

PHYSICS 1B

MIDTERM 1

Spring, 2017

Dr. Coroniti

There are 100 points on the exam, and you have 50 minutes. To receive full credit, show all your work and reasoning. No credit will be given for answers that simply "appear". The exam is closed notes and closed book. You do not need calculators, so please put them, and all cell phones, away. If you need more space, use the backside of the page.

Simon Ruter

Your Full Name - Printed Clearly

Simon Ruter

Your Normal Signature

ber

Problem

Score

1

30

2

18

3

20

4

25

Total

93

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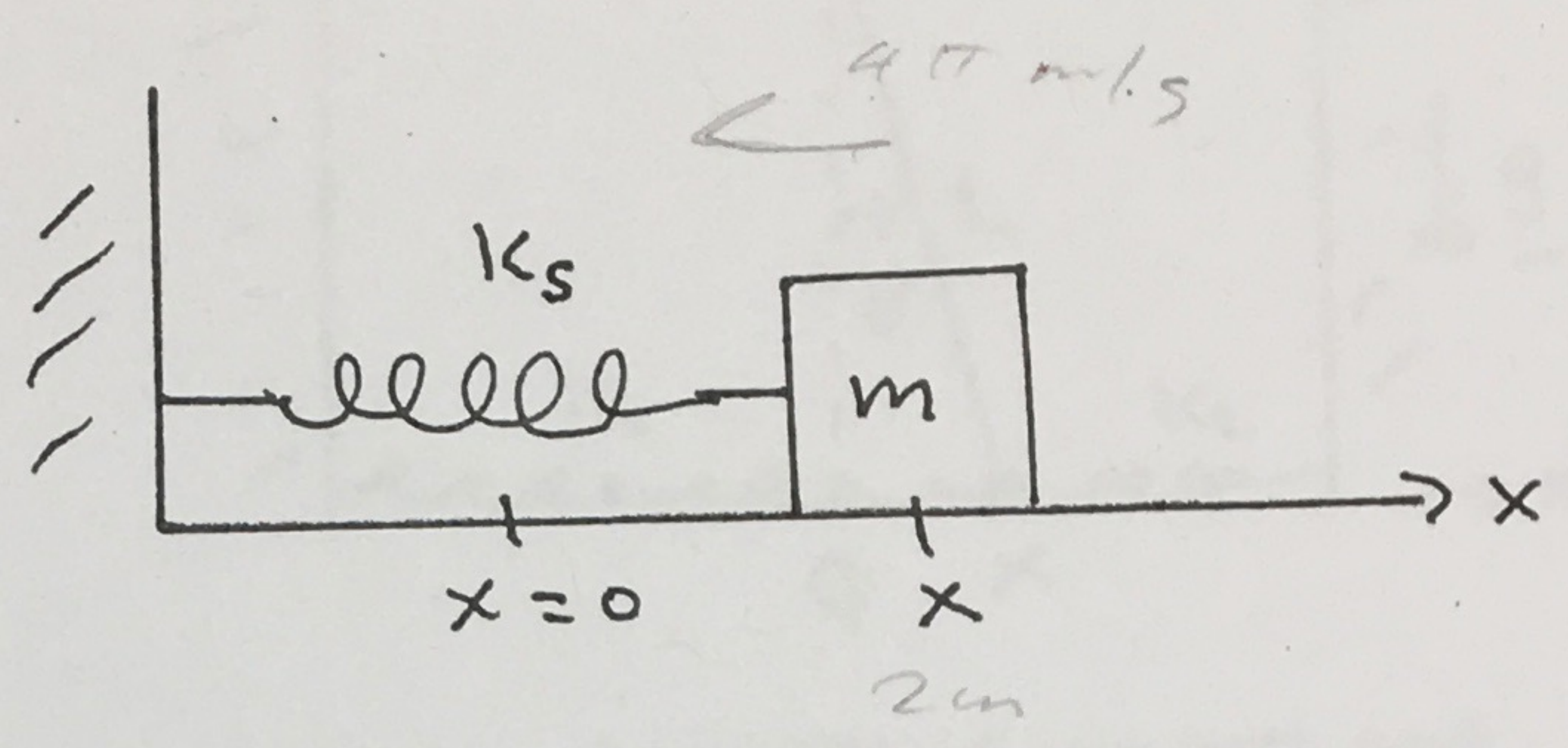
93

$A = \frac{2}{\cos \omega t}$        $\omega = 2\pi$   
 $-4\pi = -2\omega \sin(\omega t) - 4\pi = -\frac{2\omega}{\cos \omega t} \sin \omega t$   
 $x = 2$        $A \cos(\omega t)$   
 $v = -4\pi$        $-A \omega \sin(\omega t)$   
 $-4\pi = -A(2\pi) \sin(\omega t)$

(30 Pts)

1. A block with mass  $m = 2 \text{ kg}$  is attached to a spring with a stiffness constant  $k_s = 8\pi^2 \text{ N/m}$ , and is free to oscillate on a smooth horizontal surface about the spring's equilibrium position  $x = 0$ . At time  $t = 0$ , the mass is observed to be located at  $x(0) = 2 \text{ m}$ , and to be moving with a speed  $v(0) = 4\pi \text{ m/s}$  toward  $x = 0$ . Leave answers in terms of  $\pi$  and whole numbers.

- (4) a. Find the angular frequency ( $\omega_0$ ) for oscillations about  $x = 0$ , and the oscillation period.
- (10) b. Find the function  $x(t)$  that describes the position of the mass as a function of time  $t \geq 0$ .
- (8) c. Find the velocity of the mass for the first time that it passes through  $x = 0$ . [Recall:  $\sin(\pi/4) = \cos(\pi/4) = \sqrt{2}/2$ .]
- (8) d. Calculate the total mechanical energy  $E$  of the system, and the maximum displacement amplitude. [Recall the relation between  $E$  and the amplitude.]



$m = 2 \text{ kg}$        $k_s = 8\pi^2 \text{ N/m}$        $x = 0$        $t = 0$ :  $x(0) = 2 \text{ m}$        $v_0 = 4\pi \text{ m/s}$  toward  $x = 0$

a)  $\omega = \sqrt{\frac{k_s}{m}} = \sqrt{\frac{8\pi^2}{2}} = \sqrt{4\pi^2} = 2\pi \text{ rad/s}$   
 $\omega = \frac{2\pi}{T}$        $T = \frac{2\pi}{\omega}$        $T = 1 \text{ second}$

$x(t) = A \cos(\omega t + \phi)$

b)  $A = \sqrt{x_0^2 + \frac{v_0^2}{\omega_0^2}}$        $v_0 = -4\pi \text{ m/s}$        $\omega_0 = 2\pi$   
 $= \sqrt{4 + \frac{16\pi^2}{4\pi^2}} = \sqrt{4 + 4} = \sqrt{8}$   
 $x(t) = \sqrt{8} \cos(2\pi t + \frac{\pi}{4})$

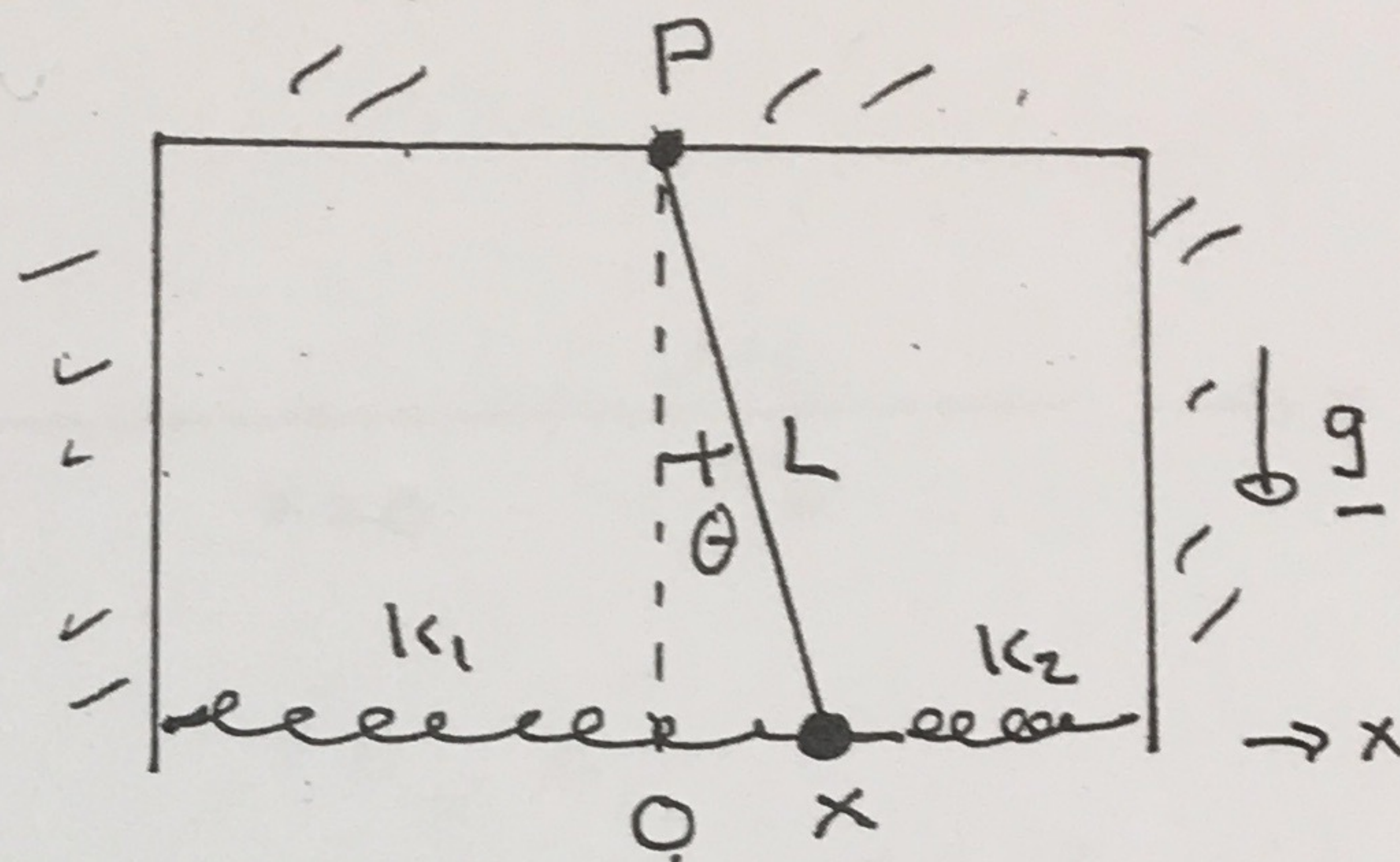
$t = 0$        $\sqrt{8} \cos(x) = 2$        $\frac{1}{\sqrt{2}} = \cos x$   
 when  $t = \frac{1}{8\pi}$

c)  $v(t) = -2\pi\sqrt{8} \sin(2\pi t + \frac{\pi}{4})$   
 when  $x = 0$ ,  $t = \frac{1}{8\pi}$  second  
 $= -2\pi\sqrt{8} \sin(\pi/2) = -2\pi\sqrt{8} \text{ m/sec} = -\omega A$

d)  $\max A = \sqrt{8} \text{ m}$   
 $E = \frac{1}{2} m v^2 + \frac{1}{2} k x^2 = \frac{1}{2} m (4\pi^2 \cdot 8 \sin^2(\dots)) + \frac{1}{2} k (8 \cos^2(\dots))$   
 $E = \frac{1}{2} k_s A^2 = \frac{1}{2} (8\pi^2) (\sqrt{8})^2 = 32\pi^2$

(20 Pts)

2. A pendulum with bob mass  $m$  and massless rod of length  $L$  hangs under gravity. The mass is attached to two horizontal springs with stiffness constants  $k_1$  and  $k_2$  that are unstretched when the mass hangs straight down. The mass is displaced by a small angle  $\theta$ , and released to oscillate about the origin  $x = 0$ . Since  $\theta \ll 1$ ,  $\sin \theta \approx \theta$ ,  $x \approx L\theta$ , and the motion essentially occurs only in the  $x$ -direction.

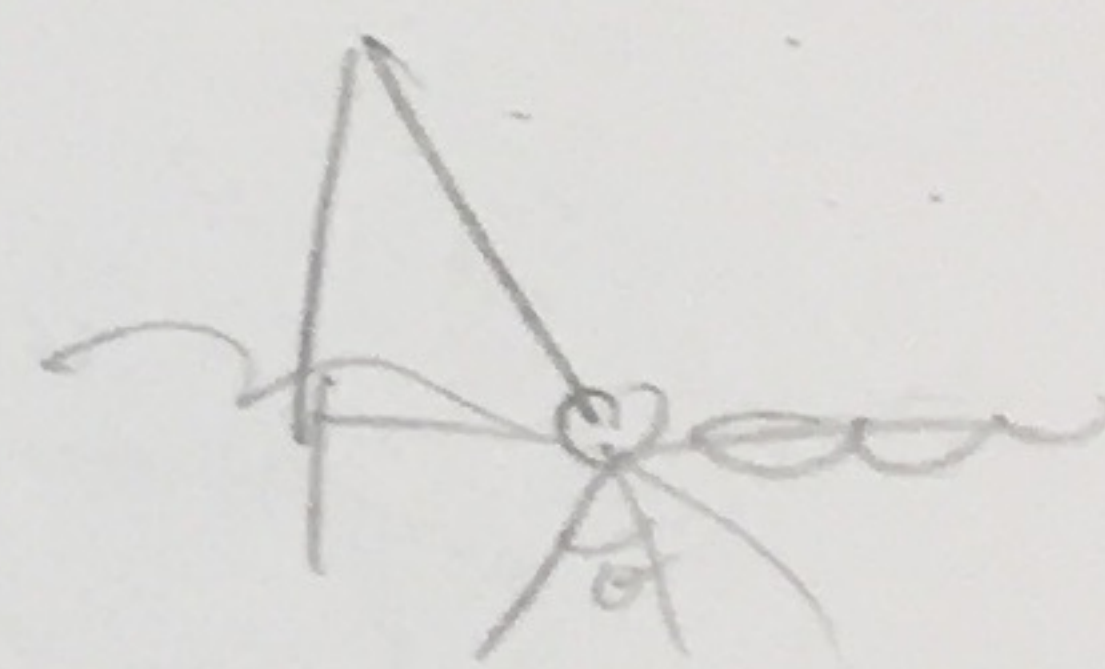


(12) a. Recalling the  $\tau = \mathbf{r} \times \mathbf{F}$ ,  $\tau = I\alpha$ ,  $\alpha = d^2\theta/dt^2$ , and  $I = mL^2$  about the pivot point P, or just using  $\mathbf{F} = m\mathbf{a}$  with  $\mathbf{F}$  being only along  $x$ , prove that the angular frequency of small oscillations about  $x = 0$  is

$$\omega_0 = \left[ \frac{k_1 + k_2}{m} + \frac{g}{L} \right]^{1/2}$$

(8) b. Now suppose that the horizontal oscillations are driven by a force  $F(t) = F_0 \sin(\omega t)$ , and that the mass moves through water and experiences a force of friction  $f = -b v$ . Write the equation that now describes the motion (Newton's Second Law or its torque equivalent). If the driving frequency  $\omega = \omega_0$ , find  $x(t)$ .

a)  $\tau = r \times F$   $\tau = I \alpha$



$$-mg \sin \theta + k_1(l\theta) + k_2(l\theta) = -I \alpha$$

$$\frac{1}{mL^2} (\theta(mgl + k_1 + k_2)(L^2)) = m L^2 \ddot{\theta} \quad \text{divide by mL}^2$$

$$-\theta \left( \frac{g}{L} + \frac{k_1 + k_2}{m} \right) = \ddot{\theta} \iff \ddot{x} = -\omega_0^2 x$$

$$\omega_0^2 = \frac{g}{L} + \frac{k_1 + k_2}{m} \quad \omega_0 = \left( \frac{g}{L} + \frac{k_1 + k_2}{m} \right)^{1/2}$$

b)  $F(t) = F_0 \sin(\omega t)$   $f = -b v = -b \omega l$   
 $v = \omega l$

$$\sum \tau = I \alpha = r \times F$$

$$\frac{1}{mL^2} [mgl\theta + (k_1 + k_2)(L^2\theta) - b \dot{\theta} L^2 + F_0 \sin(\omega t)] = \ddot{\theta}$$

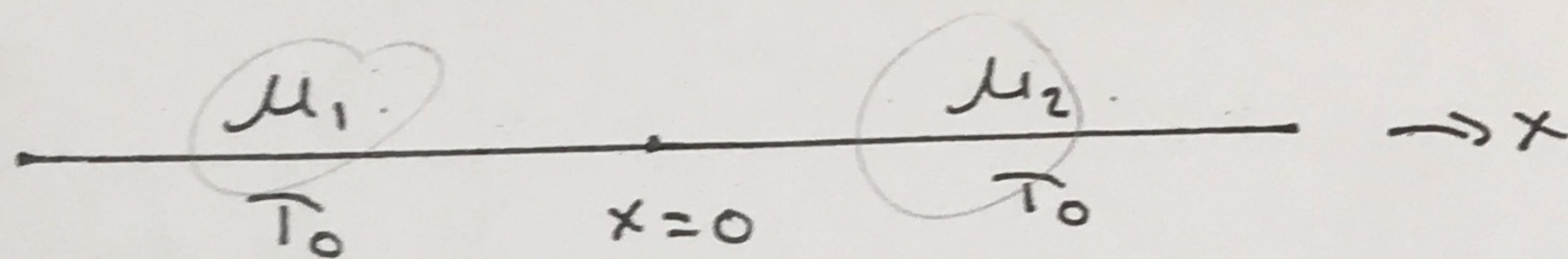
if  $\omega = \omega_0$ , then  $F_0 \sin(\omega t) = -b \dot{\theta} L^2$  (friction = driving)

$$\int \frac{F_0 \sin(\omega t)}{-b L^2} = \int \ddot{\theta}$$

$$\theta(t) = -\frac{F_0}{b L^2 \omega} \cos(\omega t)$$

(25 Pts)

3. A very long stretched string with equilibrium tension  $T_0$  consists of a piece to the left ( $x < 0$ ) of the origin with mass per unit length  $\mu_1$ , and a piece to the right ( $x > 0$ ) of the origin with a mass per unit length  $\mu_2$ . At the origin ( $x = 0$ ), the string is attached to a motor that drives the string in the  $y$ -direction with a displacement  $y(0, t) = A \sin(\omega t)$ .



(6) a. Write (do NOT derive), the partial differential equation (the wave equation) that governs the space and time dependence of the displacement  $y(x, t)$  of the string.

(10) b. Find  $y(x, t)$  for the waves which are driven by the motor to travel in the positive and the negative  $x$ -directions.

(9) c. Calculate the time-averaged power that is transported by each wave. Of the two waves, which transports the higher power? [Recall: power =  $\mathbf{F} \cdot \mathbf{v}$ , and  $F_y = -T_0 \partial y / \partial x$ ,  $v = \partial y / \partial t$ ;  $\langle \sin^2 \theta \rangle = \langle \cos^2 \theta \rangle = 1/2$ .]

a)  $\frac{\partial^2 y}{\partial t^2} = c^2 \frac{\partial^2 y}{\partial x^2}$   $c = \sqrt{\frac{T_0}{\mu}}$

$\frac{\partial^2 y}{\partial t^2} = \frac{T_0}{\mu} \frac{\partial^2 y}{\partial x^2}$

$y(x, t) = A \sin(kx - \omega t)$

b)  $k c = \omega$   $c = \sqrt{\frac{T_0}{\mu}}$

$y(0, t) = A \sin(\omega t)$   $k = \frac{\omega}{c}$

right travelling  $y(x, t) = A \sin\left(\frac{\omega}{c} x - \omega t\right)$

left travelling (negative)  $y(x, t) = A \sin\left(\omega \left(\sqrt{\frac{\mu_1}{T_0}} x + t\right)\right)$

Positive:  $y(x, t) = -A \sin\left(\omega \left(\sqrt{\frac{\mu_2}{T_0}} x - t\right)\right)$

c) Time-avg power

$P = F \cdot v = -T_0 \frac{\partial y}{\partial x} \frac{\partial y}{\partial t}$

right-travelling

$P = -T_0 A \omega \sqrt{\frac{\mu_2}{T_0}} \cos(\dots) \cdot A \omega \cos(\dots)$

$\langle P \rangle = -T_0 A^2 \sqrt{\frac{\mu_2}{T_0}} \omega^2 \langle \cos^2(\dots) \rangle$

$\langle P \rangle = \frac{-T_0 A^2 \sqrt{\frac{\mu_2}{T_0}} \omega^2}{2} = \frac{-T_0 A^2 \omega^2}{2c}$

(dependent on  $A^2$ )

left-travelling

$P = F \cdot v = -T_0 \frac{\partial y}{\partial x} \frac{\partial y}{\partial t}$

$\langle P \rangle = -T_0 \sqrt{\frac{\mu_1}{T_0}} \omega A^2 \langle \cos^2(\dots) \rangle$

$\langle P \rangle = \frac{-T_0 \sqrt{\frac{\mu_1}{T_0}} \omega^2 A^2}{2}$

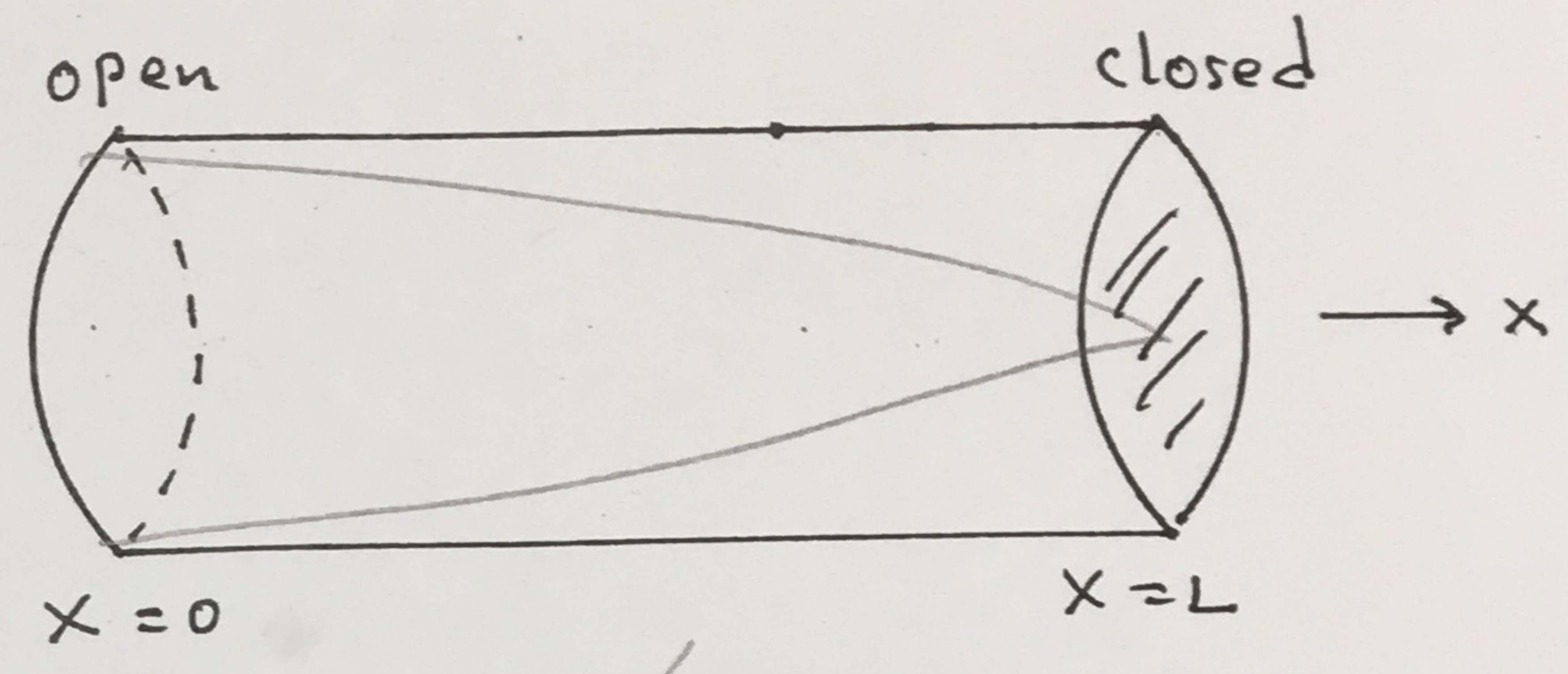
The wave with the larger mass/length  $\mu$  carries the higher power, because the power is dependent on  $1/c$

$A/k = c_s$

(25 Pts)

4. A pipe of length  $L$  and uniform cross-sectional area is open to the atmosphere at one end  $x = 0$ , and is closed at the other end  $x = L$ . The speed of sound in air is  $c_s$ , and is related to the compressibility (bulk modulus)  $\beta = \rho_0 c_s^2$  where  $\rho_0$  is the equilibrium mass density.

(8) a. State and physically explain the boundary conditions that the longitudinal displacement  $y(x,t)$  and the perturbed pressure  $\delta P(x,t)$  must satisfy at the open and closed ends of the pipe. [Recall:  $\delta P = -\beta \partial y / \partial x$ .]



(12) b. Find the solution for  $y(x,t)$  for the waves that stand in the pipe (the normal modes), and for the wavenumber  $k_n$ , angular frequency  $\omega_n$ , and ordinary frequency  $\nu_n$  for the standing waves.

(5) c. The length of the pipe is increased by a small distance  $\Delta x \ll L$ . The frequency of the  $n^{\text{th}}$  harmonic is observed to decrease by  $\Delta \nu$ . Show that  $\Delta \nu$  is approximately given by  $\Delta \nu \approx \nu_n \Delta x / L$ .

$L$   
 $c_s$   
 $\beta = \rho_0 c_s^2$   
 $2 \rightarrow \frac{\pi}{2}$   
 $2 \rightarrow \frac{3\pi}{2}$

a) At the closed end,  $\delta P(x,t)$  must be at a maximum, because at the open end  $\delta P(x,t)$  must be 0. This is because the pressure of the atmosphere cannot be changed.  $y(x,t)$  is at a max at the open end and 0 at the closed end because  $\delta P = -\beta \partial y / \partial x$ , so the two functions are  $90^\circ$  out of phase.

b)  $y(x,t) = [A \sin kx + B \cos kx] \cos \omega t = A \cos kx \cos \omega t$  ✓

@  $x=0$ ,  $\cos kx = \text{max}$  ✓ @  $x=L$ ,  $\cos kx = 0$

$kx = \frac{n\pi}{2}$   $k_n = \frac{(2n-1)\pi}{2L}$  w.k.c  $\omega_n = \frac{(2n-1)\pi}{2L} c = \frac{(2n-1)\pi}{2L} \sqrt{\frac{\beta}{\rho_0}}$

$\omega = 2\pi \nu$   $\nu = \omega / 2\pi$   $\nu_n = \frac{(2n-1)}{4L} c = \frac{(2n-1)}{4L} \sqrt{\frac{\beta}{\rho_0}}$

$y(x,t) = A \cos\left(\frac{(2n-1)\pi}{2L} x\right) \cos\left(\frac{(2n-1)\pi}{2L} \sqrt{\frac{\beta}{\rho_0}} t\right)$

c)  $\Delta x \ll L$   $\nu$  decreases  $\Delta \nu$

$\Delta \nu = (\nu_n) \frac{\Delta x}{L}$   $c = \lambda \nu$   $c$  remains constant  
 $\Delta \lambda = \frac{\Delta x}{L}$  wavelength increases by  $\frac{\Delta x}{L}$

so,  $\nu$  must decrease by a factor of  $\frac{\Delta x}{L}$

$\therefore \Delta \nu = (\nu_n) \frac{\Delta x}{L}$