

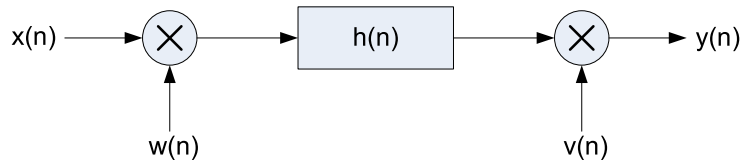
Name:

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MIDTERM SOLUTIONS

1. Problem 1

A system is described by the block diagram shown in the figure below with  $x(n)$  denoting the input sequence,  $y(n)$  denoting the output sequence,  $w(n) = e^{j\omega_0 n}$ , and  $v(n) = e^{-j\omega_0 n}$ .  $h(n)$  is known to be a linear, time-invariant, stable, and causal system.



(a) (10 PTS) Is the system linear?

The system is *linear*.

$$\begin{aligned}
 y(n) &= [x(n)w(n) * h(n)] v(n) \\
 &= [x(n)e^{j\omega_0 n} * h(n)] e^{-j\omega_0 n} \\
 &= \left[ \sum_{k=-\infty}^{\infty} h(k)x(n-k)e^{j\omega_0(n-k)} \right] e^{-j\omega_0 n} \\
 &= \left[ \sum_{k=-\infty}^{\infty} h(k)x(n-k)e^{j\omega_0 n} e^{-j\omega_0 k} \right] e^{-j\omega_0 n} \\
 &= e^{j\omega_0 n} e^{-j\omega_0 n} \left[ \sum_{k=-\infty}^{\infty} h(k)x(n-k)e^{-j\omega_0 k} \right] \\
 &= \sum_{k=-\infty}^{\infty} h(k)x(n-k)e^{-j\omega_0 k}
 \end{aligned}$$

where the last line follows from the second-to-last because  $e^{j\omega_0 n} e^{-j\omega_0 n} = 1$ . We define  $h_1(n) = h(n)e^{-j\omega_0 n}$ . Since  $y(n) = x(n) * h_1(n)$  the overall system  $S$  is basically a convolution, which we know is linear (see the derivation of the convolution sum in chapter 5 in the section titled 'The Convolution Sum'). To verify this, let  $y_1(n) = x_1(n) * h_1(n) = S[x_1(n)]$  and  $y_2(n) = x_2(n) * h_1(n) = S[x_2(n)]$ . Then,

$$\begin{aligned}
 ay_1(n) + by_2(n) &= [ax_1(n) * h_1(n) + bx_2(n) * h_1(n)] \\
 &= [ax_1(n) + bx_2(n)] * h_1(n) \\
 &= S[ax_1(n) + bx_2(n)].
 \end{aligned}$$

Therefore,  $S$  is a linear operation.

- (b) (10 PTS) Is the system time-invariant?

The system is *time-invariant*.

From part (a) we have

$$y(n) = S[x(n)] = \left[ \sum_{k=-\infty}^{\infty} h(k)x(n-k)e^{-j\omega_0 k} \right].$$

Let

$$p(n) = S[x(n-n_0)] = \sum_{k=-\infty}^{\infty} h(k)e^{-j\omega_0 k}x(n-n_0-k).$$

Comparing  $p(n)$  to

$$y(n-n_0) = \sum_{k=-\infty}^{\infty} h(k)e^{-j\omega_0 k}x(n-n_0-k)$$

we see that  $p(n) = y(n-n_0)$ . Thus,  $S$  is time-invariant.

- (c) (10 PTS) Is the system causal?

The system is *causal*.

Since  $S$  is LTI,  $S$  is causal if  $h(n) = 0$  for  $n < 0$ . In this problem, as stated above, our impulse response is  $h_1(n) = h(n)e^{-j\omega_0 n}$ .  $S$  is causal if  $h_1(n) = 0$  for  $n < 0$ . Since  $h_1(n) = h(n)e^{-j\omega_0 n}$  and  $h(n)$  is already an LTI causal system, we know  $h(n) = 0$  for  $n < 0$  so it follows that  $h_1(n) = 0$  for  $n < 0$ . Thus,  $S$  is causal.

- (d) (10 PTS) Is the system BIBO stable?

Now that we know the overall system is LTI, we know that  $S$  is BIBO stable if:

$$\sum_{n=-\infty}^{\infty} |h_1(n)| < \infty,$$

where  $h_1(n) = h(n)e^{-j\omega_0 n}$  is our overall system impulse response from part (a). We have

$$\begin{aligned} \sum_{n=-\infty}^{\infty} |h_1(n)| &< \infty \\ \sum_{n=-\infty}^{\infty} |h(n)e^{-j\omega_0 n}| &< \infty \\ \sum_{n=-\infty}^{\infty} |h(n)||e^{-j\omega_0 n}| &< \infty \\ \sum_{n=-\infty}^{\infty} |h(n)| &< \infty, \end{aligned}$$

where the last line follows from the second-to-last because  $|e^{-j\omega_0 n}| = 1$ . The above inequalities are true because the problem states that  $h(n)$  is LTI, stable, and causal. Thus,  $S$  is stable.

## 2. Problem 2

The z-transform of a causal sequence  $x(n)$  is

$$X(z) = \frac{z}{(z^2 - z + \frac{1}{2})(z + 3/4)}.$$

- (a) (10 PTS) Specify the region of convergence for  $X(z)$ .

Because  $x(n)$  is causal, the region of convergence must contain the unit-circle. Therefore,  $|z| > 3/4$  is the region of convergence.

- (b) (10 PTS) Determine  $Y(z)$ , where  $y(n) = x(-n + 3)$ .

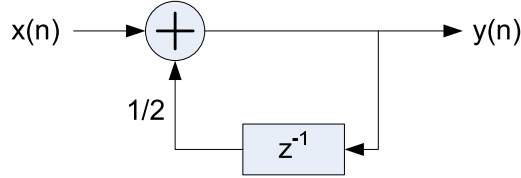
$$\begin{aligned} y(n) &= x(-n + 3) = x(-(n - 3)) \\ \Rightarrow Y(z) &= z^{-3}X(z^{-1}) = \frac{z^{-3}z^{-1}}{(z^{-2} - z^{-1} + \frac{1}{2})(z^{-1} + \frac{3}{4})} \\ &= \frac{8/3}{z(2 - 2z + z^2)(\frac{4}{3} + z)} \end{aligned}$$

- (c) (10 PTS) Specify the region of convergence for  $Y(z)$ .

We know that  $x(n)$  is a right-sided sequence because it is causal. Therefore,  $x(-n + 3)$  is left-sided, so the ROC must be  $0 < |z| < 4/3$ .

### 3. Problem 3

A causal system is described by the block diagram below with  $x(n)$  denoting the input sequence and  $y(n)$  denoting the output sequence.



- (a) (10 PTS) Determine the modes of the system.

The system can be described by the equation  $y(n) - \frac{1}{2}y(n-1) = x(n)$ .

The characteristic equation is  $\lambda - \frac{1}{2} = 0$ . Therefore, the only mode of the system is  $\lambda = \frac{1}{2}$ .

- (b) (10 PTS) Determine the impulse response of the system.

$y(n) = C(\frac{1}{2})^n$  is the solution to the homogeneous equation  $y(n) - \frac{1}{2}y(n-1) = 0$ .

Setting  $x(n) = \delta(n)$  we get  $h(n) - \frac{1}{2}h(n-1) = \delta(n)$ . Therefore,  $h(0) = \frac{1}{2}h(-1) + \delta(0) = 1$  ( $h(-1) = 0$  because  $h(n)$  is causal). This gives us  $C = 1$  and  $h(n) = (\frac{1}{2})^n u(n)$ .

- (c) (10 PTS) Determine the response of the system to the input

$$x(n) = \sum_{k=0}^{\infty} \delta(n-k) - 2u(n-n_1) + \sum_{k=n_2}^{\infty} \delta(n-k),$$

where  $n_2 > n_1 > 0$ , using convolution.

Note that  $u(n) = \sum_{k=0}^{\infty} \delta(n-k)$  and  $u(n-n_2) = \sum_{k=n_2}^{\infty} \delta(n-k)$ . This means we can express  $x(n)$  as

$$\begin{aligned} x(n) &= u(n) - 2u(n-n_1) + u(n-n_2) \\ &= [u(n) - u(n-n_1)] - [u(n-n_1) - u(n-n_2)] \end{aligned}$$

Thus,

$$\begin{aligned} y(n) &= [u(n) - 2u(n-n_1) + u(n-n_2)] * h(n) \\ &= u(n) * h(n) - 2u(n-n_1) * h(n) + u(n-n_2) * h(n). \end{aligned}$$

Let  $y_1(n) = u(n) * h(n)$ ,  $y_2(n) = -2u(n-n_1) * h(n)$ , and  $y_3(n) = u(n-n_2) * h(n)$ . Each of these have the general form  $y_i(n) = A_i u(n-n_i) * h(n)$ , where  $A_i$  and  $n_i$  are integers. From discussion,

we know that  $y_i(n) = 0$  for  $n < n_i$ . Performing the convolution, we obtain:

$$\begin{aligned}
y_i(n) &= \sum_{k=-\infty}^{\infty} h(k)A_i u(n - n_i - k) \\
&= A_i \sum_{k=0}^{\infty} h(k)u(n - n_i - k) \\
&= A_i \sum_{k=0}^{n-n_i} h(k) \\
&= A_i \sum_{k=0}^{n-n_i} \left(\frac{1}{2}\right)^k \\
&= A_i \frac{1 - \left(\frac{1}{2}\right)^{n-n_i+1}}{1 - \frac{1}{2}} \\
&= A_i \left[2 - 2\left(\frac{1}{2}\right)^{n-n_i+1}\right] u(n - n_i)
\end{aligned}$$

Finally,

$$\begin{aligned}
y(n) &= y_1(n) + y_2(n) + y_3(n) \\
&= \left[2 - 2\left(\frac{1}{2}\right)^{n+1}\right] u(n) - 2 \left[2 - 2\left(\frac{1}{2}\right)^{n-n_1+1}\right] u(n - n_1) + \left[2 - 2\left(\frac{1}{2}\right)^{n-n_2+1}\right] u(n - n_2) \\
&= \begin{cases} 0, & n < 0 \\ 2 - \left(\frac{1}{2}\right)^n, & 0 \leq n \leq n_1 - 1 \\ \left(\frac{1}{2}\right)^{n-n_1-1} - \left(\frac{1}{2}\right)^n - 2, & n_1 \leq n \leq n_2 - 1 \\ \left(\frac{1}{2}\right)^{n-n_1-1} - \left(\frac{1}{2}\right)^n - \left(\frac{1}{2}\right)^{n-n_2}, & n \geq n_2. \end{cases}
\end{aligned}$$