

EC ENRG 101A Midterm Winter 2018

Name: _____
 Student ID#: _____

- A. Please put all the work on the test paper.
- B. Show your work! Provide clear explanations and show calculations. You may not get credit for work that is not shown.

Name of person on LEFT
 even if "far" way.
 If wall, then write "Wall".
 If aisle, then write "Aisle".

ROW NUMBER:
 (as measured from front)

10

Name of person on RIGHT
 even if "far" way.
 If wall, then write "Wall".
 If aisle, then write "Aisle".

Aisle

BE SURE TO ENTER THE FOLLOWING INFORMATION

Allowed:
 pen/pencil
 calculator

formula sheet: one side of a 8 1/2" by 11" sheet of paper.

Score

1	17 /20		
2	12 /15		
3	30 /30		
4	24 /25		
5	35 /40		
Total	118 /130		

Table 3-1: Summary of vector relations.

	Cartesian Coordinates	Cylindrical Coordinates	Spherical Coordinates
Differential length $d\mathbf{l} =$	$\hat{x} dx + \hat{y} dy + \hat{z} dz$	$\hat{r} dr + \hat{\phi} r d\phi + \hat{z} dz$	$\hat{R} dR + \hat{\theta} R d\theta + \hat{\phi} R \sin\theta d\phi$
Differential surface areas	$ds_x = \hat{x} dy dz$ $ds_y = \hat{y} dx dz$ $ds_z = \hat{z} dx dy$	$ds_r = \hat{r} r d\phi dz$ $ds_\phi = \hat{\phi} dr dz$ $ds_z = \hat{z} r dr d\phi$	$ds_R = \hat{R} R^2 \sin\theta d\theta d\phi$ $ds_\theta = \hat{\theta} R \sin\theta dR d\phi$ $ds_\phi = \hat{\phi} R dR d\theta$
Differential volume $dV =$	$dx dy dz$	$r dr d\phi dz$	$R^2 \sin\theta dR d\theta d\phi$

GRADIENT, DIVERGENCE, CURL, & LAPLACIAN OPERATORS CARTESIAN (RECTANGULAR) COORDINATES (x, y, z)

$$\nabla V = \hat{x} \frac{\partial V}{\partial x} + \hat{y} \frac{\partial V}{\partial y} + \hat{z} \frac{\partial V}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla \times \mathbf{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \hat{x} \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \hat{y} \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \hat{z} \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right)$$

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$$

CYLINDRICAL COORDINATES (r, ϕ, z)

$$\nabla V = \hat{r} \frac{\partial V}{\partial r} + \hat{\phi} \frac{1}{r} \frac{\partial V}{\partial \phi} + \hat{z} \frac{\partial V}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$$

$$\nabla \times \mathbf{A} = \frac{1}{r} \begin{vmatrix} \hat{r} & \hat{\phi} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_r & r A_\phi & A_z \end{vmatrix} = \hat{r} \left(\frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) + \hat{\phi} \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) + \hat{z} \frac{1}{r} \left[\frac{\partial}{\partial r} (r A_\phi) - \frac{\partial A_r}{\partial \phi} \right]$$

$$\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2}$$

SPHERICAL COORDINATES (R, θ, ϕ)

$$\nabla V = \hat{R} \frac{\partial V}{\partial R} + \hat{\theta} \frac{1}{R} \frac{\partial V}{\partial \theta} + \hat{\phi} \frac{1}{R \sin\theta} \frac{\partial V}{\partial \phi}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{R^2} \frac{\partial}{\partial R} (R^2 A_R) + \frac{1}{R \sin\theta} \frac{\partial}{\partial \theta} (A_\theta \sin\theta) + \frac{1}{R \sin\theta} \frac{\partial A_\phi}{\partial \phi}$$

$$\nabla \times \mathbf{A} = \frac{1}{R^2 \sin\theta} \begin{vmatrix} \hat{R} & \hat{\theta} & \hat{\phi} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_R & R A_\theta & (R \sin\theta) A_\phi \end{vmatrix}$$

$$= \hat{R} \frac{1}{R \sin\theta} \left[\frac{\partial}{\partial \theta} (A_\phi \sin\theta) - \frac{\partial A_\theta}{\partial \phi} \right] + \hat{\theta} \frac{1}{R} \left[\frac{1}{\sin\theta} \frac{\partial A_R}{\partial \phi} - \frac{\partial}{\partial R} (R A_\phi) \right] + \hat{\phi} \frac{1}{R} \left[\frac{\partial}{\partial R} (R A_\theta) - \frac{\partial A_R}{\partial \theta} \right]$$

$$\nabla^2 V = \frac{1}{R^2} \frac{\partial}{\partial R} \left(R^2 \frac{\partial V}{\partial R} \right) + \frac{1}{R^2 \sin\theta} \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{R^2 \sin^2\theta} \frac{\partial^2 V}{\partial \phi^2}$$

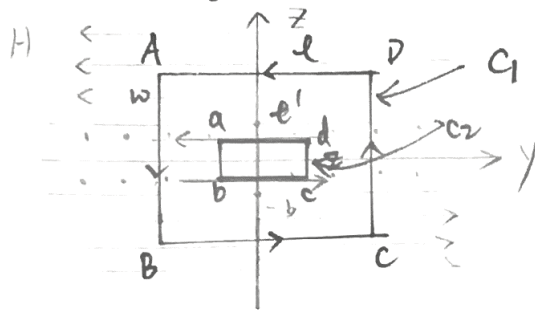
Problem 1: (20 points) – Slab of current (hopefully familiar, it's from problem set #3!)

Find the B-field and H-field created by an infinite slab of current density extending in the x-y plane, whose density is given by

$$\mathbf{J}(z) = \begin{cases} J_1 \hat{x}, & -b < z < b \\ 0, & |z| > b \end{cases}$$

Note #1: J_1 is a constant bulk density with units A/m².

Note #2: Make sure you give the field for all values of z , and don't forget the direction



(17)

As is shown above, the H-field should look like because of symmetry. And H-field is constant when $|z| > b$

① When $|z| > b$

make an Amperian contour counter clockwise centered at 0, dimension $w \times l$

Ampere's Law

$$\oint_C \vec{H} \cdot d\vec{\ell} = \int_S \mathbf{J}(z) \cdot d\mathbf{s}$$

$$-\int_{AB} \vec{H} \cdot d\vec{z} + \int_{BC} \vec{H} \cdot d\vec{y} + \int_{CD} \vec{H} \cdot d\vec{z} + \int_{DA} \vec{H} \cdot d\vec{y} = \int_S \mathbf{J}(z) \cdot d\mathbf{s}$$

$$\int_{-l}^l H(z) \hat{y} \cdot \hat{y} dy = \int_{-l}^l H(z) dz = J_1 \cdot 2b \cdot l$$

$$2lH = J_1 \cdot 2b \cdot l$$

$$H = J_1 \cdot b$$

$$\mathbf{B} = \mu \mathbf{H} = \mu b J_1$$

② when $0 < |z| < b$
similarly make an Amperian contour inside the slab with dimension $l' \times z$

$$\oint_C \vec{H} \cdot d\vec{\ell} = \int_S \mathbf{J}(z) \cdot d\mathbf{s}$$

$$-\int_{AB} H(z) \cdot (-\hat{z}) \cdot \hat{z} dz + \int_{BC} H(z) \cdot \hat{z} \cdot \hat{z} dz = J_1 \hat{x} \cdot \hat{x} l' z$$

$$2H(z) \cdot l' = J_1 \cdot l'(z)$$

$$H(z) = z J_1$$

$$\mathbf{B}(z) = z \mu J_1$$

$$\vec{H} = \begin{cases} J_1 \cdot b \cdot (-\hat{y}), & z > b \\ z \cdot J_1 \cdot (-\hat{y}), & 0 < z < b \\ z \cdot J_1 \cdot (\hat{y}), & -b < z < 0 \\ J_1 \cdot b \cdot (\hat{y}), & z < -b \end{cases}$$

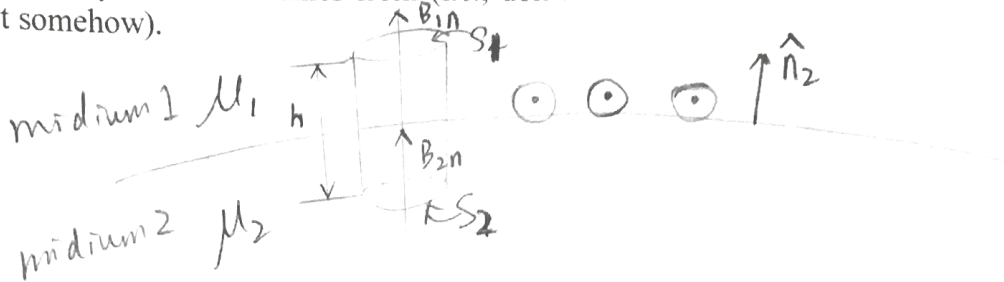
need negative sign or absolute value

$$\vec{B} = \begin{cases} \mu b J_1 \cdot (-\hat{y}), & z > b \\ z \mu J_1 \cdot (-\hat{y}), & 0 < z < b \\ z \mu J_1 \cdot (\hat{y}), & -b < z < 0 \\ \mu b J_1 \cdot (\hat{y}), & z < -b \end{cases}$$

Problem 2: (15 points) Magnetic field boundary condition

Derive the boundary condition for the normal components of the H-field across the boundary between medium 1 with $\mu = \mu_1$ and medium 2 with $\mu = \mu_2$.

NOTE: Please make sure your derivation is as clear as possible. You probably have the answer on your cheat sheet, so I want to see on the paper that you obviously know where this boundary condition comes from (i.e., don't write down the answer and try to back into it somehow).



Making a Gauss's surface as above.

Assume h is small, close to 0 so there is no magnetic field cross the side of the cylinder.

Gauss's Law for magnetic field

$$\begin{aligned} \vec{dS}_2 &= -\hat{n}_2 ds \\ \vec{dS}_1 &= \hat{n}_2 ds \\ \nabla \cdot \vec{B} &= 0 \\ \oint_S \vec{B} \cdot d\vec{S} &= 0 \\ \int_{S_2} \vec{B}_{2n} \cdot (-\hat{n}_2) \cdot dS + \int_{S_1} \vec{B}_{1n} \cdot (\hat{n}_2) \cdot dS &= 0 \\ -B_{2n} S_2 + B_{1n} S_1 &= 0 \end{aligned}$$

$$S_1 = S_2 = S$$

$$-B_{2n} + B_{1n} = 0$$

$$B_{1n} = B_{2n}$$

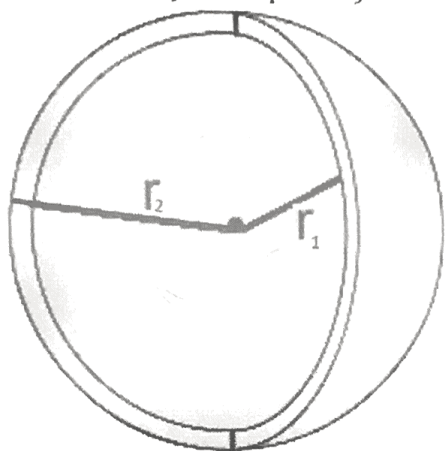
$$H_{1n} = ?$$

12

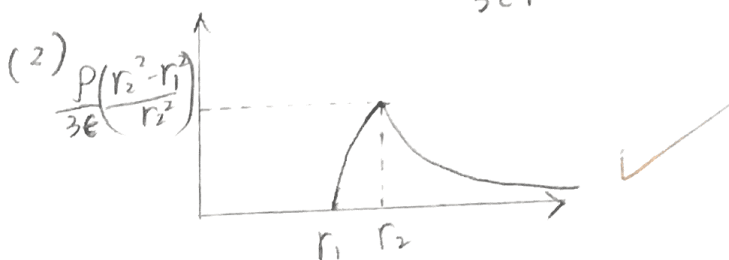
Problem 3: (30 points) Shell of charge

A suspended shell of charge in free space has inner radius r_1 and outer radius r_2 . The shell has a uniform charge density, ρ . You may assume there is empty space inside and outside the shell

- (1) Derive an expression for the electric field for all space (as a function of r).
- (2) Sketch the electric field (as a function of r).
- (3) What is the voltage between the points $(3, 0, -4)$ and $(0, 6, 8)$? You may assume both of these points fall in the space outside the outer edge of the shell.



$$\vec{E}(r) = \frac{D(r)}{\epsilon} \cdot \hat{r} = \begin{cases} 0 & 0 < r < r_1 \\ \left(\frac{\rho}{3\epsilon} - \frac{r_1^2 \rho}{3\epsilon r^2} \right) \hat{r} & r_1 \leq r \leq r_2 \\ \frac{(r_2^2 - r_1^2) \rho}{3\epsilon r^2} \hat{r} & r > r_2 \end{cases}$$



(3) When $r > r_2$

$$V(r) = - \int^r \vec{E}(r) \cdot d\vec{e} \quad d\vec{e} = dr \hat{r}$$

$$= \frac{(r_2^2 - r_1^2) \rho}{3\epsilon} \int_r^\infty -\frac{1}{r^2} dr$$

$$= \frac{(r_2^2 - r_1^2) \rho}{3\epsilon} \left[-\frac{1}{r} \right]_r^\infty$$

$$= \frac{(r_2^2 - r_1^2) \rho}{3\epsilon r}$$

$$(3, 0, -4) \quad R_1 = \sqrt{3^2 + 0^2 + (-4)^2} = 5$$

$$(0, 6, 8) \quad R_2 = \sqrt{0^2 + 6^2 + 8^2} = 10$$

$$V = V(R_1) - V(R_2)$$

$$= \frac{(r_2^2 - r_1^2) \rho}{3\epsilon} \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$$= \frac{(r_2^2 - r_1^2) \rho}{3\epsilon} \left(\frac{1}{5} - \frac{1}{10} \right)$$

$$= \frac{(r_2^2 - r_1^2) \rho}{30\epsilon} \quad 5 \checkmark$$

(1) Make a Gauss's surface that is a sphere concentric with the charged sphere. radius r

$$\oint_S \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}}$$

When $0 \leq r < r_1$, $Q_{\text{enclosed}} = 0$

$$D(r) 4\pi r^2 = 0$$

$$D(r) = 0$$

When $r_1 \leq r \leq r_2$

$$Q_{\text{enclose}} = \int_0^{2\pi} \int_0^{2\pi} \int_{r_1}^r \rho r^2 \sin\theta d\theta dr d\phi$$

$$= \frac{4}{3} \pi (r^2 - r_1^2) \rho$$

$$D(r) \cdot 4\pi r^2 = \frac{4}{3} \pi (r^2 - r_1^2) \rho$$

$$D(r) = \frac{(r^2 - r_1^2) \rho}{3r^2} = \frac{\rho}{3} - \frac{r_1^2 \rho}{3r^2}$$

When $r > r_2$

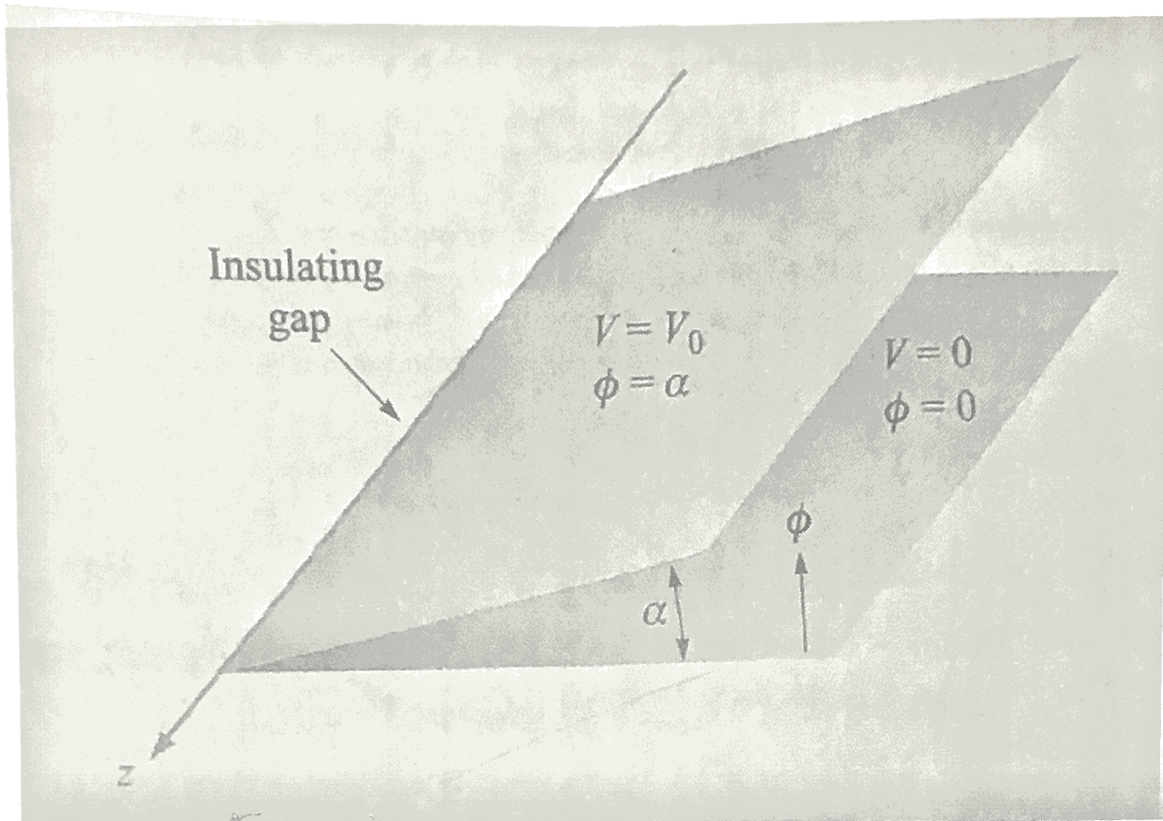
$$Q_{\text{enclose}} = \frac{4}{3} \pi (r_2^2 - r_1^2) \rho$$

$$D(r) 4\pi r^2 = \frac{(r_2^2 - r_1^2) \rho}{3r^2}$$

$$D(r) = \frac{(r_2^2 - r_1^2) \rho}{3r^2}$$

Problem 4: (25 points)

You have planes that extend into infinity in the radial and z directions as shown in the picture below. You know that the first plane, at angle $\phi = 0$, has potential $V = 0$, while the other plane at angle $\phi = \alpha$ has potential $V = V_0$. Derive an expression for the E-field between the two planes.



Given $V = -\int_{\infty}^r \vec{E} \cdot d\vec{l}$

In this case, $V(\phi) = \int_0^\phi \vec{E}(r) \cdot d\vec{l} = \int_0^\phi \hat{\phi} E(r) \cdot \hat{\phi} r d\phi = \int_0^\phi E(r) \cdot r d\phi$
 $d\vec{l} = \hat{\phi} r d\phi$
 $\vec{E}(r) = E(r) \hat{\phi}$

Given $V(\alpha) - V(0) = V_0$

$$\int_0^\alpha E(r) \cdot r d\phi - 0 = V_0$$

$$= E(r) \cdot r \int_0^\alpha d\phi = V_0$$

$$E(r) = \frac{V_0}{\alpha \cdot r}$$

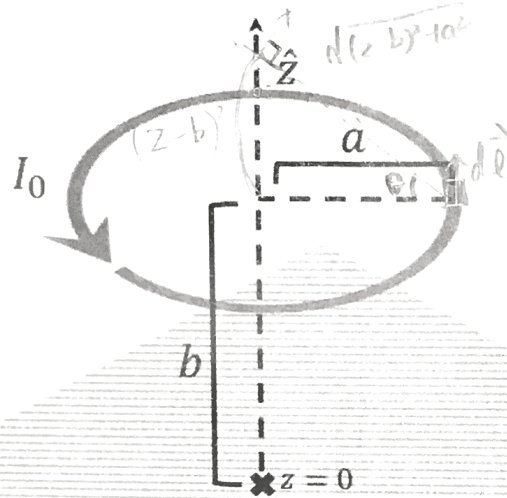
$$\boxed{\vec{E}(r) = -\frac{V_0}{\alpha \cdot r} \hat{\phi}}$$

r is the distance to the z axis

Problem 5 (40 points)

A current loop with radius a , carrying current I_0 (anti-clockwise), is placed at a height $z = b$.

- 1) Find the magnetic flux density \vec{B} caused by the current loop along the z -axis (through the center of the loop). For this part, you can assume this loop is in free space (i.e., with no conducting plane).
- 2) Now you can assume there is an infinite, perfectly conducting ground plane at $z = 0$. Where is the image current caused by the current loop in the ground plane? (Hint: to think about an image current, imagine an image charge that you move around.)
- 3) Which direction is the image current flowing (clockwise or anti-clockwise)?
- 4) What is the total magnetic flux density \vec{B} along the z -axis from the current loop and ground plane?
- 5) Where is the magnetic field zero?



(2) at $z = -b$, the direction of current rotation is opposite



(3) opposite of the real current: Anti clockwise

(4) Similarly to part (1) for the image current generates field in $-z$ direction

$$d\vec{B} = \frac{I\mu_0}{4\pi} \frac{d\vec{l} \times \hat{R}}{R^2} = \frac{I}{a} (-\hat{z})$$

$$|d\vec{l} \times \hat{R}| = dl = a d\phi$$

$$\cos\theta = \frac{a}{\sqrt{(z+b)^2 + a^2}}$$

(1) due to symmetry the y, z component of each $I d\vec{l}$ contribution is cancelled. \vec{H} is in $-\hat{z}$ direction because of R right hand Rule
Biot-Savart Law

As is shown, $\cos\theta = \frac{\sqrt{(z-b)^2 + a^2}}{a}$

Take integral $dl = a d\phi$

$$\vec{B}(z) = \int_0^{2\pi} \frac{I\mu_0}{4\pi} \frac{d\phi}{\sqrt{(z-b)^2 + a^2}} (+\hat{z})$$

$$= \frac{I\mu_0}{2} \frac{1}{\sqrt{(z-b)^2 + a^2}} \hat{z}$$

$$d\vec{B} = \frac{I\mu_0}{4\pi} \frac{d\vec{l} \times \hat{R}}{R^2} (+\hat{z})$$

$$|d\vec{l} \times \hat{R}| = dl \sin\theta = a \sin\theta$$

$$d\vec{B}_z = \frac{I\mu_0}{4\pi} \frac{a \sin\theta}{\sqrt{(z-b)^2 + a^2}} (+\hat{z})$$

$$\vec{B}_1(z) = \frac{I\mu_0}{2\sqrt{(z-b)^2 + a^2}} \hat{z}$$

$$\vec{B}_2(z) = \frac{I\mu_0}{2} \frac{1}{\sqrt{(z+b)^2 + a^2}} (-\hat{z})$$

$$\vec{B}_{tot}(z) = \frac{I\mu_0}{2} \left(\frac{1}{\sqrt{(z-b)^2 + a^2}} - \frac{1}{\sqrt{(z+b)^2 + a^2}} \right) \hat{z}$$

by superposition principle

(5) $\vec{B} = 0$ at $z = 0$