UCLA DEPARTMENT OF ELECTRICAL ENGINEERING

EE102: SYSTEMS & SIGNALS

Midterm II Solutions Winter Quarter 2017

Problem 1 (8 pts)

(a) False. The result of $y(t) = \cos(2\pi t) * h(t)$ can be interpreted as output of LTI system whose IRF is h(t) and the input is $\cos(2\pi t)$. Due to the eigenfunction property, the output is

$$y(t) = H(2\pi j)e^{2j\pi t} + H(-2\pi j)e^{-2j\pi t}$$

Therefore it is always $A\cos(2\pi t - \theta)$.

Grading comments: Full credit is not given if one simply states "frequency will not change" without further reasoning.

(b) False. Two poles are at $s = 1 \pm j$, which are in right half plane. Therefore the ROC does not contains $j\Omega$ axis. Problem 2 (12 pts)

(a)

$$x(t) = \cos(3t)u(t - 2\pi)$$

= $\cos(3(t - 2\pi) + 6\pi)u(t - 2\pi)$
= $\cos(3(t - 2\pi))u(t - 2\pi)$

Using time shift property of Laplace transform:

$$X(s) = e^{-2\pi s} \mathcal{L} \left[\cos(3t)u(t) \right]$$
$$= \frac{se^{-2\pi s}}{s^2 + 9}$$

ROC is $\mathcal{R}e[s] > 0$. Poles are at $s = \pm 3j$ and zero is at s = 0.



Figure 1: Pole-zero plot for Problem 2-a

(b)

$$y(t) = \int_0^t (t - \tau)^3 \cos(3\tau) d\tau$$

= $\int_{-\infty}^\infty (t - \tau)^3 \cos(3\tau) u(\tau) u(t - \tau) d\tau$
= $[t^3 u(t)] * [\cos(3t) u(t)]$

Using convolution property of Laplace transform:

$$Y(s) = \mathcal{L}[t^3 u(t)] \times \mathcal{L}[\cos(3t)u(t)]$$

Consider term I

$$\mathcal{L}[t^3 u(t)] = 3! \mathcal{L}\left[\frac{t^3}{3!}u(t)\right] = 3! \frac{1}{s^4} = \frac{6}{s^4}$$

It has ROC: $\mathcal{R}e[s] > 0$.

Consider term II

$$\mathcal{L}[\cos(3t)u(t)] = \frac{s}{s^2 + 9}$$

It has ROC: $\mathcal{R}e[s] > 0$.

Therefore,

$$Y(s) = \frac{6}{s^4} \times \frac{s}{s^2 + 9} = \frac{6}{s^3(s^2 + 9)}$$

and ROC: $\mathcal{R}e[s] > 0$.

There are 5 poles in total. Three poles are at s = 0 and two poles are at $s = \pm 3j$. There are no zeros.



Figure 2: Pole-zero plot for Problem 2-b

Problem 3 (15 pts)

(a) The period is $T_0 = 4$ and fundamental frequency is $\Omega_0 = \frac{2\pi}{T_0} = \frac{\pi}{2}$. $X_0 = 0$ since the signal is odd. We use following equation to find remaining coefficients

$$\begin{aligned} X_k &= \frac{1}{4} \int_{-1}^{1} \sin(\pi t) e^{-jk\Omega_0 t} dt \\ &= \frac{1}{4} \int_{-1}^{1} \frac{e^{j\pi t} - e^{-j\pi t}}{2j} e^{-jk\frac{\pi}{2}t} dt \\ &= \frac{1}{8j} \int_{-1}^{1} (e^{j\pi t(1-k/2)} - e^{-j\pi t(1+k/2)}) dt \\ &= \frac{1}{8j} \times \left[\frac{e^{j\pi t(1-k/2)}|_{-1}^1}{j\pi (1-k/2)} - \frac{e^{-j\pi t(1+k/2)}|_{-1}^1}{-j\pi (1+k/2)} \right] \\ &= \frac{1}{8j} \times \left[\frac{e^{j\pi (1-k/2)} - e^{-j\pi (1-k/2)}}{j\pi (1-k/2)} - \frac{e^{-j\pi (1+k/2)} - e^{j\pi (1+k/2)}}{-j\pi (1+k/2)} \right] \\ &= \frac{1}{4j} \times \left[\frac{\sin(\pi (1-k/2))}{\pi (1-k/2)} - \frac{\sin(\pi (1+k/2))}{\pi (1+k/2)} \right] \\ &= \frac{j}{4} \times \left[\frac{\sin(\pi (1+k/2))}{\pi (1+k/2)} - \frac{\sin(\pi (1-k/2))}{\pi (1-k/2)} \right] \end{aligned}$$

(b) Substituting k = 1 and k = -1, we get

$$X_{1} = \frac{j}{4} \times \left[\frac{\sin(3\pi/2)}{3\pi/2} - \frac{\sin(\pi/2)}{\pi/2}\right] = \frac{j}{4}\left(\frac{-2}{3\pi} - \frac{2}{\pi}\right) = \frac{-2j}{3\pi}$$
$$X_{-1} = \frac{j}{4} \times \left[\frac{\sin(\pi/2)}{\pi/2} - \frac{\sin(3\pi/2)}{3\pi/2}\right] = \frac{j}{4}\left(\frac{2}{\pi} + \frac{2}{3\pi}\right) = \frac{2j}{3\pi}$$

Therefore,

$$|X_1| = |X_{-1}| = \frac{2}{3\pi}$$
$$\angle X_1 = \frac{-\pi}{2}, \angle X_{-1} = \frac{\pi}{2}$$

(c) We have

$$a_k = \mathcal{R}e\{X_k\} = 0,$$

$$b_k = \mathcal{I}m\{X_k\} = \frac{1}{4} \times \left[\frac{\sin(\pi(1+k/2))}{\pi(1+k/2)} - \frac{\sin(\pi(1-k/2))}{\pi(1-k/2)}\right]$$

$$x(t) = -2\sum_{k=1}^{\infty} \frac{1}{4} \times \left[\frac{\sin(\pi(1+k/2))}{\pi(1+k/2)} - \frac{\sin(\pi(1-k/2))}{\pi(1-k/2)}\right] \sin\left(k\frac{\pi}{2}t\right)$$

Problem 4 (15 pts)

The fundamental frequency is $\Omega_0 = \frac{2\pi}{T_0} = \pi$. Due to the fact $X_k = 0, |k| \ge 3$, we can determine x(t) by

$$x(t) = X_0 + X_1 e^{j\pi t} + X_{-1} e^{-j\pi t} + X_2 e^{j2\pi t} + X_{-2} e^{-j2\pi t}$$

For the DC component, we use

$$X_0 = \frac{1}{2} \int_{-1}^{1} x(t) dt = 1$$

where the second equal sign is because x(t) is an even signal. Due to the fact x(t) is real and even, the Fourier coefficients are real. Let $X_1 = X_{-1} = a$ and $X_2 = X_{-2} = b$. Using x(0.5) = 3, we have

$$x(0.5) = 1 + ae^{j\pi/2} + ae^{-j\pi/2} + be^{j\pi} + be^{-j\pi} = 1 + 2b\cos(\pi) = 1 - 2b = 3$$

It gives coefficients $X_2 = X_{-2} = b = -1$.

Due to the power is 3, the Parseval's relation gives

$$\sum_{k=-\infty}^{\infty} |X_k|^2 = |b|^2 + |a|^2 + 1^2 + |a|^2 + |b|^2 = 3 + |a|^2 = 3$$

Therefore $X_1 = X_{-1} = a = 0$ and the time domain signal x(t) is

$$x(t) = 1 - e^{j2\pi t} - e^{-j2\pi t} = 1 - 2\cos(2\pi t)$$

Grading comments: Recall that for integer k, we have

$$e^{j\pi k} = (-1)^k$$
$$e^{j2\pi k} = 1.$$

A common mistake here is to assume equations

$$e^{j\pi t} = (-1)^t$$
$$e^{j2\pi t} = 1$$

are also valid for $t \in \mathbb{R}$.

Problem 5 (20 pts)

(a) Apply Laplace transform on both side of the equation

$$s^{2}Y(s) + 2sY(s) + Y(s) = s^{2}X(s) + X(s)$$

The transfer function of S_1 is

$$H_1(s) = \frac{Y(s)}{X(s)}$$

= $\frac{s^2 + 1}{s^2 + 2s + 1}$
= $1 - \frac{2}{s+1} + \frac{2}{(s+1)^2}$

The IRF of S_1 is

$$h_1(t) = \delta(t) - 2e^{-t}u(t) + 2te^{-t}u(t)$$

The IRF of S_2 is

$$h_2(t) = \cos(t)u(t) + \sin(t)u(t)$$

(b) The transfer function of S_2 is

$$H_2(s) = \mathcal{L}\{h_2(t)\} = \frac{s+1}{s^2+1}$$

The cascaded system has transfer function

$$H_{12}(s) = H_1(s) \cdot H_2(s)$$

= $\frac{s^2 + 1}{s^2 + 2s + 1} \cdot \frac{s + 1}{s^2 + 1}$
= $\frac{s^2 + 1}{(s + 1)^2} \cdot \frac{s + 1}{s^2 + 1}$
= $\frac{1}{s + 1}$

(c) We rewrite input signal using Euler's identity as

$$\begin{aligned} x(t) &= 1 + \frac{1}{j}e^{j\pi t} + \frac{-1}{j}e^{-j\pi t} + e^{j3\pi t} + e^{-j3\pi t} \\ &= e^{-j3\pi t} + 0e^{-j2\pi t} + \frac{-1}{j}e^{-j\pi t} + 1e^{j0\pi t} + \frac{1}{j}e^{j\pi t} + 0e^{j\pi 2t} + e^{j3\pi t} + e^{-j3\pi t} \end{aligned}$$

The fundamental frequency of x(t) is $\Omega_0 = \pi$ and therefore Fourier series is written as

$$x(t) = \sum_{k=-\infty}^{\infty} X_k e^{jk\pi t}$$

Comparing the above two equations, the Fourier coefficient of x(t) can be directly found as

$$X_k = \begin{cases} 1, & k = 0\\ \frac{1}{j}, & k = 1\\ -\frac{1}{j}, & k = -1\\ 1, & k = 3 \text{ and } k = -3\\ 0, & \text{otherwise} \end{cases}$$

Therefore the Fourier coefficient of z(t) are $Z_k = H_{12}(jk\Omega_0)X_k$ and therefore

$$Z_k = \begin{cases} 1, & k = 0\\ \frac{1}{j(1+j)} = -0.5 - 0.5j, & k = 1\\ -\frac{1}{j(1-j)} = -0.5 + 0.5j, & k = -1\\ 0.1 - 0.3j, & k = 3\\ 0.1 + 0.3j, & k = -3\\ 0, & \text{otherwise} \end{cases}$$

Grading comments: There are some other ways of finding coefficient X_k .

• Apply Lapalce to signal component of x(t) within one period, defined as $x_0(t)$ and use

$$\begin{aligned} X_k &= \frac{1}{T_0} \mathcal{L}\{x_0(t)\}|_{s=jk\Omega_0} \\ &= \frac{1}{2\pi} \mathcal{L}\{x_0(t)\}|_{s=jk} \\ &= \frac{1}{2\pi} \mathcal{L}\{[1+2\sin(t)+2\cos(3t)][u(t)-u(t-2\pi)]\}|_{s=jk} \\ &= \frac{1}{2\pi} \left[\frac{1}{s} + \frac{2}{s^2+1} + \frac{2s}{s^2+9}\right] \left[1-e^{-2\pi s}\right]|_{s=jk} \\ &= \frac{1}{2\pi} \left[\frac{1}{jk} + \frac{2}{1-k^2} + \frac{2jk}{9-k^2}\right] \left[1-e^{-j2\pi k}\right] \end{aligned}$$

One can find $X_k = 0$ for $k \neq 0, \pm 1, \pm 3$ because of the $e^{-j2\pi k}$ term. Otherwise it involves with $\frac{0}{0}$ terms and requires special attention. For example when k = 3 the $\frac{0}{0}$ term comes from

$$X_3 = \frac{1}{2\pi} \frac{2jk(1 - e^{-j2\pi k})}{9 - k^2}|_{k=3}$$

Using L'hospital's rule in terms of k it becomes

$$X_3 = \frac{1}{\pi} \frac{jk(j2\pi)}{-2k} = 1$$

A common mistake is to directly apply Laplace transform to x(t) rather than $x_0(t)$. Besides, since x(t) is not a causal signal, one cannot find Laplace transform of x(t) using single-sided Laplace transform table. Actually Laplace of periodic signal does not converge.

• Compute coefficient using definition

$$\begin{aligned} X_k &= \frac{1}{2\pi} \int_0^{2\pi} x(t) e^{-jkt} dt \\ &= \frac{1}{2\pi} \int_0^{2\pi} \left[1 + 2\sin(t) + 2\cos(3t) \right] e^{-jkt} dt \\ &= \frac{1}{2\pi} \int_0^{2\pi} e^{-jkt} dt + \frac{1}{2j\pi} \int_0^{2\pi} e^{-j(k-1)t} dt - \frac{1}{2j\pi} \int_0^{2\pi} e^{-j(k+1)t} dt \\ &+ \frac{1}{2\pi} \int_0^{2\pi} e^{-j(k-3)t} dt + \frac{1}{2\pi} \int_0^{2\pi} e^{-j(k+3)t} dt \end{aligned}$$

Note that all the above intergral has form $\int_0^{2\pi} e^{-jmt} dt$ for some interger m and

$$\int_{0}^{2\pi} e^{-jmt} dt = \begin{cases} e^{-j2\pi m} - 1 = 0, & m \neq 0\\ 2\pi, & m = 0 \end{cases}$$

One can find $X_k = 0$ unless $k = 0, \pm 1, \pm 3$. This approach gives same results as in other methods.

(d) The power of output signal is

$$P_{z} = \sum_{k=-\infty}^{\infty} |Z_{k}|^{2}$$

=1 + |0.5 + 0.5j|^{2} + |0.5 - 0.5j|^{2} + |0.1 - 0.3j|^{2} + |0.1 + 0.3j|^{2}
=1 + 0.5 + 0.5 + 0.1 + 0.1
=2.2