

1. Let  $\mathbf{x}(t) = (\cosh(t), t)$  where  $\cosh(t) = \frac{1}{2}(e^t + e^{-t})$ .

(a) (1/2) Find the velocity,  $\dot{\mathbf{x}}(t)$ .

$$\begin{aligned}\mathbf{x}(t) &= \left(\frac{1}{2}(e^t + e^{-t}), t\right) \\ \dot{\mathbf{x}}(t) &= \left(\frac{1}{2}(e^t - e^{-t}), 1\right)\end{aligned}$$

(b) (1/3) Find the speed.

$$\begin{aligned}\|\dot{\mathbf{x}}(t)\| &= \sqrt{\left(\frac{1}{2}e^t - \frac{1}{2}e^{-t}\right)^2 + 1} \\ &= \sqrt{\frac{1}{4}(e^{2t} - 2 + e^{-2t}) + 1} \\ &\approx \frac{1}{2}\sqrt{e^{2t} + e^{-2t} + 2} \\ &= \frac{1}{2}(e^t + e^{-t})\end{aligned}$$

(c) (1/5) Compute the arclength,  $s$ , from  $(1, 0)$  in direction  $t > 0$ . What is the  $x$  coordinate on the curve when  $s = 1$ ?

$$S = \int_0^t \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

$$S = \int_0^t \frac{1}{2}(e^t + e^{-t}) dt$$

$$2S = (e^t - e^{-t})$$

$$\ln(2S) = \ln(e^t - e^{-t}) = \ln((e^t - e^{-t})^t)$$

$$\ln 2S = t \ln(e^{-\frac{1}{2}})$$

$$t = \frac{\ln(e^{-\frac{1}{2}})}{\ln(2S)} = \ln(e^{-\frac{1}{2}} - 2)$$

$$\text{at } S=1, t = \frac{\ln(e^{-\frac{1}{2}})}{\ln 2} = \ln(e^{-\frac{1}{2}} - 2)$$

$$\times(\ln(e^{-\frac{1}{2}} - 2)) = \left(\frac{1}{2}(e^{-\frac{1}{2}} - 2 + e^{\frac{1}{2}} - 2)\right) \ln(e^{-\frac{1}{2}} - 2)$$

I know this is wrong, but I have to relate it somehow. Then make 0

2. (10) Recall the Frenet-Serret formulae

$$\begin{aligned}\frac{dT}{ds} &= \kappa N, \\ \frac{dN}{ds} &= -\kappa T + \tau B, \\ \frac{dB}{ds} &= -\tau N.\end{aligned}$$

Find  $\frac{d^2T}{ds^2}$ ,  $\frac{d^2N}{ds^2}$  and  $\frac{d^2B}{ds^2}$  in terms of the frame  $T, N$  and  $B$  and the curvature,  $\kappa$ , torsion,  $\tau$  and their derivatives,  $\kappa'$  and  $\tau'$ .

$$\begin{aligned}\frac{d^2T}{ds^2} &= \frac{d}{ds} \left( \kappa N \right) \\ &= \kappa \frac{dN}{ds} + N \kappa' \\ &= \kappa (-\kappa T + \tau B) + \kappa' N\end{aligned}$$

$$\begin{aligned}\frac{d^2N}{ds^2} &= -(\kappa'T + \kappa \frac{dT}{ds}) + \tau'B + \tau \frac{dB}{ds} \\ &= -\kappa'T + \kappa^2 N + \tau'B - \tau^2 N\end{aligned}$$

$$\begin{aligned}\frac{d^2B}{ds^2} &= -(\tau'H + \tau \frac{dN}{ds}) \\ &= -\tau'N + \tau\kappa T - \tau^2 B\end{aligned}$$

3. Let  $f(x,y) = x^2y + xy^2$ .

(a) (/5) From the definition find the directional derivative of  $f$  at the point  $(1,1)$  in the direction  $(\frac{1}{2}, \frac{\sqrt{3}}{2})$ .

$$\text{D}_{\vec{v}} f(x,y) = f(v_x(x), v_y(y))$$

$$r(t) = t(\frac{1}{2}, \frac{\sqrt{3}}{2})$$

$$f(\frac{1}{2}t, \frac{\sqrt{3}}{2}t) = \frac{t^2}{4} \cdot \frac{\sqrt{3}}{2}t + \frac{3t^2}{4} \cdot \frac{t}{2}$$

$$= \frac{t^3\sqrt{3}}{8} + \frac{3t^3}{8}$$

$$f(1,1) = 2 \text{ if } t=2$$

$$= \frac{\sqrt{3}\sqrt{3}+3}{2}$$

(b) (/5) Repeat the above problem only this time use the fact that  $f$  is differentiable and the gradient of  $f$  to simplify the calculation. Be wary that two identical calculations wont get you 10 points.

$$\nabla f(x,y) = (2xy + y^2, x^2 + 2xy)$$

$$\sqrt{\left(\frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2} = \sqrt{\frac{1}{4} + \frac{3}{4}} = 1$$

It's a unit vector.

$$\nabla f(1,1) = (3, 3)$$

$$\nabla f(1,1) \cdot (\frac{1}{2}, \frac{\sqrt{3}}{2}) = \frac{3}{2} + \frac{3\sqrt{3}}{2}$$

$$= \boxed{\frac{3+3\sqrt{3}}{2}}$$

4. (/10) Consider the quadric surface in  $\mathbb{R}^3$  defined by the equation

$$-\frac{x^2}{4} - \frac{y^2}{9} + z^2 = 9.$$

Find the equation of the tangent plane of the quadric at the point, (8, 36, 13) by thinking of the quadric as the level set of an appropriately defined function.

$$F(x, y, z) = -\frac{x^2}{4} - \frac{y^2}{9} + z^2$$

$$\nabla F(x, y, z) = \left( -\frac{x}{2}, -\frac{2y}{9}, 2z \right) \text{ for level } L=9$$

$$\nabla F(8, 36, 13) = (-4, -8, 26), \text{ normal for plane}$$

$$\vec{n} = (-2, -4, 13)$$

Plane:

$$\begin{aligned} -2x - 4y + 13z &= (-2, -4, 13) \cdot (8, 36, 13) \\ &= -16 - 144 + 169 \end{aligned}$$

$$\boxed{-2x - 4y + 13z = 9}$$

5. (a) (4) Consider a path parameterized by arclength,  $\mathbf{x} = \mathbf{x}(s)$ . Show that in this special case the curvature,  $\kappa$ , is the magnitude of the acceleration. That is:

$$\kappa = \|\mathbf{x}''(s)\|.$$

$$R = \left\| \frac{dT}{ds} \right\| \text{ by definition}$$

$$T = \frac{\frac{d\mathbf{x}}{ds}}{\left\| \frac{d\mathbf{x}}{ds} \right\|} =$$

$$\text{thus } T = \frac{d\mathbf{x}}{ds}$$

$$\|T\| = \left\| \frac{d}{ds} \left( \frac{d\mathbf{x}}{ds} \right) \right\| = \left\| \frac{d^2\mathbf{x}}{ds^2} \right\|$$

- (b) (6) For a helix parametrized by

$$\mathbf{x}(t) = (\cos(t), \sin(t), t)$$

compute the torsion,

$$\tau = \frac{(\dot{\mathbf{x}} \times \ddot{\mathbf{x}}) \cdot \dddot{\mathbf{x}}}{\|\dot{\mathbf{x}} \times \ddot{\mathbf{x}}\|^2}.$$

$$\mathbf{x}'(t) = (-\sin t, \cos t, 1)$$

$$\mathbf{x}''(t) = (-\cos t, -\sin t, 0)$$

$$\mathbf{x}'''(t) = (\sin t, -\cos t, 0)$$

$$\begin{aligned} (\mathbf{x}' \times \mathbf{x}'') &= (0 + \cos t, 0 + \sin t, \sin^2 t + \cos^2 t) \\ &= (\cos t, \sin t, 1) \end{aligned}$$

$$\|\mathbf{x}' \times \mathbf{x}''\| = \sqrt{\sin^2 t + \cos^2 t + 1} = \sqrt{2}$$

$$(\mathbf{x}' \times \mathbf{x}'') \cdot \mathbf{x}''' = \sin t \cos t + \sin t \cos t$$

$$\boxed{\tau = \sin t \cos t}$$

6. An object is said to move under the influence of a central force if its acceleration vector satisfies

$$\ddot{\mathbf{x}} = f(\tau) \mathbf{x}$$

where  $\tau = \|\mathbf{x}\|$  and  $f$  is a real value differentiable function of one variable and  $\mathbf{x} = \mathbf{x}(t)$  is the path of the object in  $\mathbb{R}^3$ .

- (a) (/6) Show that the path of an object moving under the influence of a central force is in a plane that contains the origin. Hint: The key trick is to show that  $\dot{\mathbf{x}} \times \mathbf{x}$  is a constant vector (i.e. does not change with time).

$$\begin{aligned} \frac{d}{dt} (\dot{\mathbf{x}} \times \mathbf{x}) &= \cancel{\dot{\mathbf{x}}'' \times \mathbf{x}} + \cancel{\dot{\mathbf{x}} \times \dot{\mathbf{x}}}^0 \\ &= \cancel{\dot{\mathbf{x}} \times \mathbf{x}}^0 \\ &= f(r) \cancel{\dot{\mathbf{x}} \times \mathbf{x}}^0 \\ &= 0, \text{ thus } \cancel{\dot{\mathbf{x}} \times \mathbf{x}}^0 \text{ is constant.} \end{aligned}$$

Since  $\dot{\mathbf{x}} \times \mathbf{x}$  defines the motion perpendicular to velocity & position, it is a normal to a plane that encompasses the motion. If that normal is constant, the plane is constant.

If the motion begins at the origin, then that constant plane must contain that point.

- (b) (/4) If the path of an object goes through the points,  $(1, 2, 3)$ ,  $(0, 4, 5)$  and  $(0, 0, 6)$ , could the object be moving under the influence of a central force? Justify your answer with a calculation.

If the points are all in a plane intersecting the origin, it could be.

$$\vec{PR} = (-1, 2, 3)$$

$$\vec{PQ} = (-1, 2, 2)$$

$$\begin{aligned} \vec{PR} \times \vec{PQ} &= (-2+3, 6+4, -2-2) \\ &= (1, 10, -4) \end{aligned}$$

$x + 10y - 4z = -24$ , this object is not under the influence of a central force.

$$0 + 0 - 0 \neq -24$$