t) = t + \cos(t) + e^{2t}$

$$\therefore y_p(t) = (A_0 + A_1 t) + A_2 \cos(t) + A_3 \sin(t) + A_4 t^2 e^{2t}$$

complete general solution:

$$y_p(t) = A_0 + A_1 t + A_2 \cos(t) + A_3 \sin(t) + A_4 t^2 e^{2t}$$

$$y_p'(t) = A_1 - A_2 \sin(t) + A_3 \cos(t) + 2A_4 t e^{2t} + 2A_4 t^2 e^{2t}$$

$$y_p''(t) = -A_2 \cos(t) - A_3 \sin(t) + 2A_4 e^{2t} + 4A_4 t e^{2t} + 4A_4 t e^{2t} + 4A_4 t^2 e^{2t}$$

plug into  $y'' - 4y' + 4y = g(t)$ . & rearrange for comparison

$$y_p'' - 4y_p' + 4y_p = t + \cos(t) + e^{2t}$$

$$-A_2 \cos(t) - A_3 \sin(t) + 2A_4 e^{2t} + 4A_4 t e^{2t} + 4A_4 t e^{2t} + 4A_4 t^2 e^{2t}$$

$$-4(A_1 - A_2 \sin(t) + A_3 \cos(t) + 2A_4 t e^{2t} + 2A_4 t^2 e^{2t})$$

$$+4(A_0 + A_1 t + A_2 \cos(t) + A_3 \sin(t) + A_4 t^2 e^{2t})$$

$$= t + \cos(t) + e^{2t}$$

$$(4A_0 - 4A_1) + (3A_2 - 4A_3) \cos(t) + (3A_3 + 4A_2) \sin(t)$$

$$+ (4A_1)t + (2A_4)e^{2t} + (8A_4 - 8A_4)t e^{2t} + (8A_4 - 8A_4)t^2 e^{2t}$$

$$= t + \cos(t) + e^{2t}$$

$$(4A_0 - 4A_1) + (3A_2 - 4A_3) \cos(t) + (3A_3 + 4A_2) \sin(t) + (4A_1)t$$

$$+ (2A_4)e^{2t} = t + \cos(t) + e^{2t}$$



## Problem 2

b. complete general solution.

compare:

$$\text{constants: } 4A_0 - 4A_1 = 0$$

$$t: 4A_1 = 1$$

$$\cos(t): 3A_2 - 4A_3 = 1$$

$$\sin(t): 4A_2 + 3A_3 = 0$$

$$e^{2t}: 2A_4 = 1$$

$$\therefore A_0 = \frac{1}{4}$$

$$A_1 = \frac{1}{4}$$

$$A_2 = \frac{3}{25}$$

$$A_3 = -\frac{4}{25}$$

$$A_4 = \frac{1}{2}$$

general:  $y_p + y_h = y_g$ .

$$\therefore y_g = C_1 e^{2t} + C_2 t e^{2t} + \frac{1}{4} + \frac{1}{4}t + \frac{3}{25} \cos(t) - \frac{4}{25} \sin(t) + \frac{1}{2} t^2 e^{2t}$$

**Problem 3 (4+4+6+6)**

Consider a linear,  $n$ -th order differential equation with constant coefficients

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y = g(t), \quad y^{(n)} = \frac{d^n y}{dx^n}$$

- Explain the procedures leading to the complete solution of the homogenous equation  $L[y] = 0$
- Does the form of the particular solution  $y_p(t)$  of  $L[y] = g(t)$  depend on the coefficients  $a_0, a_1, \dots, a_n$  and the form of  $g(t)$ ? If so, explain the nature of such dependency.
- For the fourth order equation  $L[y] = y^{(4)} + 3y'' - 4y = g(t) = t + t^2 e^t + 3t \sin(2t)$ , derive the general solution of  $L[y] = 0$ , and
- Using result in (c), write down the form of the particular solution  $y_p$  of  $L[y] = g(t)$ . Explain your form of  $y_p$ . **Do not solve for the unknown constants in your formulation.**

Solution

(a) Using the trial solution  $y = e^{\lambda t}$  in  $L[y] = 0$ ,  $\lambda$  satisfies the  $n$ -th degree equ<sup>n</sup>:  $a_0 \lambda^n + a_1 \lambda^{n-1} + \dots + a_{n-1} \lambda + a_n = 0$ .

This equ<sup>n</sup> yields  $n$ -sol<sup>s</sup> of  $\lambda = \lambda_1, \lambda_2, \dots, \lambda_n$ . Hence the solution can be written as  $y = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t} + \dots + c_n e^{\lambda_n t}$ . These fundamental solutions should be modified if the roots are repeated.

(b) Yes since the form of  $y_p$  depends on  $g(t)$  as well as the roots  $\lambda_1, \lambda_2, \dots, \lambda_n$ , which depend on  $a_0, a_1, \dots, a_n$ .

(c) Using  $y \sim e^{\lambda t}$ ,  $\lambda$  satisfies  $\lambda^4 + 3\lambda^2 - 4 = 0$  in  $L[y] = 0$

$$\lambda^2 = \frac{-3 \pm \sqrt{9+16}}{2} = 1, -4 \Rightarrow \lambda = 1, -1, -2i, 2i$$

Fundamental sol<sup>s</sup>:  $e^t, e^{-t}, \sin 2t, \cos 2t$

General sol<sup>s</sup> of  $L[y] = 0$ ,  $y = c_1 e^t + c_2 e^{-t} + c_3 \sin 2t + c_4 \cos 2t$

(d) When  $g(t) = t + t^2 e^t + 3t \sin(2t)$ .

$$g(t) = (A_1 + A_2 t) + t e^t (B_1 + B_2 t + B_3 t^2) e^t + t [(C_1 + C_2 t) \sin 2t + (D_1 + D_2 t) \cos 2t]$$

Since  $e^t$  and  $\sin 2t$  are fundamental sol<sup>s</sup> of  $L[y] = 0$