

EE110 – Circuit Analysis II
Winter 2017 – Dr. Shervin Moloudi
Mid-Term Exam – Wednesday February 8, 2017

Instructions

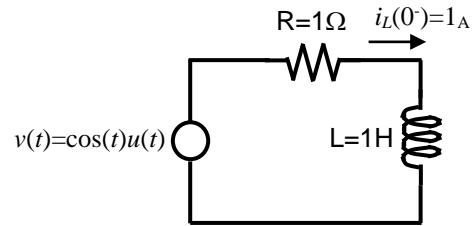
- 1- You have 1 hour and 50 minutes.
- 2- Do not attach your own paper. Ask the proctors for extra paper
- 5- The exam is closed book. No formula sheets, electronic devices, tablets, smart phones/watches allowed. Regular wrist watches allowed.

| Question | |
|-----------------|-------|
| 1 | / 25 |
| 2 | / 25 |
| 3 | / 25 |
| 4 | / 25 |
| Grade | / 100 |

1- In the RL circuit shown:

- A) Use your favorite method to find the complete response for $i_L(t)$.
- B) After the transient part of the response dies out, find the energy delivered to the resistor in one cycle.

(15+10=25 points)



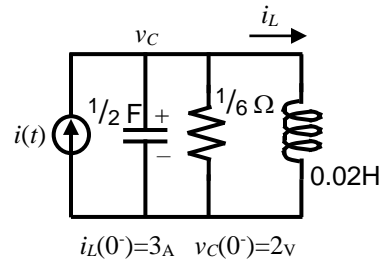
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2- Use Laplace Transform to find the complete response for $v_C(t)$ if:

- A) $i(t)=u(t)$
- B) $i(t)=\delta(t)$
- C) Is the response in part B the derivative of the response in Part A and why?



(10+10+5=25 points)

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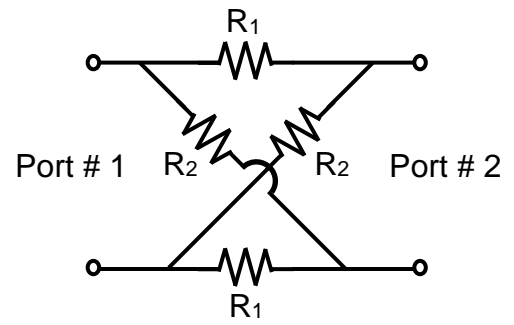
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3- Find the Y-parameters of the two-port network shown here.

(25 points)



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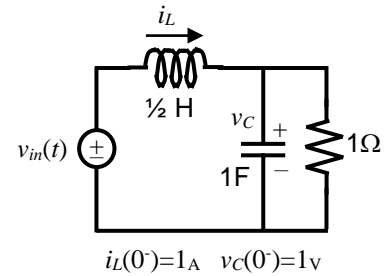
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4- Without using Laplace Transform:

A) Write the integro-differential equations in time domain relating $v_C(t)$ to $v_{in}(t)$.

A) For $v_{in}(t)=u(t)$ find the homogenous and particular responses.

B) Find the complete response by applying the initial conditions.



(10+10+5=25 points)

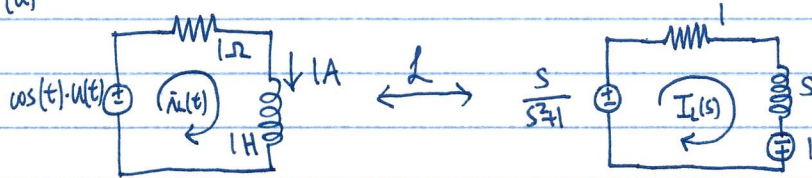
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EE 110 Midterm Solution

1. (a)



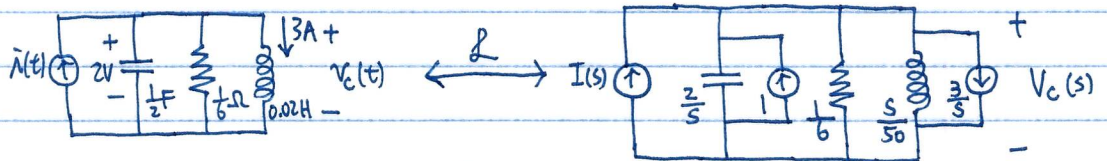
$$I_L(s) = \left(\frac{S}{S^2+1} + 1 \right) \cdot \frac{1}{S+1} = \frac{S^2+S+1}{(S^2+1)(S+1)} = \frac{A \cdot S+B}{S^2+1} + \frac{C}{S+1}$$

$$\begin{cases} A+C=1 \\ A+B=1 \\ B+C=1 \end{cases} \Rightarrow \begin{cases} A=\frac{1}{2} \\ B=\frac{1}{2} \\ C=\frac{1}{2} \end{cases}$$

$$\xrightarrow{\mathcal{L}^{-1}} \tilde{i}_L(t) = \left[\frac{1}{2} \cdot \cos(t) + \frac{1}{2} \cdot \sin(t) + \frac{1}{2} \cdot e^{-t} \right] \cdot u(t)$$

$$\begin{aligned} (b) \quad E &= \int_0^T \tilde{i}_L^2(t) \cdot R \cdot dt = \int_0^{2\pi} \left(\frac{\sqrt{2}}{2} \right)^2 \cdot \cos^2 \left(t - \frac{\pi}{4} \right) \cdot (1) dt \\ &= \frac{1}{2} \cdot \int_0^{2\pi} \left[\frac{1}{2} + \frac{1}{2} \cdot \cos(2t - \frac{\pi}{2}) \right] dt = \frac{1}{2} \cdot \left(\frac{t}{2} \right) \Big|_0^{2\pi} = \underline{\underline{\frac{\pi}{2}}} \end{aligned}$$

2.



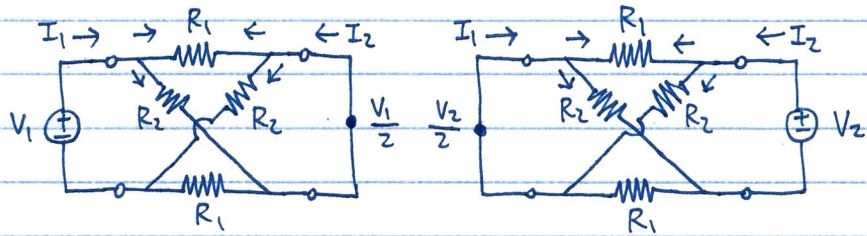
$$\begin{aligned} V_C(s) &= \left(I(s) + 1 - \frac{3}{s} \right) \cdot \left(\frac{2}{s} \parallel \frac{1}{6} \parallel \frac{s}{50} \right) = \left(I(s) + 1 - \frac{3}{s} \right) \cdot \frac{2s}{s^2 + 12s + 100} \\ &= \left(I(s) + 1 - \frac{3}{s} \right) \cdot \frac{2s}{[(s+6)^2 + 8^2]} \end{aligned}$$

$$\begin{aligned} (a) \quad I(s) = \frac{1}{s} &\Rightarrow V_C(s) = \left(1 - \frac{2}{s} \right) \cdot \frac{2s}{[(s+6)^2 + 8^2]} = \frac{2 \cdot (s+6)}{[(s+6)^2 + 8^2]} - \frac{2 \cdot (8)}{[(s+6)^2 + 8^2]} \\ &\xrightarrow{\mathcal{L}^{-1}} v_C(t) = \left[2 \cdot e^{-6t} \cdot \cos(8t) - 2 \cdot e^{-6t} \cdot \sin(8t) \right] \cdot u(t) \end{aligned}$$

$$\begin{aligned} (b) \quad I(s) = 1 &\Rightarrow V_C(s) = \left(2 - \frac{3}{s} \right) \cdot \frac{2s}{[(s+6)^2 + 8^2]} = \frac{4 \cdot (s+6)}{[(s+6)^2 + 8^2]} - \frac{\frac{15}{4} \cdot (8)}{[(s+6)^2 + 8^2]} \\ &\xrightarrow{\mathcal{L}^{-1}} v_C(t) = \left[4 \cdot e^{-6t} \cdot \cos(8t) - \frac{15}{4} e^{-6t} \cdot \sin(8t) \right] \cdot u(t) \end{aligned}$$

(c) No. The zero-state response in part B will be the derivative of zero-state response in part A. However, with the superposition of zero-input response, the statement will generally not hold for the total response.

3.



$$Y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0} = \left(\frac{V_1 - \frac{V_1}{2}}{R_1} + \frac{V_1 - \frac{V_1}{2}}{R_2} \right) \cdot \frac{1}{V_1} = \frac{1}{2R_1} + \frac{1}{2R_2}$$

$$Y_{21} = \frac{I_2}{V_1} \Big|_{V_2=0} = \left(\frac{\frac{V_1}{2} - V_1}{R_1} + \frac{\frac{V_1}{2} - 0}{R_2} \right) \cdot \frac{1}{V_1} = \frac{1}{2R_2} - \frac{1}{2R_1}$$

By symmetry, $Y_{22} = \frac{1}{2R_1} + \frac{1}{2R_2}$, $Y_{12} = \frac{1}{2R_2} - \frac{1}{2R_1}$.

4. (a) KCL: $\tilde{i}_L(t) = \tilde{i}_C(t) + \tilde{i}_R(t)$

$$\Rightarrow \frac{1}{L} \int_{0^-}^t (v_{in}(z) - v_C(z)) dz + \tilde{i}_L(0^-) = C \cdot \frac{dv_C(t)}{dt} + \frac{v_C(t)}{R}$$

$$\Rightarrow \underline{2 \cdot \int_{0^-}^t (v_{in}(z) - v_C(z)) dz + 1 = \frac{d v_C(t)}{dt} + v_C(t)}$$

(b) Taking derivative: $2 \cdot (v_{in} - v_C) = v_C'' + v_C' \Rightarrow v_C'' + v_C' + 2 \cdot v_C = 2 \cdot v_{in} = 2 \cdot u(t)$

Characteristic equation: $s^2 + s + 2 = 0 \Rightarrow s = -\frac{1}{2} \pm \frac{\sqrt{7}}{2}$

$$\begin{cases} \text{homogeneous: } v_{Ch}(t) = \left[k_1 \cdot e^{-\frac{1}{2}t} \cdot \cos\left(\frac{\sqrt{7}}{2}t + \phi\right) \right] \cdot u(t) \\ \text{particular: } v_{Cp}(t) = k_2 \cdot u(t) \end{cases}$$

Find k_2 : $v_{Cp}'' + v_{Cp}' + 2 \cdot v_{Cp} = 2 \cdot k_2 \cdot u(t) = 2 \cdot u(t) \Rightarrow k_2 = 1 \Rightarrow v_{Cp}(t) = u(t)$.

$$\Rightarrow v_C(t) = \left[k_1 \cdot e^{-\frac{1}{2}t} \cdot \cos\left(\frac{\sqrt{7}}{2}t + \phi\right) + 1 \right] \cdot u(t)$$

(c) Initial condition:

$$\begin{cases} \tilde{i}_L(0^-) = \tilde{i}_L(0^+) = v_C'(0^+) + v_C(0^+) = 1 \\ v_C(0^-) = v_C(0^+) = 1 \end{cases} \Rightarrow \begin{cases} v_C(0^+) = 1 \\ v_C'(0^+) = 0 \end{cases}$$

Find k_1 and ϕ :

$$\begin{cases} v_C(0^+) = k_1 \cdot \cos(\phi) + 1 = 1 \\ v_C'(0^+) = -\frac{1}{2} k_1 \cdot \cos(\phi) - \frac{\sqrt{7}}{2} k_1 \cdot \sin(\phi) = 0 \end{cases} \Rightarrow \begin{cases} k_1 = 0 \\ \phi = \tan^{-1}\left(-\frac{1}{\sqrt{7}}\right) \end{cases}$$

$$\Rightarrow \text{Total response: } v_C(t) = \underline{u(t)}$$