CS180 Midterm

Spenser Wong

TOTAL POINTS

71 / 100

QUESTION 1

1 Problem 1 **14 / 16**

✓ **- 2 pts You were almost there, buddy! Some tiny errors / absence of a sound or a complete proof / silly errors etc.**

QUESTION 2

2 Problem 2 **6 / 16**

✓**- 4 pts Proof missing/wrong** ✓**- 6 pts The given algorithm doesn't work for most of the test cases / No proper explanation / Inefficient, but points awarded for creativity**

QUESTION 3

3 Problem 3 **16 / 16**

✓ **- 0 pts Correct**

QUESTION 4

4 Problem 4 **3 / 16** ✓ **- 13 pts (a). wrong algorithm**

QUESTION 5

5 Problem 5 **12 / 16**

✓ **- 4 pts Attempt with essentially right ideas and some form of pseudocode or analysis or data structures.**

QUESTION 6

6 Problem 6 **20 / 20**

✓ **- 0 pts congratulations! good answer**

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Student ID:

CS180 Winter 2018 - Midterm Wednesday, February 21, 2018

You will have 110 minutes to take this exam. This exam is closed-book and closed-notes. There are 6 questions for a total of 100 points. Please write your name and student ID on every page of your solutions. Please use separate pages for each question.

 ~ 100

Student ID

1. [16 points] We call stable matching fair among n men and n woman if all participants get their best matching among all possible stable matchings. Is there a polynomial time algorithm to find if a fair stable matching exists? If so, please describe it, prove it correct and state it's running time.

ر ۽ ٻا there is. I propose we use the Gale-Shapely Algorithm. We have alrealy proven in class. that the Gale-Shapely aloordom is proposer offimal,i.e. that a member of the proposing set will always be matched with the best powible valis pertair. Vi have proven that this matching is unique as well. I propose that we can the Gale-Shapely Algorithm first with the men proposing, 商用 with the a winth proposing. It these two matchings then are identical, we prive. that all perficipants oct their best possible matching $1+$ impossible for these is matchings to match and not be a $r_{\rm J}$ $f_{0,1r}$ matching, of this controllets the earlier a stive that each partner gold their boot valid partner. We call Gale-Shapely twise, which is Olne), compare matchings in 0 (n) time, so the running time is and $k₀$ c an $0(n^2)$.

 $\label{eq:2.1} \begin{array}{ccccccccc} \mathcal{G}^{\mu} & & & & & & \mathcal{G}^{\mu} & & & & & \mathcal{G}^{\mu} \\ & & & & & & & & & \mathcal{G}^{\mu} & & & & \mathcal{G}^{\mu} \\ & & & & & & & & & & \mathcal{G}^{\mu} & & & & \mathcal{G}^{\mu} \\ & & & & & & & & & & & \mathcal{G}^{\mu} & & & & \mathcal{G}^{\mu} \\ & & & & & & & & & & & \mathcal{G}^{\mu} & & & & \mathcal{G}^{\mu} \\ & & & & & & & & & & & & \mathcal{G}^$ $\mathfrak{g} \in \mathbb{R}$, $\begin{array}{lcl} \mathbf{s} & \math$

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2. [16 points] You are given two sorted lists of size n_1 and n_2 . Give an $O(\log n_1 + \log n_2)$ time algorithm for computing the kth smallest element in the union of the two lists. Prove that your algorithm is correct.

Fur this algorithm I propose that we use a divide and forgor appearsh, as lo<u>g in runtime</u> repersent of subdivision of work, and the is the only way to mest the time bound. We already have a supplication into two lists

For k=1 or k=n, an_{z,} be can simply compare the first element of n₁ with the first of no, and estorn that the kol, or the bod element of no with the last of ne for konithe. For Ickcnitre, we use oitterent approach. I suggest that we insert the elements of n, into a heap and the olimints of me into a heap, Ve can act the Icth element by removing the top element of the heap limes, we would insert no elements into the heap, which takes $O(\log n_i)$ and the elements of n_{2i} which takes $O(\log n_i)$. Removing every element Jales $O(\log ln_i + n_i)$, thus our algorithm is O (logn, Llogn2), A heap is arranged so that the minimum element is always at the top. Thus , as long as we have a properly implemented heap, our algorithm will always be correct. We ensure this by creest beopily velove operations

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 $\sim 10^{-11}$ $\label{eq:R} \begin{array}{l} \mathcal{R} \quad \left(\mathcal{R} \right) \quad \left$ $\mathbf{R} = \mathbf{a} \cdot \nabla \mathbf{A} \qquad \mathbf$ $\label{eq:R1} \xi_1 = \frac{1}{2} \mathcal{F} \qquad \qquad \xi_2 = \frac{1}{2} \mathcal{F} \qquad \qquad \xi_3 = \frac{1}{2} \mathcal{F} \qquad \qquad \xi_4 = \xi_5 \qquad \qquad \xi_5 = \xi_6 \qquad \qquad \xi_6 = \frac{1}{2} \mathcal{F} \qquad \qquad \xi_7 = \frac{1}{2} \mathcal{F} \qquad \qquad \xi_8 = \frac{1}{2} \mathcal{F} \qquad \qquad \xi_9 = \frac{1}{2} \mathcal{F} \qquad \qquad \xi_1 = \frac{1}{2} \math$

 $\label{eq:2.1} \begin{array}{cccccccccc} \ddot{\gamma} & & & & & & & \\ \ddot{\gamma} & & & & & & & \\ \ddot{\gamma} & & & & & & & \\ \end{array} \qquad \qquad \begin{array}{cccccccccc} \ddot{\gamma} & & & \ddot{\gamma} & & \ddot{\gamma} & & \ddot{\gamma} & & \ddot{\gamma} & \\ \ddot{\gamma} & & & & & & & \\ \ddot{\gamma} & & & & & & & \\ \end{array} \qquad \qquad \begin{array}{cccccccccc} \ddot{\gamma} & & & & & & & \\ \ddot{\gamma} & & & & & & & \\ \ddot{\gamma} & & & & & & & \\ \end{array} \qquad \$ $\label{eq:R1} \tilde{\mathbf{y}} = \begin{bmatrix} \mathbf{y} & \mathbf{y} & \mathbf{y} \\ \mathbf{y} & \mathbf{y} & \mathbf{y} \end{bmatrix} \quad \quad \mathbf{y} = \begin{bmatrix} \mathbf{y} & \mathbf{y} & \mathbf{y} \\ \mathbf{y} & \mathbf{y} & \mathbf{y} \end{bmatrix} \quad \quad \mathbf{y} = \begin{bmatrix} \mathbf{y} & \mathbf{y} & \mathbf{y} \\ \mathbf{y} & \mathbf{y} & \mathbf{y} \end{bmatrix}$ $\mathbf{v}^{\mathbf{x}} = \left\{ \begin{array}{ccc} \mathbf{v} & \mathbf{v} & \mathbf{v} & \mathbf{v} \\ \mathbf{v} & \mathbf{v} & \mathbf{v} & \mathbf{v} \end{array} \right. \quad \text{and} \quad \mathbf{v}^{\mathbf{x}} = \left\{ \begin{array}{ccc} \mathbf{v} & \mathbf{v} & \mathbf{v} \\ \mathbf{v} & \mathbf{v} & \mathbf{v} \end{array} \right. \quad \text{and} \quad \mathbf{v}^{\mathbf{x}} = \left\{ \begin{array}{ccc} \mathbf{v} & \mathbf{v} & \mathbf{$

 $\mathcal{A}(\mathcal{X}) = \mathcal{A}(\mathcal{X}) = \mathcal{A}(\mathcal{X})$ $\frac{\partial F}{\partial x}$ (see).

 $\label{eq:2.1} \begin{array}{cccccccccccccc} \mathbf{y} & \mathbf{y$ $\label{eq:3.1} \mathcal{N}(\frac{1}{2}) = \mathcal{N}(\frac{1}{2}) \mathcal{N}(\frac{1}{2}) = \mathcal{N}(\frac$

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Student ID:

3. [16 points] You are given a directed acyclic graph G. Give a linear time algorithm that checks if there exists a Hamiltonian Path in G. (Recall that Hamiltonian Path is a simple path that visits every node exactly once).

We can do this by an reduction to a dopological ordering the proved in the textbook, we can create a topological ordering by the ing the node in 6 that has no incoming edges. We then remove this note to be the next note in the topological wroning and remove all adiges incident and the midt hold had liter ecosog eith sonitaos sub the \mathfrak{g} $+h_{1,1}$ to pological ordering. We continue this prosess watil all edges and nodes are in the topological ordering, we then shock it, for every nove V: in the topological ordering, there is an edge between Vi ond vite claim this will voly not true of there is a Hamiltonian path. \overline{I} need to visit all nodes A in an order, In a topological We

Ordering, edges can never point built word. Thus it we take on odoe (v,, vm) for men, we have no way of reaching the nodes in between v, und Vm. Becouse we cannot go backwore, the only way we can form of Hamilterian path on the equivalent topological ororing is to fake the edge from one virtex to the next adjacent vertex every time, If there are a noted ont bedoed, we can construct a topological ordering in O (a +b), and check whether each restex now an edge to the next adjacent vertex in OCb), so we have linear runting of O(atb).

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 $\label{eq:1.1} \mathbb{E}[x] = \langle \phi \rangle \quad \text{ and } \quad \mathbb{E}[f^2] = \langle \mathbb{E}[x], \phi^2 \rangle \quad \text{ and } \quad \mathbb{E}[x] = \langle \phi^2 \rangle \quad \text{ and } \quad \mathbb{E}[x] = \langle \phi^2 \rangle \quad \text{ and } \quad \mathbb{E}[x] = \langle \phi^2 \rangle \quad \text{ and } \quad \mathbb{E}[x] = \langle \phi^2 \rangle \quad \text{ and } \quad \mathbb{E}[x] = \langle \phi^2 \rangle \quad \text{ and } \quad \mathbb{E}[x] = \langle \phi^2 \rangle \quad \text$

 $\label{eq:1.1} \begin{array}{cccccccccccccc} \mathbf{y} & & & & & \mathbf{B} & & & & \mathbf{$

 $\label{eq:R} \mathbf{x} \cdot \mathbf{z} = \begin{bmatrix} \mathbf{x} & \mathbf{z} & \mathbf{z} \\ \mathbf{z} & \mathbf{z} & \mathbf{z} \end{bmatrix}$ $\label{eq:12} \begin{array}{cccccccccc} \mathbf{e} & \cdots & \mathbf{e} \\ \mathbf{e} & \mathbf{e} \end{array}$

 $\label{eq:2.1} \begin{array}{ccccc} \mu & & \mu & \tau \\ \end{array}$

 $\label{eq:1.1} \mathcal{P}_{\mathcal{C}}(\mathcal{C})=\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\mathcal{C}}(\mathcal{C})=\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\mathcal{C}}(\mathcal{C})\oplus\mathcal{P}_{\$

 $\label{eq:3.1} \mathcal{A}^{(N-1)} = \mathcal{A}^{(N-1)}$ $\mathcal{L}=\frac{1}{2}$. The set of $\mathcal{L}=\frac{1}{2}$ $\label{eq:2.1} \theta_{\rm c} = \pi \pm \lambda^{(1)} \Xi \qquad \qquad \Xi^{\rm w} \to \Gamma \Xi \qquad \qquad \Xi^{\rm w}$ and

 \sim \sim $\label{eq:2.1} \begin{array}{cccccccccc} \lambda & \lambda & \lambda & \lambda & \lambda & \lambda & \cdots & \lambda & \lambda \\ \end{array}$

 $\label{eq:2.1} \begin{array}{cccccccccc} \mathcal{C} & & & & & & \mathcal{C} & & \mathcal{C} &$

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4. [16 points] Given strings $x = x_1x_2x_3...x_n$ and $y = y_1y_2y_3...y_m$ the longest common substring (LCS) is the identical substring (of sequential matching characters) in x and y of longest length. Show $O(mn)$ algorithm to find the length of LCS. Prove it is correct.

define a moximum substring of length for every character x; in X or x or y termin ates (1) iterale through y until a character y; == x; is found (1) continue checking X itk with yith until the characters do not match (3) if the length of this is longer than the maximum substring, the lingth of the new maximum is $k-1$, and update the substring $k_1 = R_1 \cdot 1 + R_2 \cdot 1 + R_3 \cdot 1 + R_4 \cdot 1 + R_5 \cdot 1 + R_6 \cdot 1 + R_7 \cdot 1 + R_8 \cdot 1 + R_9 \cdot 1 + R_1 \cdot 1 + R_1 \cdot 1 + R_2 \cdot 1 + R_3 \cdot 1 + R_4 \cdot 1 + R_5 \cdot 1 + R_7 \cdot 1 + R_8 \cdot 1 + R_9 \cdot 1 + R_1 \cdot 1 + R_1 \cdot 1 + R_1 \cdot 1 + R_1 \cdot 1 + R_2 \cdot 1 + R_3 \cdot 1 + R_4 \cdot 1 + R_5 \cdot 1 + R_6 \cdot 1 +$ attorn the substring and lingth

For each n characters in x, ve only consider the m characters in y once, so we have a runtime of O(mn)

 $4r+$ alsorithm is correct. Every LCJ most start with some womman this common tharacter. Thus we think the most part it on every LCJ that could start for every x; in x, xz.,. xn. Then we walle through x and simultaneously vatil the substrings no longer motion, Consider whos y would need to happen it was a longer string indeed existed. Then the tratture lout our algorithm was incorrect. By definition the $\int a \cdot 4$ character most motion of the substring must motch, But our algorithm valy firminules when the last charachter does not match, or string terminates, in which there can be no longer substring. Thus $0nt$ algorithm vould have tound linis substring 100

 $\label{eq:3.1} \varphi^{\mu}=\varphi^{\mu\nu\lambda}\varphi^{\nu\lambda}=\varphi^{\mu\nu}\varphi^{\nu\nu\lambda}\varphi^{\nu\lambda}\varphi^{\nu\lambda}$ $\label{eq:1.1} \frac{\partial}{\partial t} \chi_{\alpha} = \chi_{\alpha} \chi_{\alpha} \chi_{\alpha} + \chi_{\alpha} \chi_{\alpha} \chi_{\alpha}$

 $\label{eq:2.1} \begin{array}{cccccccccc} \mathbf{v} & \mathbf{v}$ $\label{eq:2.1} \mathcal{M}(\mathbf{X}) = \mathcal{M}(\mathbf{X}) = \mathcal{M}(\mathbf{X}) = \mathcal{M}(\mathbf{X})$

 $\label{eq:2.1} \frac{1}{2} \left(\frac{1}{\sqrt{2}} \right) \left(\frac{1}{2} \right) = \frac{1}{2} \left(\frac{1}{2} \right)$ $\label{eq:1.1} \begin{array}{cccccccccc} \Sigma^{\pm} & \cdots & \Sigma^{\pm} & \Sigma^{\pm} & \Sigma^{\pm} & \cdots & \Sigma^{\pm} & \cdots & \Sigma^{\pm} \end{array}$

 $\label{eq:psi} \psi_{\mathbf{k}} = \left\langle \mathbf{r} \right\rangle \left\langle \mathbf{$

 $\label{eq:3.1} \mathcal{A} = \mathcal{A} \otimes \mathcal{A} \otimes \mathcal{A}$ $\sim 10^{11}$ and $\sim 10^{11}$ α

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5. [16 points] Given a directed graph $G = (V, E)$ on n nodes and m edges describe $O(m+n)$ algorithm to find the length of shortest length cycle (if one exists).

can find for shortoid tength cycle by voing a simple adoptation of V_{ℓ} orpry
breading first sourch, Recall that we construct a free housed on G using &FS by choosing an orbitrary rude, then tonsidering the neighbors of this note, then the neighbors of this neighbor, until the entire then considering following a path starting at this nove as far or we can go, soly backing up when necessary, The difference is that when normally, it we reach an olde was involved on (viv) could have agold but to the the fight a cycle, mother blood it hd light are less H , we count the distance of U to the least common ancestor of (x_1, y_1) and the distance of v to this least common ancestor, It this sum is shorter than the vurrent shortest length eyele, this is the newest shortest length cycle. We choose DFS because this is the natural analogue of following a path until it forms a cycle or frominates, and we want to consider cases where eyeler are formed, tothappen meanscore is that thus by vuring OFS hevered pailing too stea a fa pailing and called sldiceog lla 114 cases by the path become a cyste of some point, or the puth derminals, they we consider l all egills. We can implement OFS in O (mtn) time, thus we have met the time constraint. Mote that we also whould check it some vertexes are not in the tree, as it is possible they are in a different component or variathable from our liest node, We repeals the process for these which head modes and empare minimums to the the true minimum \mathcal{O}

 $\mathbb{R}^{2d} \mathbb{R}^2 \qquad \qquad \widetilde{\mathbb{R}}^{2d} \mathbb{R}^2 \qquad \qquad \mathbb{R}^{2d} \mathbb{R}^2 \qquad \qquad \mathbb{R}^{2d} \qquad \mathbb{R}^{2d}$ $\label{eq:1.1} \begin{array}{cccccccccccccc} \mathbf{x} & \cdots & \mathbf{x} & \mathbf{y} & \cdots & \mathbf{y} & \cd$

 $\label{eq:R1} \mathcal{S} = \mathcal{S} \times \mathcal{S} = \mathcal{S} \times \mathcal{S} \times \mathcal{S} = \mathcal{S} \times \mathcal{S} \times \mathcal{S} \times \mathcal{S}$ $\label{eq:2.1} \mathcal{A}_{\mathcal{A}} = \frac{1}{\sqrt{2\pi}}\sum_{i=1}^N \mathcal{A}_{\mathcal{A}} \left(\mathcal{A}_{\mathcal{A}} \right)^2 \mathcal{A}_{\mathcal{A}} \left(\mathcal{A}_{\$

 $\label{eq:R1} \frac{1}{R^2} \sum_{i=1}^N \frac{1}{\left(\sum_{i=1}^N \frac$ $\mathbf{x}^{(i)}$, $\mathbf{x}^{(i)}$

 $\kappa = -\vec{\kappa}$

 $\frac{1}{2}$ $\overline{\mathcal{A}}$. The set of \mathcal{A}

 $\label{eq:1.1} \mathbf{f}_{\mathrm{max}} = \mathbf{f}_{\mathrm{max}}$

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6. [20 points]

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- (a) [15 points] Recall that in class we showed a reduction from 3-SAT to Hamiltonian Cycle (in directed graphs). Explain how you would modify it to make a reduction from 20-SAT (e.g. every clause has at most 20 literals) to Hamiltonian Cycle problem. Does the number of nodes change? Does the number of edges change? If 20-SAT has n clauses and m variables, how many vertices and directed edges does your HC graph in the reduction has?
- (b) [5 points] Someone shows that problem X is in NP and poly-time reducible to Graph 3-Coloring (i.e. $X \leq_p$ 3-COLORING). Is it true that X must be NP-Complete? If yes, justify your answer, if no, show a counter-example.
	- Retuth that our godget was composed of in rows of 3n+3 \mathfrak{A} notes in the case of 3-stif, This is breast ve have 3 mol. $for \pm a \in \mathbb{R}$

gadget was composed of m rows of 3n+3 R_{t+h} h 0 u r nover, we altrally do not hart to do mech admotation trom 3-SAT. Like 3-SAT, for 20 JAM, we still have no rows of 3n+3 noves. The only officially in 3-JAT each classe had 6 edges uttached to its vode, and directed edge in and one directed edge out for each literal in elovat. In the case of 20-SAT, each added clavic node has 40 $4h_{l}$ edoes, and we connect these in the same way us we did in S-SAT that a traversal from left for right olding the rlasse line in 50 of to taimnevers an I ar I at m to I an increase an ensumer $|int$ right to lett. The only difference is that each classe is now \int_{∂} r pat connected on a puth 20 lines instead of 3. $2+m(3a+3)+n$ vertices. This is because we have have W_l otart and one wise, plus m(3n23), rectices for each row, additional vertices for classes, We have 22 m +40 a + 4m. plus n edges. This is because each claves has 40 attached elses, each line in has 22 class, and each line vaca Hedges of concert to the next line, the Notill the number of nodes is unchanged, but olges \mathfrak{g} f \mathcal{A} No. In Inst, for X to be PP-complete, the ceveral vould have to true, namely $X \nleq_{\rho} 3$ - coloring for example, b

 \bar{a} $\label{eq:2.1} \begin{array}{cc} \mathbb{E} & \left(\begin{array}{cc} \mathbb{E} & \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{array} \right) & \mathbb{E} & \mathbb{E} \\ \mathbb{E} & \mathbb{E} & \mathbb{E} \end{array} \end{array}$