

MATH 33A Midterm II, Spring 2018

Name:

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Instruction: Justify all your answers. No points will be given without sufficient reasoning/calculations.

Problem 1. (4)

(i) Use row or column reduction to compute $\det A$, where

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 4 & 5 \\ 1 & 4 & 5 & 6 \end{bmatrix}$$

(ii) Find $\det B$, where

$$B = \begin{bmatrix} 0 & 0 & a & 4 \\ 0 & 0 & 3 & 0 \\ 0 & 2 & b & c \\ 1 & d & e & f \end{bmatrix}$$

Here a, b, c, d, e and f are constants.

(iii) Find $\det(AB)$, $\det(A^{-1})$ and $\det(B^{-1})$.

(i) $|A| = \begin{vmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 2 & 3 & 4 \\ 0 & 3 & 4 & 5 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & -1 & -2 \\ 0 & 0 & -2 & -3 \end{vmatrix} = \boxed{-1}$

(ii) $|B| = \begin{vmatrix} 0 & 2 & b & c \\ 1 & d & e & f \\ 0 & 0 & a & 4 \\ 0 & 0 & 3 & 0 \end{vmatrix} = \begin{vmatrix} 0 & 2 \\ 1 & d \end{vmatrix} \cdot \begin{vmatrix} a & 4 \\ 3 & 0 \end{vmatrix}$
 $= (-2) \cdot (-12) = \boxed{24}$

(iii) $|AB| = |A| |B| = \boxed{-24}$ $|A^{-1}| = |A|^{-1} = \boxed{-1}$
 $|B^{-1}| = |B|^{-1} = \boxed{\frac{1}{24}}$

Problem 2. (4)

Let $V = \text{span}\{\vec{v}_1, \vec{v}_2\}$ be a subspace in \mathbb{R}^3 , where $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, and $\vec{v}_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

(i) Find an orthonormal basis for V by using Gram-Schmidt process.

(ii) Find the QR-factorization for A , where

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \\ 1 & 0 \end{bmatrix}$$

$$(i) \quad \boxed{w_1} = \frac{\vec{v}_1}{\|\vec{v}_1\|} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\tilde{w}_2 = v_2 - \langle v_2, w_1 \rangle w_1, \quad \langle v_2, w_1 \rangle = \frac{1}{\sqrt{3}}$$

$$= \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

2 pts

$$= \frac{1}{3} \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}, \quad \boxed{w_2} = \frac{\tilde{w}_2}{\|\tilde{w}_2\|} = \frac{1}{\sqrt{6}} \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}$$

$$(ii) \quad A = (v_1, v_2) = QR$$

$$= (w_1, w_2) \begin{pmatrix} r_{11} & r_{12} \\ 0 & r_{22} \end{pmatrix}$$

2 pts

$$r_{11} = v_1 \cdot w_1 = \sqrt{3}$$

$$r_{12} = v_2 \cdot w_1 = \frac{1}{\sqrt{3}}$$

$$r_{22} = v_2 \cdot w_2 = \frac{2}{\sqrt{6}}$$

$$\therefore Q = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{-1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{-1}{\sqrt{6}} \end{pmatrix}$$

$$R = \begin{pmatrix} \sqrt{3} & \frac{1}{\sqrt{3}} \\ 0 & \frac{2}{\sqrt{6}} \end{pmatrix}$$

Problem 3. (4)

(i) Decide if the equation $A\vec{x} = \vec{b}$ solvable, where $A = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 1 \end{bmatrix}$, and $\vec{b} =$

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

(ii) Find the least-squares solution of the equation $A\vec{x} = \vec{b}$ for A and \vec{b} in (i).

(i) $A\vec{x} = \vec{b}$ is solvable $\Leftrightarrow \text{rk}(\tilde{A}) = \text{rk}(A)$

$$\tilde{A} = \left(\begin{array}{cc|c} 1 & 0 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{array} \right)$$

2 pts $\rightarrow \left(\begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{array} \right) \text{rk}(\tilde{A}) = 3 > 2 = \text{rk}(A) \Rightarrow \text{not solvable.}$

(ii) Normal equations for least square solution:

2 pts $A^* A \vec{x} = A^* \vec{b} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \vec{x} = \begin{pmatrix} 3 & 1 \\ 1 & 1 \end{pmatrix} \vec{x}$$

$$\vec{x} = \begin{pmatrix} 3 & 1 \\ 1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \left[\begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix} \right]^{-1} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \left[\begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix} \right]^{-1} \begin{pmatrix} 2 \\ 1 \end{pmatrix} \cdot \frac{1}{2} = \left[\begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix} \right]^{-1} \begin{pmatrix} 2 \\ 1 \end{pmatrix} \cdot \frac{1}{2}$$

(1) / 2
↑ det A

Since $\text{proj}_{V^\perp}(\vec{x}') = W \{ W^{-1} \vec{x}' \} = (W \cdot W^T) \vec{x}'$.

Problem 4. (4)

Let $V = \text{span} \{ \vec{v}_1, \vec{v}_2 \}$, where $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, and $\vec{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

(i) Find a basis for the orthogonal complement V^\perp of V .

(ii) Find the matrix for the projection to V^\perp , $\text{Proj}_{V^\perp}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ w.r.t the std basis.

(i) Since $\dim V = 2 \Rightarrow \dim V^\perp = 3 - 2 = 1$

Let $V^\perp = \text{span} \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right\} \Rightarrow$

$$\begin{aligned} V_1 \cdot \vec{x}' &= 0 \\ V_2 \cdot \vec{x}' &= 0 \end{aligned} \iff \begin{pmatrix} V_1^T \cdot x \\ V_2^T \cdot x \end{pmatrix} = \begin{pmatrix} V_1^T \\ V_2^T \end{pmatrix} x$$

$$= (V_1 \ V_2)^T x = 0$$

2 pts

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \implies$$

$$\vec{x}' = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad \text{let } w = \frac{\vec{x}'}{\|\vec{x}'\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

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be the orthonormal basis for V^\perp .

\implies (ii) The matrix = $W \cdot W^T = \frac{1}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} -1 & 1 & 0 \end{pmatrix}$

2 pts = $\frac{1}{2} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$$E_{\lambda_2} = \text{span} \left\{ \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

0.5 (iii) Since for λ_1 , alg. mult = 2 > geo. mult. = 1

Problem 5. (4)

$$\text{Let } A = \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & -2 \\ 0 & 1 & 4 \end{bmatrix}$$

A is not diagonalizable.

(i) Find the eigenvalues of A and their algebraic multiplicities.

(ii) Find a basis for each eigenspace of A , and find the geometric multiplicity for each eigenvalue of A .

(iii) Decide if A is diagonalizable.

$$(i) f_A(\lambda) = \det(A - \lambda I) = \det \begin{bmatrix} 2-\lambda & 1 & 1 \\ 0 & 1-\lambda & -2 \\ 0 & 1 & 4-\lambda \end{bmatrix}$$

$$= (2-\lambda) \det \begin{bmatrix} 1-\lambda & -2 \\ 1 & 4-\lambda \end{bmatrix} = (2-\lambda)(\lambda^2 - 5\lambda + 6)$$

$$= (2-\lambda)(\lambda-2)(\lambda-3) = 0 \implies$$

1.5

$$\lambda_1 = 2 \quad w/ \text{ alg. mult} = 2$$

$$\lambda_2 = 3 \quad w/ \text{ ————— } = 1$$

$$(ii) E_{\lambda_1}: (A - \lambda_1 I)X = \begin{pmatrix} 0 & 1 & 1 \\ 0 & -1 & -2 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{rk}(A - \lambda_1 I) = 2$$

$$\implies \dim(E_{\lambda_1}) = 1$$

2 pb geometric mult

$$\& E_{\lambda_1} = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} \implies \vec{x} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$E_{\lambda_2}: (A - \lambda_2 I)X = \begin{pmatrix} -1 & 1 & 1 \\ 0 & -2 & -2 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$X = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \quad \text{Since } \text{rk}(A - \lambda_2 I) = 2 \implies \dim(E_{\lambda_2}) = 1$$